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## DEPARTMENT OF TRANSPORTATION

**Federal Aviation Administration** 

14 CFR Part 60

[Docket No.: FAA-2014-0391; Amdt. No. 60—4]

RIN 2120-AK08

Flight Simulation Training Device Qualification Standards for Extended Envelope and Adverse Weather Event Training

Tasks

Correction

## 14 CFR PART 60 [CORRECTED]

In FR Rule Doc. No. 2016-05860 beginning on page 18178 in the issue of March 30, 2016, make the following corrections:

1. Correct the table appearing on page 18240 to read as follows:

	Table A1B - Table of Tasks vs. Simulator Level											
	QPS REQUIREMENTS INFORMATION											
Entry Numb	Subjective Requirements  In order to be qualified at the simulator qualification level indicated, the simulator must be able to perform at least the tasks associated with that level of qualification.	S A	imul Lev B	lator els C	D	Notes						

* * * * *	* * *					
Maneuvers.						
* * * * *						
High Angle of Attack Maneuvers						
Approaches to Stall		X	X	X	X	
Full Stall				X	X	Stall maneuvers at angles of attack above the activation of the stall warning system.  Required only for FSTDs qualified to conduct full stall training tasks as indicated on the Statement of Qualification.
* * * * *						-
Upset Prevention and Recovery Training (UPRT)				X	X	Upset recovery or unusual attitude training maneuvers within the FSTD's validation envelope that are intended to exceed pitch attitudes greater than 25 degrees nose up; pitch attitudes greater than 10 degrees nose down, and bank angles greater than 45 degrees.
	* * * * * *  High Angle of Attack Maneuvers  Approaches to Stall  Full Stall  * * * * * *	* * * * * *  High Angle of Attack Maneuvers  Approaches to Stall  Full Stall  * * * * * *	* * * * * * *  High Angle of Attack Maneuvers  Approaches to Stall  Full Stall  * * * * * * *	* * * * * * * * * * * * * * * * * * *	Maneuvers.  * * * * * *  High Angle of Attack Maneuvers  Approaches to Stall  Full Stall  * * * * * *	* * * * * * * * * * * * * * * * * * *

## 2. Correct the table appearing on pages 18242-18282 to read as follows:

	Table A2A - Full Flight Simulator (FFS) Objective Tests											
	QPS REQUIREMENTS											
	Test	- Tolerance	Flight	Test	Simulator Level		r	Notes				
Entry Number	Title	Tolerunce	Conditions	Details	A	В	C	D	riotes			
1. Perfor	mance.											
1.a.	Taxi.											
1.a.1	Minimum radius turn.	±0.9 m (3 ft) or ±20% of airplane turn radius.	Ground.	Plot both main and nose gear loci and key engine parameter(s). Data for no brakes and the minimum thrust required to maintain a steady turn except for airplanes requiring asymmetric thrust or braking to achieve the minimum radius turn.		X	X	X				
1.a.2	Rate of turn versus nosewheel steering angle (NWA).	$\pm 10\%$ or $\pm 2^{\circ}/s$ of turn rate.	Ground.	Record for a minimum of two speeds, greater than minimum turning radius speed with one at a typical taxi speed, and with a spread of at least 5 kt.		X	X	X				
1.b.	Takeoff.			Note.— All airplane manufacturer commonly-used certificated take-off flap settings must be demonstrated at least once either in minimum unstick speed (1.b.3), normal take-off (1.b.4), critical engine failure on take-off (1.b.5) or crosswind take-off (1.b.6).								
1.b.1	Ground acceleration time and distance.	±1.5 s or ±5% of time; and ±61 m (200 ft) or ±5% of distance.	Takeoff.	Acceleration time and distance must be recorded for a minimum of $80\%$ of the total time from brake release to $V_r$ . Preliminary aircraft certification data may be used.	X	X	X	X	May be combined with normal takeoff (1.b.4.) or rejected takeoff (1.b.7.). Plotted data should be shown using appropriate scales for each portion of the maneuver.			
1.b.2	Minimum control speed, ground (V <sub>mcg</sub> ) using aerodynamic controls only per applicable airworthiness requirement or	±25% of maximum airplane lateral deviation reached or ±1.5 m (5 ft).  For airplanes with reversible flight control	Takeoff.	Engine failure speed must be within ±1 kt of airplane engine failure speed. Engine thrust decay must be that resulting from the mathematical model for the engine applicable to the FSTD under test. If the modeled engine is not the same as the airplane manufacturer's flight test engine, a further test may be run with the same initial	X	X	X	X	If a $V_{mcg}$ test is not available, an acceptable alternative is a flight test snap engine deceleration to idle at a speed between $V_1$ and $V_1$ -10 kt, followed by control of heading using aerodynamic			

	Table A2A - Full Flight Simulator (FFS) Objective Tests										
	QPS REQUIREMENTS										
	Test	Tolerance	Flight	Test	S	imu Le		r	Notes		
Entry Number	Title		Conditions	Details	A	B	C	D			
	alternative engine inoperative test to demonstrate ground control characteristics.	systems: ±2.2 daN (5 lbf) or ±10% of rudder pedal force.		conditions using the thrust from the flight test data as the driving parameter.					control only and recovery should be achieved with the main gear on the ground.  To ensure only aerodynamic control, nosewheel steering should be disabled (i.e. castored) or the nosewheel		
1.b.3	$\begin{array}{c} \mbox{Minimum unstick} \\ \mbox{speed } (\mbox{V}_{mu}) \mbox{ or} \\ \mbox{equivalent test to} \\ \mbox{demonstrate early} \\ \mbox{rotation take-off} \\ \mbox{characteristics.} \end{array}$	±3 kt airspeed. ±1.5° pitch angle.	Takeoff.	Record time history data from 10 knots before start of rotation until at least 5 seconds after the occurrence of main gear lift-off.	X	X	X	X	held slightly off the ground.  V <sub>mu</sub> is defined as the minimum speed at which the last main landing gear leaves the ground. Main landing gear strut compression or equivalent air/ground signal should be recorded. If a V <sub>mu</sub> test is not available, alternative acceptable flight tests are a constant highattitude takeoff run through main gear lift-off or an early rotation takeoff.		
									If either of these alternative solutions is selected, aft body contact/tail strike protection functionality, if present on the airplane, should be active.		
1.b.4	Normal take-off.	±3 kt airspeed.  ±1.5° pitch angle.  ±1.5° AOA.  ±6 m (20 ft) height.	Takeoff.	Data required for near maximum certificated takeoff weight at mid center of gravity location and light takeoff weight at an aft center of gravity location. If the airplane has more than one certificated takeoff configuration, a different configuration must be used for each weight.	X	X	X	X	The test may be used for ground acceleration time and distance (1.b.1).  Plotted data should be shown using appropriate scales for each portion of the maneuver.		

	Table A2A - Full Flight Simulator (FFS) Objective Tests											
			<b>QPS REQUIREM</b>	IENTS					INFORMATION			
	Test	Tolerance	Flight	Test	S	imu Le		r	Notes			
Entry Number	Title	Total	Conditions	Details	A	В	C	D	11000			
		For airplanes with reversible flight control systems:		Record takeoff profile from brake release to at least 61 m (200 ft) AGL.								
		±2.2 daN (5 lbf) or ±10% of column force.										
1.b.5	Critical engine failure on take-off.	±3 kt airspeed. ±1.5° pitch angle.	Takeoff.	Record takeoff profile to at least 61 m (200 ft) AGL.	X	X	X	X				
		$\pm 1.5^{\circ}$ AOA.		Engine failure speed must be within $\pm 3$ kt of airplane data.								
		±6 m (20 ft) height.										
		+2° roll angle										
		±2° side-slip angle.		Test at near maximum takeoff weight.								
		±3° heading angle.										
		For airplanes with reversible flight control systems:										
		±2.2 daN (5 lbf) or ±10% of column force;										
		±1.3 daN (3 lbf) or ±10% of wheel force; and										
		±2.2 daN (5 lbf) or ±10% of rudder pedal force.										
1.b.6	Crosswind takeoff.	± 3 kt airspeed.	Takeoff.	Record takeoff profile from brake release to at	X	X	X	X	In those situations where a maximum crosswind or a			
		±1.5° pitch angle.		least 61 m (200 ft) AGL.  This test requires test data, including wind profile, for a crosswind component of at least 60% of the airplane performance data value					maximum demonstrated			
		±1.5° AOA.							crosswind is not known, contact the NSPM.			
		±6 m (20 ft) height.		measured at 10 m (33 ft) above the runway.								

Table A2A - Full Flight Simulator (FFS) Objective Tests											
	QPS REQUIREMENTS										
	Test	- Tolerance	Flight	Test	S	imu Le	lato vel	r	Notes		
Entry Number	Title	1 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Conditions	Details	A	В	C	D	1,000		
		±2° roll angle.		Wind components must be provided as headwind and crosswind values with respect to the runway.							
		±2° side-slip angle.		and crosswind values with respect to the ran way.							
		±3° heading angle.									
		Correct trends at ground speeds below 40 kt for rudder/pedal and heading angle.									
		For airplanes with reversible flight control systems:									
		±2.2 daN (5 lbf) or ±10% of column force;									
		±1.3 daN (3 lbf) or ±10% of wheel force; and									
		$\pm 2.2$ daN (5 lbf) or $\pm 10\%$ of rudder pedal force.									
1.b.7.	Rejected Takeoff.	$\pm 5\%$ of time or $\pm 1.5$ s.	Takeoff.	Record at mass near maximum takeoff weight.	X	X	X	X	Autobrakes will be used		
		±7.5% of distance or		Speed for reject must be at least 80% of V <sub>1</sub> .					where applicable.		
		±76 m (250 ft).		Maximum braking effort, auto or manual.							
				Where a maximum braking demonstration is not available, an acceptable alternative is a test using approximately 80% braking and full reverse, if applicable.							

	Table A2A - Full Flight Simulator (FFS) Objective Tests											
	QPS REQUIREMENTS											
	Test	Tolerance	Flight	Test	Simula Leve			r	Notes -			
Entry Number	Title	Toterunee	Conditions	Details	A	В	C	D	- 10000			
				Time and distance must be recorded from brake release to a full stop.								
1.b.8.	Dynamic Engine Failure After Takeoff.	$\pm 2^{\circ}$ /s or $\pm 20\%$ of body angular rates.	Takeoff.	Engine failure speed must be within ±3 kt of airplane data.  Engine failure may be a snap deceleration to idle.  Record hands-off from 5 s before engine failure to +5 s or 30° roll angle, whichever occurs first.  CCA: Test in Normal and Non-normal control state.			X	X	For safety considerations, airplane flight test may be performed out of ground effect at a safe altitude, but with correct airplane configuration and airspeed.			
1.c.	Climb.			State								
1.c.1.	Normal Climb, all engines operating.	±3 kt airspeed. ±0.5 m/s (100 ft/ min) or ±5% of rate of climb.	Clean.	Flight test data are preferred; however, airplane performance manual data are an acceptable alternative.  Record at nominal climb speed and mid initial climb altitude.	X	X	X	X				
				FSTD performance is to be recorded over an interval of at least 300 m (1 000 ft).								
1.c.2.	One-engine- inoperative 2nd segment climb.	±3 kt airspeed.  ±0.5 m/s (100 ft/ min) or ±5% of rate of climb, but not less than airplane performance data requirements.	2nd segment climb.	Flight test data is preferred; however, airplane performance manual data is an acceptable alternative.  Record at nominal climb speed.  FSTD performance is to be recorded over an interval of at least 300 m (1,000 ft).  Test at WAT (weight, altitude or temperature) limiting condition.	X	X	X	X				

	Table A2A - Full Flight Simulator (FFS) Objective Tests											
	INFORMATION											
	Test	Tolerance	Flight	Test	Simulator Level		r	Notes				
Entry Number	Title	Toterunce	Conditions	Details	A	В	C	D	110005			
1.c.3.	One Engine Inoperative En route Climb.	$\pm 10\%$ time, $\pm 10\%$ distance, $\pm 10\%$ fuel used	Clean	Flight test data or airplane performance manual data may be used.  Test for at least a 1,550 m (5,000 ft) segment.			X	X				
1.c.4.	One Engine Inoperative Approach Climb for airplanes with icing accountability if provided in the airplane performance data for this phase of flight.	±3 kt airspeed.  ±0.5 m/s (100 ft/ min) or ±5% rate of climb, but not less than airplane performance data.	Approach	Flight test data or airplane performance manual data may be used.  FSTD performance to be recorded over an interval of at least 300 m (1,000 ft).  Test near maximum certificated landing weight as may be applicable to an approach in icing conditions.	X	X	X	X	Airplane should be configured with all anti-ice and de-ice systems operating normally, gear up and go-around flap.  All icing accountability considerations, in accordance with the airplane performance data for an approach in icing conditions, should be applied.			
1.d.	Cruise / Descent.	l	J									
1.d.1.	Level flight acceleration	±5% Time	Cruise	Time required to increase airspeed a minimum of 50 kt, using maximum continuous thrust rating or equivalent.  For airplanes with a small operating speed range, speed change may be reduced to 80% of operational speed change.	X	X	X	X				
1.d.2.	Level flight deceleration.	±5% Time	Cruise	Time required to decrease airspeed a minimum of 50 kt, using idle power.  For airplanes with a small operating speed range, speed change may be reduced to 80% of operational speed change.	X	X	X	X				
1.d.3.	Cruise performance.	±.05 EPR or ±3% N1 or ±5% of torque.  ±5% of fuel flow.	Cruise.	The test may be a single snapshot showing instantaneous fuel flow, or a minimum of two consecutive snapshots with a spread of at least 3 minutes in steady flight.			X	X				
1.d.4.	Idle descent.	±3 kt airspeed. ±1.0 m/s (200 ft/min) or	Clean.	Idle power stabilized descent at normal descent speed at mid altitude.	X	X	X	X				

	QPS REQUIREMENTS									
Test		- Tolerance	Flight		Simu Lev			r	- Notes	
Entry Number	Title	Toterunce	Conditions	Details	A	В	C	D	riotes	
		±5% of rate of descent.		FSTD performance to be recorded over an interval of at least 300 m (1,000 ft).						
1.d.5.	Emergency descent.	±5 kt airspeed. ±1.5 m/s (300 ft/min) or ±5% of rate of descent.	As per airplane performance data.	FSTD performance to be recorded over an interval of at least 900 m (3,000 ft).	X	X	X	X	Stabilized descent to be conducted with speed brakes extended if applicable, at mid altitude and near $V_{\rm mo}$ or according to emergency descent procedure.	
1.e.	Stopping.									
1.e.1.	Deceleration time and distance, manual wheel brakes, dry runway, no reverse thrust.	$\pm 1.5$ s or $\pm 5\%$ of time. For distances up to 1,220 m (4,000 ft), the smaller of $\pm 61$ m (200 ft) or $\pm 10\%$ of distance. For distances greater than 1,220 m (4,000 ft), $\pm 5\%$ of distance.	Landing.	Time and distance must be recorded for at least 80% of the total time from touchdown to a full stop.  Position of ground spoilers and brake system pressure must be plotted (if applicable).  Data required for medium and near maximum certificated landing mass.  Engineering data may be used for the medium mass condition.	X	X	X	X		
1.e.2.	Deceleration time and distance, reverse thrust, no wheel brakes, dry runway.	$\pm 1.5$ s or $\pm 5\%$ of time; and the smaller of $\pm 61$ m (200 ft) or $\pm 10\%$ of distance.	Landing	Time and distance must be recorded for at least 80% of the total time from initiation of reverse thrust to full thrust reverser minimum operating speed.  Position of ground spoilers must be plotted (if applicable).  Data required for medium and near maximum certificated landing mass.  Engineering data may be used for the medium mass condition.	X	X	X	X		

		Tab	le A2A - Full Fligl	nt Simulator (FFS) Objective Tests					
	INFORMATION								
	Test	- Tolerance	Flight	Test	Simulator Level			r	Notes
Entry Number	Title		Conditions	Details	A	В	С	D	Tions
1.e.3.	Stopping distance, wheel brakes, wet runway.	$\pm 61$ m (200 ft) or $\pm 10\%$ of distance.	Landing.	Either flight test or manufacturer's performance manual data must be used, where available.  Engineering data, based on dry runway flight test stopping distance and the effects of contaminated runway braking coefficients, are an acceptable alternative.			X	X	
1.e.4.	Stopping distance, wheel brakes, icy runway.	$\pm 61$ m (200 ft) or $\pm 10\%$ of distance.	Landing.	Either flight test or manufacturer's performance manual data must be used, where available.  Engineering data, based on dry runway flight test stopping distance and the effects of contaminated runway braking coefficients, are an acceptable alternative.			X	X	
1.f.	Engines.	•							
1.f.1.	Acceleration.	±10% Ti or ±0.25 s; and ±10% Tt or ±0.25 s.	Approach or landing	Total response is the incremental change in the critical engine parameter from idle power to go-around power.	X	X	X	X	See Appendix F of this part for definitions of $T_{i,}$ and $T_{t}$ .
1.f.2.	Deceleration.	$\pm 10\%$ Ti or $\pm 0.25$ s; and $\pm 10\%$ Tt or $\pm 0.25$ s.	Ground	Total response is the incremental change in the critical engine parameter from maximum takeoff power to idle power.	X	X	X	X	See Appendix F of this part for definitions of $T_{i,}$ and $T_{t}$ .
2. Handlin	ng Qualities.	•							
2.a.	Static Control Tests.								

Note.1 — Testing of position versus force is not applicable if forces are generated solely by use of airplane hardware in the FSTD.

Note 2 — Pitch, roll and yaw controller position versus force or time should be measured at the control. An alternative method in lieu of external test fixtures at the flight controls would be to have recording and measuring instrumentation built into the FSTD. The force and position data from this instrumentation could be directly recorded and matched to the airplane data. Provided the instrumentation was verified by using external measuring equipment while conducting the static control checks, or equivalent means, and that evidence of the satisfactory comparison is included in the MQTG, the instrumentation could be used for both initial and recurrent evaluations for the measurement of all required control checks. Verification of the instrumentation by using external measuring equipment should be repeated if major modifications and/or repairs are made to the control loading system. Such a permanent installation could be used without any time being lost for the installation of external devices. Static and dynamic flight control tests should be accomplished at the same feel or impact pressures as the validation data where applicable.

Note 3 — FSTD static control testing from the second set of pilot controls is only required if both sets of controls are not mechanically interconnected on the FSTD. A rationale is required from the data provider if a single set of data is applicable to both sides. If controls are mechanically interconnected in the FSTD, a single set of tests is sufficient.

	Table A2A - Full Flight Simulator (FFS) Objective Tests											
	INFORMATION											
	Test	- Tolerance	Flight	Test	S		ılato evel	r	Notes			
Entry Number	Title		Conditions	Details	A	В	C	D	Tiotes			
2.a.1.a.	Pitch controller position versus force and surface position calibration.	±0.9 daN (2 lbf) breakout. ±2.2 daN (5 lbf) or ±10% of force. ±2° elevator angle.	Ground.	Record results for an uninterrupted control sweep to the stops.	X	X	X	X	Test results should be validated with in-flight data from tests such as longitudinal static stability, stalls, etc.			
2.a.1.b.	(Reserved)	±2 elevator ungle.										
2.a.2.a.	Roll controller position versus force and surface position calibration.	±0.9 daN (2 lbf) breakout. ±1.3 daN (3 lbf) or ±10% of force. ±2° aileron angle. ±3° spoiler angle.	Ground.	Record results for an uninterrupted control sweep to the stops.	X	X	X	X	Test results should be validated with in-flight data from tests such as engine-out trims, steady state side-slips, etc.			
2.a.2.b.	(Reserved)	±3 sponer angie.										
2.a.3.a.	Rudder pedal position versus force and surface position calibration.	±2.2 daN (5 lbf) breakout.  ±2.2 daN (5 lbf) or ±10% of force.  ±2° rudder angle.	Ground.	Record results for an uninterrupted control sweep to the stops.	X	X	X	X	Test results should be validated with in-flight data from tests such as engine-out trims, steady state side-slips, etc.			
2.a.3.b.	(Reserved)	J										
2.a.4.	Nosewheel Steering Controller Force and Position Calibration.	±0.9 daN (2 lbf) breakout. ±1.3 daN (3 lbf) or ±10% of force. ±2° NWA.	Ground.	Record results of an uninterrupted control sweep to the stops.	X	X	X	X				

Table A2A - Full Flight Simulator (FFS) Objective Tests											
	QPS REQUIREMENTS										
	Test	- Tolerance	Flight	Test	Simulator Level			r	Notes		
Entry Number	Title	Toterunce	Conditions	Details	A	В	C	D	Tiotes		
2.a.5.	Rudder Pedal Steering Calibration.	±2° NWA.	Ground.	Record results of an uninterrupted control sweep to the stops.	X		X	X			
2.a.6.	Pitch Trim Indicator vs. Surface Position Calibration.	±0.5° trim angle.	Ground.		X	X	X	X	The purpose of the test is to compare FSTD surface position and indicator against the flight control model computed value.		
2.a.7.	Pitch Trim Rate.	$\pm 10\%$ of trim rate (°/s) or $\pm 0.1$ °/s trim rate.	Ground and approach.	Trim rate to be checked at pilot primary induced trim rate (ground) and autopilot or pilot primary trim rate in-flight at go-around flight conditions.  For CCA, representative flight test conditions must be used.	X	X	X	X			
2.a.8.	Alignment of cockpit throttle lever versus selected engine parameter.	When matching engine parameters:  ±5° of TLA.  When matching detents:  ±3% N1 or ±.03 EPR or ±3% torque, or equivalent.  Where the levers do not have angular travel, a tolerance of ±2 cm (±0.8 in) applies.	Ground.	Simultaneous recording for all engines. The tolerances apply against airplane data.  For airplanes with throttle detents, all detents to be presented and at least one position between detents/ endpoints (where practical). For airplanes without detents, end points and at least three other positions are to be presented.	X	X	X	X	Data from a test airplane or engineering test bench are acceptable, provided the correct engine controller (both hardware and software) is used.  In the case of propeller-driven airplanes, if an additional lever, usually referred to as the propeller lever, is present, it should also be checked. This test may be a series of snapshot tests.		
2.a.9.	Brake pedal position versus force and brake system pressure calibration.	±2.2 daN (5 lbf) or ±10% of force. ±1.0 MPa (150 psi) or ±10% of brake system pressure.	Ground.	Relate the hydraulic system pressure to pedal position in a ground static test.  Both left and right pedals must be checked.	X	X	X	X	FFS computer output results may be used to show compliance.		

	Table A2A - Full Flight Simulator (FFS) Objective Tests										
			<b>QPS REQUIREM</b>	ENTS					INFORMATION		
	Test	Tolerance	Flight	Test	Si	mul Lev		r	Notes		
Entry Number	Title		Conditions	Details	A	В	C	D			
2.a.10	Stick Pusher System Force Calibration (if applicable)	±10% or ±5 lb (2.2 daN)) Stick/Column force	Ground or Flight	Test is intended to validate the stick/column transient forces as a result of a stick pusher system activation.  This test may be conducted in an on-ground condition through stimulation of the stall protection system in a manner that generates a stick pusher response that is representative of an in-flight condition.			X	X	Aircraft manufacturer design data may be utilized as validation data as determined acceptable by the NSPM.  Test requirement may be met through column force validation testing in conjunction with the Stall Characteristics test (2.c.8.a.).  This test is required only for FSTDs qualified to conduct full stall training tasks.		
2.b.	Dynamic Control Tes	ts.							run stan tranning tasks.		
		t installed in the FSTD. Pow		trol forces are completely generated within the red for level flight unless otherwise specified. See							
2.b.1.	Pitch Control.	For underdamped systems: $T(P_0) \pm 10\% \text{ of } P_0 \text{ or } \pm 0.05 \text{ s.}$ $T(P_1) \pm 20\% \text{ of } P_1 \text{ or } \pm 0.05 \text{ s.}$ $T(P_2) \pm 30\% \text{ of } P_2 \text{ or } \pm 0.05 \text{ s.}$ $T(P_a) \pm 10*(n+1)\% \text{ of } P_n \text{ or } \pm 0.05 \text{ s.}$ $T(P_n) \pm 10*(n+1)\% \text{ of } P_n \text{ or } \pm 0.05 \text{ s.}$ $T(A_n) \pm 10\% \text{ of } A_{max}, \text{ where } A_{max} \text{ is the largest amplitude or } \pm 0.5\% \text{ of }$	Takeoff, Cruise, and Landing.	Data must be for normal control displacements in both directions (approximately 25% to 50% of full throw or approximately 25% to 50% of maximum allowable pitch controller deflection for flight conditions limited by the maneuvering load envelope).  Tolerances apply against the absolute values of each period (considered independently).			X	X	n = the sequential period of a full oscillation.  Refer to paragraph 4 of this Attachment.  For overdamped and critically damped systems, see Figure A2B of Appendix A for an illustration of the reference measurement.		

Table A2A - Full Flight Simulator (FFS) Objective Tests										
7	Гest	Tolerance	QPS REQUIREM Flight	Test	S	Simu Le	llato vel	r	INFORMATION  Notes	
Entry Number	Title	Tolerance	Conditions	Details	A	В	C	D	Notes	
		the total control travel (stop to stop).								
		$T(A_d) \pm 5\%$ of $A_d =$ residual band or $\pm 0.5\%$ of the maximum control travel = residual band.								
		±1 significant overshoots (minimum of 1 significant overshoot).								
		Steady state position within residual band.								
		Note 1.— Tolerances should not be applied on period or amplitude after the last significant overshoot.								
		Note 2.— Oscillations within the residual band are not considered significant and are not subject to tolerances.								
		For overdamped and critically damped systems only, the following tolerance applies: $T(P_0) \pm 10\%$ of $P_0$ or $\pm 0.05$ s.								

	Table A2A - Full Flight Simulator (FFS) Objective Tests										
	QPS REQUIREMENTS										
	Test	- Tolerance	Flight	Test	S	imu Le		r	Notes		
Entry Number	Title		Conditions	Details	A	В	C	D			
2.b.2.	Roll Control.	Same as 2.b.1.	Takeoff, Cruise, and Landing.	Data must be for normal control displacement (approximately 25% to 50% of full throw or approximately 25% to 50% of maximum allowable roll controller deflection for flight conditions limited by the maneuvering load envelope).			X	X	Refer to paragraph 4 of this Attachment.  For overdamped and critically damped systems, see Figure A2B of Appendix A for an illustration of the reference measurement.		
2.b.3.	Yaw Control.	Same as 2.b.1.	Takeoff, Cruise, and Landing.	Data must be for normal control displacement (approximately 25% to 50% of full throw).			X	X	Refer to paragraph 4 of this Attachment.  For overdamped and critically damped systems, see Figure A2B of Appendix A for an illustration of the reference measurement.		
2.b.4.	Small Control Inputs – Pitch.	±0.15°/s body pitch rate or ±20% of peak body pitch rate applied throughout the time history.	Approach or Landing.	Control inputs must be typical of minor corrections made while established on an ILS approach (approximately 0.5 to 2°/s pitch rate).  Test in both directions.  Show time history data from 5 s before until at least 5 s after initiation of control input.  If a single test is used to demonstrate both directions, there must be a minimum of 5 s before control reversal to the opposite direction.  CCA: Test in normal and non-normal control state.			X	X			
2.b.5.	Small Control Inputs - Roll.	±0.15°/s body roll rate or ±20% of peak body roll rate applied throughout the time history.	Approach or landing.	Control inputs must be typical of minor corrections made while established on an ILS approach (approximately 0.5 to 2°/s roll rate).  Test in one direction. For airplanes that exhibit non-symmetrical behavior, test in both directions.			X	X			

	Table A2A - Full Flight Simulator (FFS) Objective Tests										
	QPS REQUIREMENTS										
	Test	- Tolerance	Flight	Test	S	imu Le		r	Notes		
Entry Number	Title	Toterunce	Conditions	Details	A	В	C	D	Tiotes		
2.b.6.	Small Control Inputs  – Yaw.	±0.15°/s body yaw rate or ±20% of peak body yaw rate applied throughout the time history.	Approach or landing.	Show time history data from 5 s before until at least 5 s after initiation of control input.  If a single test is used to demonstrate both directions, there must be a minimum of 5 s before control reversal to the opposite direction.  CCA: Test in normal and non-normal control state.  Control inputs must be typical of minor corrections made while established on an ILS approach (approximately 0.5 to 2°/s yaw rate).  Test in both directions.  Show time history data from 5 s before until at least 5 s after initiation of control input.  If a single test is used to demonstrate both directions, there must be a minimum of 5 s before control reversal to the opposite direction.			X	X			
				CCA: Test in normal and non-normal control state.							
2.c.	Longitudinal Control										
	· ·	quired for level flight unless									
2.c.1.	Power Change Dynamics.	±3 kt airspeed. ±30 m (100 ft) altitude. ±1.5° or ±20% of pitch angle.	Approach.	Power change from thrust for approach or level flight to maximum continuous or go-around power.	X	X	X	X			
		ungic.		Time history of uncontrolled free response for a time increment equal to at least 5 s before initiation of the power change to the completion							

	Table A2A - Full Flight Simulator (FFS) Objective Tests										
	QPS REQUIREMENTS										
	Test	Tolerance	Flight	Test	S	imu Le	ılato vel	r	- Notes		
Entry Number	Title	Tolerance	Conditions	Details	A	В	C	D	11000		
				of the power change + 15 s. CCA: Test in normal and non-normal control mode							
2.c.2.	Flap/Slat Change Dynamics.	$\pm 3$ kt airspeed. $\pm 30$ m (100 ft) altitude. $\pm 1.5^{\circ}$ or $\pm 20\%$ of pitch angle.	Takeoff through initial flap retraction, and approach to landing.	Time history of uncontrolled free response for a time increment equal to at least 5 s before initiation of the reconfiguration change to the completion of the reconfiguration change + 15 s.  CCA: Test in normal and non-normal control mode	X	X	X	X			
2.c.3.	Spoiler/Speedbrake Change Dynamics.	±3 kt airspeed.  ±30 m (100 ft) altitude.  ±1.5° or ±20% of pitch angle.	Cruise.	Time history of uncontrolled free response for a time increment equal to at least 5 s before initiation of the configuration change to the completion of the configuration change +15 s.  Results required for both extension and retraction.  CCA: Test in normal and non-normal control mode	X	X	X	X			
2.c.4.	Gear Change Dynamics.	±3 kt airspeed. ±30 m (100 ft) altitude. ±1.5° or ±20% of pitch angle.	Takeoff (retraction), and Approach (extension).	Time history of uncontrolled free response for a time increment equal to at least 5 s before initiation of the configuration change to the completion of the configuration change + 15 s.  CCA: Test in normal and non-normal control mode	X	X	X	X			
2.c.5.	Longitudinal Trim.	$\pm 1^{\circ}$ elevator angle. $\pm 0.5^{\circ}$ stabilizer or trim surface angle.	Cruise, Approach, and Landing.	Steady-state wings level trim with thrust for level flight. This test may be a series of snapshot tests.  CCA: Test in normal or non-normal control mode, as applicable.	X	X	X	X			

	Table A2A - Full Flight Simulator (FFS) Objective Tests  QPS REQUIREMENTS  INFORMATION											
	QPS REQUIREMENTS											
	Test	Tolerance	Flight	Test	S		ılato evel	r	Notes			
Entry Number	Title	Toteranee	Conditions	Details	A	В	C	D	110005			
2.c.6.	Longitudinal	±1° pitch angle.  ±5% of net thrust or equivalent.  ±2.2 daN (5 lbf) or	Cruise, Approach, and	Continuous time history data or a series of	X	X	X	X				
26.0	Maneuvering Stability (Stick Force/g).	±10% of pitch controller force.  Alternative method:  ±1° or ±10% of the change of elevator angle.	Landing.	snapshot tests may be used.  Test up to approximately 30° of roll angle for approach and landing configurations. Test up to approximately 45° of roll angle for the cruise configuration.  Force tolerance not applicable if forces are generated solely by the use of airplane hardware in the FSTD.  Alternative method applies to airplanes which do not exhibit stick-force-per-g characteristics.  CCA: Test in normal or non-normal control mode	A	Α	A	Α				
2.c.7.	Longitudinal Static Stability.	±2.2 daN (5 lbf) or ±10% of pitch controller force.  Alternative method: ±1° or ±10% of the change of elevator angle.	Approach.	Data for at least two speeds above and two speeds below trim speed. The speed range must be sufficient to demonstrate stick force versus speed characteristics.  This test may be a series of snapshot tests.  Force tolerance is not applicable if forces are generated solely by the use of airplane hardware in the FSTD.  Alternative method applies to airplanes which do not exhibit speed stability characteristics.	X	X	X	X				

Table A2A - Full Flight Simulator (FFS) Objective Tests																											
			<b>QPS REQUIREM</b>	ENTS					INFORMATION																		
	Test	- Tolerance	Flight	Test	S	Simulator Level														Level		Level		Level		r	Notes
Entry Number	Title	Toterance	Conditions	Details	A	В	C	D	Notes																		
				<b>CCA:</b> Test in normal or non-normal control mode, as applicable.																							
2.c.8.a	Stall Characteristics	±3 kt airspeed for stall warning and stall speeds.  ±2.0° angle of attack for buffet threshold of perception and initial buffet based upon Nz component.  Control inputs must be plotted and demonstrate correct trend and magnitude.  Approach to stall: ±2.0° pitch angle; ±2.0° angle of attack; and ±2.0° bank angle  Stall warning up to stall: ±2.0° pitch angle; ±2.0° angle of attack; and Correct trend and magnitude for roll rate and yaw rate.  Stall Break and Recovery: SOC Required (see Attachment 7)  Additionally, for those	Second Segment Climb, High Altitude Cruise (Near Performance Limited Condition), and Approach or Landing	Each of the following stall entries must be demonstrated in at least one of the three flight conditions:  Stall entry at wings level (1g)  Stall entry in turning flight of at least 25° bank angle (accelerated stall)  Stall entry in a power-on condition (required only for propeller driven aircraft)  The cruise flight condition must be conducted in a flaps-up (clean) configuration. The second segment climb flight condition must use a different flap setting than the approach or landing flight condition.  Record the stall warning signal and initial buffet, if applicable. Time history data must be recorded for full stall through recovery to normal flight. The stall warning signal must occur in the proper relation to buffet/stall. FSTDs of airplanes exhibiting a sudden pitch attitude change or "g break" must demonstrate this characteristic. FSTDs of airplanes exhibiting a roll off or loss of roll control authority must demonstrate this characteristic.  Numerical tolerances are not applicable past the stall angle of attack, but must demonstrate correct trend through recovery. See Attachment 7 for additional requirements and information concerning data sources and required angle of attack ranges.  CCA: Test in normal and non-normal control states. For CCA aircraft with stall envelope			X	X	Buffet threshold of perception should be based on 0.03 g peak to peak normal acceleration above the background noise at the pilot seat. Initial buffet to be based on normal acceleration at the pilot seat with a larger peak to peak value relative to buffet threshold of perception (some airframe manufacturers have used 0.1 g peak to peak). Demonstrate correct trend in growth of buffet amplitude from initial buffet to stall speed for normal and lateral acceleration.  The FSTD sponsor/FSTD manufacturer may limit maximum buffet based on motion platform capability/limitations or other simulator system limitations.  Tests may be conducted at centers of gravity and weights typically required for airplane certification stall testing.  This test is required only for FSTDs qualified to conduct full stall training tasks.  In instances where flight test validation data is limited due																		

	Table A2A - Full Flight Simulator (FFS) Objective Tests										
			<b>QPS REQUIREM</b>	ENTS					INFORMATION		
	Test	Tolerance	Flight	Test	S	imu Le	lato vel	r	Notes		
Entry Number	Title	2 0202 44200	Conditions	Details	A	В	C	D	rvotes		
		simulators with reversible flight control systems or equipped with stick pusher systems: ±10% or ±5 lb (2.2 daN)) Stick/Column force (prior to the stall angle of attack).		protection systems, the normal mode testing is only required to an angle of attack range necessary to demonstrate the correct operation of the system. These tests may be used to satisfy the required (angle of attack) flight maneuver and envelope protection tests (test 2.h.6.). Non-normal control states must be tested through stall identification and recovery.					to safety of flight considerations, engineering simulator validation data may be used in lieu of flight test validation data for angles of attack that exceed the activation of a stall protection system or stick pusher system.  Where approved engineering		
									simulation validation is used, the reduced engineering tolerances (as defined in paragraph 11 of this appendix) do not apply.		
2.c.8.b	Approach to Stall Characteristics	±3 kt airspeed for stall warning speeds.  ±2.0° angle of attack for initial buffet.  Control displacements and flight control surfaces must be plotted and demonstrate correct trend and magnitude.  ±2.0° pitch angle; ±2.0° angle of attack; and ±2.0° bank angle  Additionally, for those simulators with reversible flight control systems: ±10% or ±5 lb (2.2 daN))	Second Segment Climb, High Altitude Cruise (Near Performance Limited Condition), and Approach or Landing	Each of the following stall entries must be demonstrated in at least one of the three flight conditions:  Approach to stall entry at wings level (1g) Approach to stall entry in turning flight of at least 25° bank angle (accelerated stall) Approach to stall entry in a power-on condition (required only for propeller driven aircraft)  The cruise flight condition must be conducted in a flaps-up (clean) configuration. The second segment climb flight condition must use a different flap setting than the approach or landing flight condition.  CCA: Test in Normal and Non-normal control states. For CCA aircraft with stall envelope protection systems, the normal mode testing is only required to an angle of attack range necessary to demonstrate the correct operation of the system. These tests may be used to satisfy the	X	X			Tests may be conducted at centers of gravity and weights typically required for airplane certification stall testing.  Tolerances on stall buffet are not applicable where the first indication of the stall is the activation of the stall warning system (i.e. stick shaker).		

Table A2A - Full Flight Simulator (FFS) Objective Tests											
	QPS REQUIREMENTS										
	Test	Tolerance	Flight	Test	S		imulator Level		Notes		
Entry Number	Title	Tolerunce	Conditions	Details	A	В	C	D	110005		
		Stick/Column force		required (angle of attack) flight maneuver and envelope protection tests (test 2.h.6.).							
2.c.9.	Phugoid Dynamics.	±10% of period.  ±10% of time to one half or double amplitude or ±0.02 of damping ratio.	Cruise.	Test must include three full cycles or that necessary to determine time to one half or double amplitude, whichever is less.  CCA: Test in non-normal control mode.	X	X	X	X			
2.c.10	Short Period Dynamics.	±1.5° pitch angle or ±2°/s pitch rate. ±0.1 g normal acceleration	Cruise.	CCA: Test in normal and non-normal control mode.	X	X	X	X			
2.c.11.	(Reserved)										
2.d.	Lateral Directional T	ests.									
	Power setting is that re	quired for level flight unless	otherwise specified.								
2.d.1.	Minimum control speed, air $(V_{mca})$ or landing $(V_{mcl})$ , per applicable airworthiness requirement or low speed engine-inoperative handling characteristics in the air.	±3 kt airspeed.	Takeoff or Landing (whichever is most critical in the airplane).	Takeoff thrust must be set on the operating engine(s).  Time history or snapshot data may be used.  CCA: Test in normal or non-normal control state, as applicable.	X	X	X	X	Minimum speed may be defined by a performance or control limit which prevents demonstration of $V_{\text{mea}}$ or $V_{\text{mel}}$ in the conventional manner.		
2.d.2.	Roll Response (Rate).	±2°/s or ±10% of roll rate.  For airplanes with reversible flight control systems:  ±1.3 daN (3 lbf) or ±10% of wheel force.	Cruise, and Approach or Landing.	Test with normal roll control displacement (approximately one-third of maximum roll controller travel).  This test may be combined with step input of flight deck roll controller test 2.d.3.	X	X	X	X			

	Table A2A - Full Flight Simulator (FFS) Objective Tests											
	QPS REQUIREMENTS											
	Test	- Tolerance	Flight	Test	S	imu Le		r	Notes			
Entry Number	Title		Conditions	Details	A	В	C	D	2.0002			
2.d.3.	Step input of flight deck roll controller.	±2° or ±10% of roll angle.	Approach or Landing.	This test may be combined with roll response (rate) test 2.d.2.  CCA: Test in normal and non-normal control mode	X	X	X	X	With wings level, apply a step roll control input using approximately one-third of the roll controller travel. When reaching approximately 20° to 30° of bank, abruptly return the roll controller to neutral and allow approximately 10 seconds of airplane free response.			
2.d.4.	Spiral Stability.	Correct trend and ±2° or ±10% of roll angle in 20 s. If alternate test is used: correct trend and ±2° aileron angle.	Cruise, and Approach or Landing.	Airplane data averaged from multiple tests may be used.  Test for both directions. As an alternative test, show lateral control required to maintain a steady turn with a roll angle of approximately 30°.  CCA: Test in non-normal control mode.	X	X	X	X				
2.d.5.	Engine Inoperative Trim.	±1° rudder angle or ±1° tab angle or equivalent rudder pedal.  ±2° side-slip angle.	Second Segment Climb, and Approach or Landing.	This test may consist of snapshot tests.	X	X	X	X	Test should be performed in a manner similar to that for which a pilot is trained to trim an engine failure condition.  2nd segment climb test should be at takeoff thrust. Approach or landing test should be at thrust for level flight.			
2.d.6.	Rudder Response.	$\pm 2^{\circ}$ /s or $\pm 10\%$ of yaw rate.	Approach or Landing.	Test with stability augmentation on and off.  Test with a step input at approximately 25% of full rudder pedal throw.	X	X	X	X				

	Table A2A - Full Flight Simulator (FFS) Objective Tests										
			<b>QPS REQUIREM</b>	ENTS					INFORMATION		
	Test	Tolerance	Flight	Test	S	imu Le	lato vel	r	Notes		
Entry Number	Title	Toterunee	Conditions	Details	A	В	C	D	110005		
				CCA: Test in normal and non-normal control mode							
2.d.7.	Dutch Roll	±0.5 s or ±10% of period.  ±10% of time to one half or double amplitude or ±.02 of damping ratio.  ±1 s or ±20% of time difference between peaks of roll angle and side-slip angle.	Cruise, and Approach or Landing.	Test for at least six cycles with stability augmentation off.  CCA: Test in non-normal control mode.		X	X	X			
2.d.8.	Steady State Sideslip.	For a given rudder position:  ±2° roll angle;  ±1° side-slip angle;  ±2° or ±10% of aileron angle; and  ±5° or ±10% of spoiler or equivalent roll controller position or force.  For airplanes with reversible flight control systems:  ±1.3 daN (3 lbf) or	Approach or Landing.	This test may be a series of snapshot tests using at least two rudder positions (in each direction for propeller-driven airplanes), one of which must be near maximum allowable rudder.	X	X	X	X			

	Table A2A - Full Flight Simulator (FFS) Objective Tests											
	QPS REQUIREMENTS											
	Test	Tolerance	Flight	Test	S	imu Le	llato vel	r	Notes			
Entry Number	Title	Toterunce	Conditions	Details	A	В	C	D				
		±10% of wheel force.  ±2.2 daN (5 lbf) or ±10% of rudder pedal force.										
2.e.	Landings.											
2.e.1.	Normal Landing.	±3 kt airspeed.  ±1.5° pitch angle.  ±1.5° AOA.  ±3 m (10 ft) or ±10% of height.  For airplanes with reversible flight control systems:  ±2.2 daN (5 lbf) or ±10% of column force.	Landing.	Test from a minimum of 61 m (200 ft) AGL to nosewheel touchdown.  CCA: Test in normal and non-normal control mode, if applicable.		X	X	X	Two tests should be shown, including two normal landing flaps (if applicable) one of which should be near maximum certificated landing mass, the other at light or medium mass.			
2.e.2.	Minimum Flap Landing.	±3 kt airspeed.  ±1.5° pitch angle.  ±1.5° AOA.  ±3 m (10 ft) or ±10% of height.  For airplanes with reversible flight control systems:	Minimum Certified Landing Flap Configuration.	Test from a minimum of 61 m (200 ft) AGL to nosewheel touchdown.  Test at near maximum certificated landing weight.			X	X				

Table A2A - Full Flight Simulator (FFS) Objective Tests										
			QPS REQUIREM	IENTS					INFORMATION	
	Test	- Tolerance	Flight	Test	S		ılato vel	r	Notes	
Entry Number	Title	Toterunce	Conditions	Details	A	В	C	D	Notes	
		$\pm 2.2$ daN (5 lbf) or $\pm 10\%$ of column force.								
2.e.3.	Crosswind Landing.	±3 kt airspeed.  ±1.5° pitch angle.  ±1.5° AOA.  ±3 m (10 ft) or ±10% of height.  ±2° roll angle.  ±2° side-slip angle.  ±3° heading angle.  For airplanes with reversible flight control systems:  ±2.2 daN (5 lbf) or ±10% of column force.  ±1.3 daN (3 lbf) or ±10% of wheel force.  ±2.2 daN (5 lbf) or ±10% of rudder pedal force.	Landing.	Test from a minimum of 61 m (200 ft) AGL to a 50% decrease in main landing gear touchdown speed.  Test data is required, including wind profile, for a crosswind component of at least 60% of airplane performance data value measured at 10 m (33 ft) above the runway.  Wind components must be provided as headwind and crosswind values with respect to the runway.		X	X	X	In those situations where a maximum crosswind or a maximum demonstrated crosswind is not known, contact the NSPM.	
2.e.4.	One Engine Inoperative Landing.	±3 kt airspeed. ±1.5° pitch angle.	Landing.	Test from a minimum of 61 m (200 ft) AGL to a 50% decrease in main landing gear touchdown speed.		X	X	X		

	Table A2A - Full Flight Simulator (FFS) Objective Tests										
	QPS REQUIREMENTS										
	Test	- Tolerance	Flight	Test	S		ılato vel	r	_ Notes		
Entry Number	Title	Total	Conditions	Details	A	В	С	D	Tiotes		
2.e.5.	Autopilot landing (if applicable).	±1.5° AOA.  ±3 m (10 ft) or ±10% of height.  ±2° roll angle.  ±2° side-slip angle.  ±3° heading angle.  ±1.5 m (5 ft) flare height.  ±0.5 s or ± 10% of Tf.  ±0.7 m/s (140 ft/min) rate of descent at touchdown.  ±3 m (10 ft) lateral deviation during rollout.	Landing.	If autopilot provides roll-out guidance, record lateral deviation from touchdown to a 50% decrease in main landing gear touchdown speed.  Time of autopilot flare mode engage and main gear touchdown must be noted.		X	X	X	See Appendix F of this part for definition of $T_f$ .		
2.e.6.	All-engine autopilot go-around.	±3 kt airspeed.  ±1.5° pitch angle.  ±1.5° AOA.	As per airplane performance data.	Normal all-engine autopilot go-around must be demonstrated (if applicable) at medium weight.		X	X	X			
2.e.7.	One engine inoperative go around.	±3 kt airspeed.  ±1.5° pitch angle.  ±1.5° AOA.  ±2° roll angle.	As per airplane performance data.	Engine inoperative go-around required near maximum certificated landing weight with critical engine inoperative.  Provide one test with autopilot (if applicable) and one without autopilot.		X	X	X			

	Table A2A - Full Flight Simulator (FFS) Objective Tests										
			<b>QPS REQUIREM</b>	MENTS					INFORMATION		
	Test	Tolerance	Flight	Test	S	imu Le	lato vel	r	Notes		
Entry Number	Title	_ 0.02 W.200	Conditions	Details	A	В	C	D	1,000		
		±2° side-slip angle.		CCA: Non-autopilot test to be conducted in non-normal mode.							
2.e.8.	Directional control (rudder effectiveness) with symmetric reverse thrust.	±5 kt airspeed. ±2°/s yaw rate.	Landing.	Apply rudder pedal input in both directions using full reverse thrust until reaching full thrust reverser minimum operating speed.		X	X	X			
2.e.9.	Directional control (rudder effectiveness) with asymmetric reverse thrust.	±5 kt airspeed. ±3° heading angle.	Landing.	With full reverse thrust on the operating engine(s), maintain heading with rudder pedal input until maximum rudder pedal input or thrust reverser minimum operation speed is reached.		X	X	X			
2.f.	Ground Effect.	•									
	Test to demonstrate Ground Effect.	±1° elevator angle.  ±0.5° stabilizer angle.  ±5% of net thrust or equivalent.  ±1° AOA.  ±1.5 m (5 ft) or ±10% of height.  ±3 kt airspeed.  ±1° pitch angle.	Landing.	A rationale must be provided with justification of results.  CCA: Test in normal or non-normal control mode, as applicable.		X	X	X	See paragraph 5 of this Attachment for additional information.		
2.g.	Windshear.  Four tests, two takeoff and two landing, with one of each conducted in still air and the other with windshear active to demonstrate	See Attachment 5 of this appendix.	Takeoff and Landing.	Requires windshear models that provide training in the specific skills needed to recognize windshear phenomena and to execute recovery procedures. See Attachment 5 of this appendix for tests, tolerances, and procedures.			X	X	See Attachment 5 of this appendix for information related to Level A and B simulators.		

	Table A2A - Full Flight Simulator (FFS) Objective Tests									
			ENTS					INFORMATION		
	Test	Tolerance	Flight	Test	Si		ılato vel	r	Notes	
Entry Number	Title	1010141100	Conditions	Details	A	В	C	D	110005	
	windshear models.									
2.h.	Flight Maneuver and	<b>Envelope Protection Funct</b>	ions.							
	to control inputs during		otection function (i.e. with r	ontrolled airplanes. Time history results of response normal and degraded control states if their function n function.						
2.h.1.	Overspeed.	±5 kt airspeed.	Cruise.			X	X	X		
2.h.2.	Minimum Speed.	±3 kt airspeed.	Takeoff, Cruise, and Approach or Landing.			X	X	X		
2.h.3.	Load Factor.	±0.1g normal load factor	Takeoff, Cruise.			X	X	X		
2.h.4.	Pitch Angle.	±1.5° pitch angle	Cruise, Approach.			X	X	X		
2.h.5.	Bank Angle.	$\pm 2^{\circ}$ or $\pm 10\%$ bank angle	Approach.			X	X	X		
2.h.6.	Angle of Attack.	±1.5° angle of attack	Second Segment Climb, and Approach or Landing.			X	X	X		
2.i.	Engine and Airframe	Icing Effects								
2.i.	Engine and Airframe Icing Effects Demonstration (High Angle of Attack)		Takeoff or Approach or Landing  [One flight condition – two tests (ice on and off)]	Time history of a full stall and initiation of the recovery. Tests are intended to demonstrate representative aerodynamic effects caused by inflight ice accretion. Flight test validation data is not required.  Two tests are required to demonstrate engine and airframe icing effects. One test will demonstrate the FSTDs baseline performance without ice accretion, and the second test will demonstrate the aerodynamic effects of ice accretion relative to the baseline test.  The test must utilize the icing model(s) as described in the required Statement of Compliance in Table A1A, Section 2.j. Test must include rationale that describes the icing effects being demonstrated. Icing effects may include, but are not limited to, the following effects applicable to the particular airplane type:  • Decrease in stall angle of attack			X	X	Tests will be evaluated for representative effects on relevant aerodynamic and other parameters such as angle of attack, control inputs, and thrust/power settings.  Plotted parameters must include:	

		Tab	ole A2A - Full Fligh	nt Simulator (FFS) Objective Tests					
			QPS REQUIREM	IENTS					INFORMATION
	Test	Tolerance	Flight	Test	S		ılato vel	r	Notes
Entry Number	Title	1010141100	Conditions	Details	A	В	C	D	11000
				<ul> <li>Changes in pitching moment</li> <li>Decrease in control effectiveness</li> <li>Changes in control forces</li> <li>Increase in drag</li> <li>Change in stall buffet characteristics and threshold of perception</li> <li>Engine effects (power reduction/variation, vibration, etc. where expected to be present on the aircraft in the ice accretion scenario being tested)</li> </ul>					Stall warning and stall buffet onset
3. Motion	System.								
3.a.	Frequency response.								
		As specified by the sponsor for FSTD qualification.	Not applicable.	Appropriate test to demonstrate required frequency response.	X	X	X	X	See paragraph 6 of this Attachment.
3.b.	Turn-around check.								
		As specified by the sponsor for FSTD qualification.	Not applicable.	Appropriate test to demonstrate required smooth turn-around.	X	X	X	X	See paragraph 6 of this Attachment.
3.c	Motion effects.				X	X	X	X	Refer to Attachment 3 of this Appendix on subjective testing.
3.d.	Motion system repeat	ability.		1					8
	Motion system repeatability	±0.05 g actual platform linear accelerations.	None.		X	X	X	X	Ensure that motion system hardware and software (in normal FSTD operating mode) continue to perform as originally qualified. Performance changes from the original baseline can be readily identified with this information.  See paragraph 6.c. of this Attachment.

	Table A2A - Full Flight Simulator (FFS) Objective Tests										
			<b>QPS REQUIREM</b>	MENTS					INFORMATION		
	Test	Tolerance	Flight	Test	S	imu Le		r	Notes		
Entry Number	Title	2 0101 01100	Conditions	Details	A	В	C	D	1,000		
3.e.	Motion cueing fidelity	,									
3.e.1.	Motion cueing fidelity – Frequency- domain criterion.	As specified by the FSTD manufacturer for initial qualification.	Ground and flight.	For the motion system as applied during training, record the combined modulus and phase of the motion cueing algorithm and motion platform over the frequency range appropriate to the characteristics of the simulated aircraft.  This test is only required for initial FSTD qualification.			X	X	Testing may be accomplished by the FSTD manufacturer and results provided as a statement of compliance.		
3.e.2.	Reserved										
3.f	Characteristic motion vibrations. The following tests with recorded results and an SOC are required for characteristic motion vibrations, which can be sensed at the flight deck where applicable by airplane type.	None.	Ground and flight.					X	The recorded test results for characteristic buffets should allow the comparison of relative amplitude versus frequency.  See also paragraph 6.e. of this Attachment.		
3.f.1. 3.f.2.	Thrust effect with brakes set.  Buffet with landing gear extended.	The FSTD test results must exhibit the overall appearance and trends of the airplane data, with at least three (3) of the predominant frequency "spikes" being present within ± 2 Hz of the airplane data.  The FSTD test results must exhibit the overall	Ground.  Flight.	Test must be conducted at maximum possible thrust with brakes set.  Test condition must be for a normal operational speed and not at the gear limiting speed.				X			
		appearance and trends of the airplane data, with at least three (3) of									

	Table A2A - Full Flight Simulator (FFS) Objective Tests										
			<b>QPS REQUIREM</b>	ENTS					INFORMATION		
	Test	Tolerance	Flight	Test	S		ılato evel	r	Notes		
Entry Number	Title		Conditions	Details	A	В	C	D	2.0002		
		the predominant frequency "spikes" being present within ± 2 Hz of the airplane data.									
3.f.3.	Buffet with flaps extended.	The FSTD test results must exhibit the overall appearance and trends of the airplane data, with at least three (3) of the predominant frequency "spikes" being present within ± 2 Hz of the airplane data.	Flight.	Test condition must be at a normal operational speed and not at the flap limiting speed.				X			
3.f.4.	Buffet with speedbrakes deployed.	The FSTD test results must exhibit the overall appearance and trends of the airplane data, with at least three (3) of the predominant frequency "spikes" being present within ± 2 Hz of the airplane data.	Flight.	Test condition must be at a typical speed for a representative buffet.				X			
3.f.5.	Stall buffet	The FSTD test results must exhibit the overall appearance and trends of the airplane data, with at least three (3) of the predominant frequency "spikes" being present within ± 2 Hz of the airplane data.	Cruise (High Altitude), Second Segment Climb, and Approach or Landing	Tests must be conducted for an angle of attack range between the buffet threshold of perception to the pilot and the stall angle of attack. Post stall characteristics are not required.			X	X	If stabilized flight data between buffet threshold of perception and the stall angle of attack are not available, PSD analysis should be conducted for a time span between initial buffet and the stall angle of attack.  Test required only for FSTDs qualified for full stall training tasks or for those aircraft which exhibit stall buffet before the activation of the stall		

	QPS REQUIREMENTS									
	Test	Tolerance	Flight	Test	S		ılator evel		Notes	
Entry Number	Title	Totalica	Conditions	Details	A	В	C	D		
3.f.6.	Buffet at high airspeeds or high Mach.	The FSTD test results must exhibit the overall appearance and trends of the airplane data, with at least three (3) of the predominant frequency "spikes" being present within ± 2 Hz of the airplane data.	Flight.					X	warning system.  Test condition should be for high-speed maneuver buffet/wind-up-turn or alternatively Mach buffet.	
3.f.7.	In-flight vibrations for propeller driven airplanes.	The FSTD test results must exhibit the overall appearance and trends of the airplane data, with at least three (3) of the predominant frequency "spikes" being present within ± 2 Hz of the airplane data.	Flight (clean configuration).					X	Test should be conducted to be representative of in-flight vibrations for propeller- driven airplanes.	
4. Visual S	System.	1								
4.a.	Visual scene quality									
4.a.1.	Continuous collimated cross- cockpit visual field of view.	Cross-cockpit, collimated visual display providing each pilot with a minimum of 176° horizontal and 36° vertical continuous field of view.	Not applicable.	Required as part of MQTG but not required as part of continuing evaluations.			X	X	Field of view should be measured using a visual test pattern filling the entire visual scene (all channels) consisting of a matrix of black and white 5° squares.	
									Installed alignment should be confirmed in an SOC (this would generally consist of results from acceptance testing).	
	Continuous collimated cross- cockpit visual field of view.	Continuous collimated field-of-view providing at least 45° horizontal and 30° vertical field-	Not applicable.	Required as part of MQTG but not required as part of continuing evaluations.	X	X			A vertical field-of-view of 30° may be insufficient to meet visual ground segment requirements.	

		Tab	le A2A - Full Fligh	nt Simulator (FFS) Objective Tests					
			<b>QPS REQUIREM</b>	IENTS					INFORMATION
	Test	- Tolerance	Flight	Test	S	Simu Le	ılato vel	r	Notes
Entry Number	Title	Toterance	Conditions	Details	A	В	C	D	Tiotes
		of-view for each pilot seat. Both pilot seat visual systems must be operable simultaneously.							
4.a.2.	System geometry	5° even angular spacing within ±1° as measured from either pilot eye point and within 1.5° for adjacent squares.	Not applicable.	The angular spacing of any chosen 5° square and the relative spacing of adjacent squares must be within the stated tolerances.	X	X	X	X	The purpose of this test is to evaluate local linearity of the displayed image at either pilot eye point. System geometry should be measured using a visual test pattern filling the entire visual scene (all channels) with a matrix of black and white 5° squares with light points at the intersections.  For continuing qualification testing, the use of an optical checking device is encouraged. This device should typically consist of a hand-held go/no go gauge to check that the relative positioning is maintained.
4.a.3	Surface resolution (object detection).	Not greater than 2 arc minutes.	Not applicable.	An SOC is required and must include the relevant calculations and an explanation of those calculations.  This requirement is applicable to any level of simulator equipped with a daylight visual system.			X	X	Resolution will be demonstrated by a test of objects shown to occupy the required visual angle in each visual display used on a scene from the pilot's eyepoint.  The object will subtend 2 arc minutes to the eye.  This may be demonstrated using threshold bars for a

	Table A2A - Full Flight Simulator (FFS) Objective Tests										
			QPS REQUIREN	MENTS					INFORMATION		
	Test	Tolerance	Flight	Test	S		ılato evel	r	Notes		
Entry Number	Title	2010141100	Conditions	Details	A	В	C	D	1,000		
									horizontal test.  A vertical test should also be demonstrated.		
4.a.4	Light point size.	Not greater than 5 arc minutes.	Not applicable.	An SOC is required and must include the relevant calculations and an explanation of those calculations.  This requirement is applicable to any level of simulator equipped with a daylight visual system.			X	X	Light point size should be measured using a test pattern consisting of a centrally located single row of white light points displayed as both a horizontal and vertical row.  It should be possible to move the light points relative to the eyepoint in all axes.  At a point where modulation is just discernible in each visual channel, a calculation		
4.a.5	Raster surface contrast ratio.	Not less than 5:1.	Not applicable.	This requirement is applicable to any level of simulator equipped with a daylight visual system.			X	X	should be made to determine the light spacing.  Surface contrast ratio should be measured using a raster drawn test pattern filling the entire visual scene (all channels).  The test pattern should consist of black and white squares, 5° per square, with a white square in the center of		
									each channel.  Measurement should be made on the center bright square for each channel using a 1° spot photometer. This value should have a minimum		

	Table A2A - Full Flight Simulator (FFS) Objective Tests									
			<b>QPS REQUIREM</b>	ENTS					INFORMATION	
	Test	Tolerance	Flight	Test	Simulator Level		r	Notes		
Entry Number	Title	2 0202 02200	Conditions	Details	A	В	C	D	1,000	
									brightness of 7 cd/m <sup>2</sup> (2 ft-lamberts). Measure any adjacent dark squares.	
									The contrast ratio is the bright square value divided by the dark square value.	
									Note 1. — During contrast ratio testing, FSTD aft-cab and flight deck ambient light levels should be as low as possible.	
									Note 2. — Measurements should be taken at the center of squares to avoid light spill into the measurement device.	
4.a.6	Light point contrast ratio.	Not less than 25:1.	Not applicable.	An SOC is required and must include the relevant calculations.			X	X	Light point contrast ratio should be measured using a test pattern demonstrating an area of greater than 1° area filled with white light points and should be compared to the adjacent background.  Note. — Light point modulation should be just discernible on calligraphic systems but will not be	
									discernable on raster systems.  Measurements of the background should be taken	

	Table A2A - Full Flight Simulator (FFS) Objective Tests										
	QPS REQUIREMENTS										
	Test	- Tolerance	Flight	Test	S	imu Le		r	Notes		
Entry Number	Title	1010141100	Conditions	Details	A	В	C	D	1,000		
									such that the bright square is just out of the light meter FOV.		
									Note. — During contrast ratio testing, FSTD aft-cab and flight deck ambient light levels should be as low as practical.		
	Light point contrast ratio.	Not less than 10:1.	Not applicable.		X	X					
4.a.7	Light point brightness.	Not less than 20 cd/m <sup>2</sup> (5.8 ft-lamberts).	Not applicable.				X	X	Light points should be displayed as a matrix creating a square.		
									On calligraphic systems the light points should just merge.		
									On raster systems the light points should overlap such that the square is continuous (individual light points will not be visible).		
4.a.8	Surface brightness.	Not less than 20 cd/m <sup>2</sup> (5.8 ft-lamberts) on the display.	Not applicable.	This requirement is applicable to any level of simulator equipped with a daylight visual system.			X	X	Surface brightness should be measured on a white raster, measuring the brightness using the 1° spot photometer.		
									Light points are not acceptable.		
									Use of calligraphic capabilities to enhance raster brightness is acceptable.		
4.a.9	Black level and	Black intensity:	Not applicable.		X	X	X	X	All projectors should be		

Table A2A - Full Flight Simulator (FFS) Objective Tests									
			<b>QPS REQUIREM</b>	ENTS					INFORMATION
	Test	_ Tolerance	Flight	Test	S	imu Le		r	Notes
Entry Number	Title	Toterance	Conditions	Details	A	В	C	D	110005
	sequential contrast.	Background brightness  – Black polygon brightness < 0.015 cd/m² (0.004 ft- lamberts).  Sequential contrast:  Maximum brightness –							turned off and the cockpit environment made as dark as possible. A background reading should be taken of the remaining ambient light on the screen.  The projectors should then be turned on and a black polygon displayed. A second reading
4.a.10	Motion blur.	(Background brightness  – Black polygon brightness) > 2,000:1.  When a pattern is	Not applicable.		X	X	X	X	should then be taken and the difference between this and the ambient level recorded.  A full brightness white polygon should then be measured for the sequential contrast test.  This test is generally only required for light valve projectors.  A test pattern consists of an
4.8.10	Motion blur.	rotated about the eyepoint at 10°/s, the smallest detectable gap must be 4 arc min or less.	Not applicable.		X	X	X	X	A test pattern consists of an array of 5 peak white squares with black gaps between them of decreasing width.  The range of black gap widths should at least extend above and below the required detectable gap, and be in steps of 1 arc min.  The pattern is rotated at the required rate.

			QPS REQUIREM	IENTS					INFORMATION
	Test	Tolerance	Flight	Test	S	imu Le	ılato evel	r	Notes
Entry Number	Title	Toterunce	Conditions	Details	A	В	C	D	Trotes
									Two arrays of squares should be provided, one rotating in heading and the other in pitch, to provide testing in both axes.  A series of stationary numbers identifies the gap number.  Note.— This test can be limited by the display technology. Where this is the case the NSPM should be consulted on the limitations.  This test is generally only required for light valve projectors.
4.a.11	Speckle test.	Speckle contrast must be < 10%.	Not applicable.	An SOC is required describing the test method.	X	X	X	X	This test is generally only required for <b>laser projectors</b> .
4.b	Head-Up Display (HUD)								
4.b.1	Static Alignment.	Static alignment with displayed image.  HUD bore sight must align with the center of the displayed image spherical pattern.  Tolerance +/- 6 arc min.	N/A				X	X	Alignment requirement applies to any HUD system in use or both simultaneously if they are used simultaneously for training.
4.b.2	System display.	All functionality in all flight modes must be	N/A				X	X	A statement of the system capabilities should be

	Table A2A - Full Flight Simulator (FFS) Objective Tests											
	QPS REQUIREMENTS											
	Test	- Tolerance	Flight	Test	S	imu Le		r	Notes			
Entry Number	Title		Conditions	Details	A	В	C	D	- 10002			
		demonstrated.							provided and the capabilities demonstrated			
4.b.3	HUD attitude versus FSTD attitude indicator (pitch and roll of horizon).	Pitch and roll align with aircraft instruments.	Flight.				X	X				
4.c	Enhanced Flight Vision System (EFVS)											
4.c.1	Registration test.	Alignment between EFVS display and out of the window image must represent the alignment typical of the aircraft and system type.	Takeoff point and on approach at 200 ft.				X	X	Note.— The effects of the alignment tolerance in 4.b.1 should be taken into account.			
4.c.2	EFVS RVR and visibility calibration.	The scene represents the EFVS view at 350 m (1,200 ft) and 1,609 m (1 sm) RVR including correct light intensity.	Flight.				X	X	Infra-red scene representative of both 350 m (1,200 ft), and 1,609 m (1 sm) RVR.  Visual scene may be removed.			
4.c.3	Thermal crossover.	Demonstrate thermal crossover effects during day to night transition.	Day and night.				X	X	The scene will correctly represent the thermal characteristics of the scene during a day to night transition.			
4.d	Visual ground segmen	nt										
4.d.1	Visual ground segment (VGS).	Near end: the correct number of approach lights within the computed VGS must be visible.  Far end: ±20% of the	Trimmed in the landing configuration at 30 m (100 ft) wheel height above touchdown zone on glide slope at an RVR setting of 300 m (1,000 ft) or 350 m (1,200 ft).	This test is designed to assess items impacting the accuracy of the visual scene presented to a pilot at DH on an ILS approach. These items include:  1) RVR/Visibility;	X	X	X	X				

	QPS REQUIREMENTS									
	Test	- Tolerance	Flight	Test	S	imu Le		r	Notes	
Entry Number	Title	1 0.010.100	Conditions	Details	A	В	C	D	1,000	
4.e	Visual System	computed VGS.  The threshold lights computed to be visible must be visible in the FSTD.		2) glide slope (G/S) and localizer modeling accuracy (location and slope) for an ILS;  3) for a given weight, configuration and speed representative of a point within the airplane's operational envelope for a normal approach and landing; and  4) Radio altimeter.  Note. — If non-homogeneous fog is used, the vertical variation in horizontal visibility should be described and included in the slant range visibility calculation used in the VGS computation.						
4.6	Capacity									
4.e.1	System capacity – Day mode.	Not less than: 10,000 visible textured surfaces, 6,000 light points, 16 moving models.	Not applicable.				X	X	Demonstrated through use of a visual scene rendered with the same image generator modes used to produce scenes for training.  The required surfaces, light points, and moving models should be displayed simultaneously.	
4.e.2	System capacity – Twilight/night mode.	Not less than: 10,000 visible textured surfaces, 15,000 light points, 16 moving models.	Not applicable.				X	X	Demonstrated through use of a visual scene rendered with the same image generator modes used to produce scenes for training.  The required surfaces, light points, and moving models should be displayed	

		Tab	ole A2A - Full Fligh OPS REQUIREM	at Simulator (FFS) Objective Tests					INFORMATION
	Test	Tolerance	Flight	Test	S	imu Le	ılato vel	or	Notes
Entry Number	Title	Tolerance	Conditions	Details	A	В	C	D	Titotes
									simultaneously.
during conti initial qualit the frequence sponsor may compared as 1/3-octave b	will not be required to inuing qualification evaluation resulting resulting response test method y elect to repeat the airpigainst initial qualification and format from band 1	tuations if frequency responsits, and the sponsor shows that is chosen and fails, the sponsitant tests. If the airplane tests on evaluation results or airplant to 42 (50 Hz to 16 kHz). A	e and background noise test at no software changes have sor may elect to fix the freq as are repeated during continue me master data. All tests in a minimum 20 second avera	or 5.b.1. through 5.b.9.) and 5.c., as appropriate) results are within tolerance when compared to the occurred that will affect the airplane test results. If uency response problem and repeat the test or the nuing qualification evaluations, the results may be this section must be presented using an unweighted age must be taken at the location corresponding to					
		•	ist be produced using comp	arable data analysis techniques.					
5.a.	Turbo-jet airplane	s.							All tests in this section should be presented using an unweighted 1/3-octave band format from at least band 17 to 42 (50 Hz to 16 kHz).
									A measurement of minimum 20 s should be taken at the location corresponding to the approved data set.
									The approved data set and FSTD results should be produced using comparable data analysis techniques.
									Refer to paragraph 7 of this Attachment
5.a.1.	Ready for engine start.	Initial evaluation: ± 5 dB per 1/3 octave band. Recurrent evaluation:	Ground.	Normal condition prior to engine start.  The APU should be on if appropriate.				X	For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB tolerance but not more than 2 that are consecutive and in
		cannot exceed ±5 dB difference on three consecutive bands when							any case within ± 7 dB from approved reference data, providing that the overall

	Table A2A - Full Flight Simulator (FFS) Objective Tests																		
			QPS REQUIREM	IENTS					INFORMATION										
	Test	- Tolerance	Flight	Test	S	Simulator Level		Simulator Level						Level		Level		r	Notes
Entry Number	Title	1010141100	Conditions	Details	A	В	C	D											
		compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.							trend is correct.  Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.										
5.a.2.	All engines at idle.	Initial evaluation: ± 5 dB per 1/3 octave band.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Ground.	Normal condition prior to takeoff.				X	For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB tolerance but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct.  Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.										
5.a.3.	All engines at maximum allowable thrust with brakes set.	Initial evaluation: ± 5 dB per 1/3 octave band.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial	Ground.	Normal condition prior to takeoff.				X	For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB tolerance but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct.										

	Table A2A - Full Flight Simulator (FFS) Objective Tests									
	Test	Tolerance	QPS REQUIREM Flight	Test	S		mulator Level Notes		INFORMATION	
Entry Number	Title	Tolerance	Conditions	Details	A	В	C	D	Notes	
		evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.							Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.	
5.a.4.	Climb	Initial evaluation: ± 5 dB per 1/3 octave band.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	En-route climb.	Medium altitude.				X	For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB tolerance but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct.  Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.	
5.a.5.	Cruise	Initial evaluation: ± 5 dB per 1/3 octave band.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the	Cruise.	Normal cruise configuration.				X	For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB tolerance but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct.	

		Tab	ole A2A - Full Fligh	nt Simulator (FFS) Objective Tests							
	QPS REQUIREMENTS										
	Test	- Tolerance	Flight	Test	S	imu Le		r	Notes		
Entry Number	Title		Conditions	Details	A	B	C	D			
		average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.							Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used		
5.a.6.	Speed brake/spoilers extended (as appropriate).	Initial evaluation: ± 5 dB per 1/3 octave band.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Cruise.	Normal and constant speed brake deflection for descent at a constant airspeed and power setting.				X	during recurrent evaluations.  For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB tolerance but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct.  Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.		
5.a.7	Initial approach.	Initial evaluation: ± 5 dB per 1/3 octave band.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between	Approach.	Constant airspeed, gear up, flaps/slats as appropriate.				X	For initial evaluation, it is acceptable to have some $1/3$ octave bands out of $\pm 5$ dB tolerance but not more than 2 that are consecutive and in any case within $\pm 7$ dB from approved reference data, providing that the overall trend is correct.		

	Table A2A - Full Flight Simulator (FFS) Objective Tests											
			<b>QPS REQUIREN</b>	MENTS					INFORMATION			
	Test	Tolerance	Flight	Test		Simulator Level		r	Notes			
Entry Number	Title	Toterunee	Conditions	Details	A	В	C	D	Notes			
		initial and recurrent evaluation results cannot exceed 2 dB.							employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.			
5.a.8	Final approach.	Initial evaluation: ± 5 dB per 1/3 octave band.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Landing.	Constant airspeed, gear down, landing configuration flaps.				X	For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB tolerance but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct.  Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.			

		Tab	le A2A - Full Fligh	t Simulator (FFS) Objective Tests					
			<b>QPS REQUIREM</b>	IENTS					INFORMATION
	Test	- Tolerance	Flight	Test	S	imu Le		r	Notes
Entry Number	Title	1 9101 01100	Conditions	Details	A	В	C	D	1,000
5.b	Propeller-driven a	irplanes							All tests in this section should be presented using an unweighted 1/3-octave band format from at least band 17 to 42 (50 Hz to 16 kHz).  A measurement of minimum 20 s should be taken at the location corresponding to the approved data set.  The approved data set and FSTD results should be produced using comparable data analysis techniques.  Refer to paragraph 3.7 of this Appendix.
5.b.1.	Ready for engine start.	Initial evaluation: ± 5 dB per 1/3 octave band.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Ground.	Normal condition prior to engine start.  The APU should be on if appropriate.				X	For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB tolerance but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct.  Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.

Table A2A - Full Flight Simulator (FFS) Objective Tests									
			QPS REQUIREM	IENTS					INFORMATION
	Test	Tolerance	Flight	Test	S	imu Le	latoı vel	r	Notes
Entry Number	Title	Toterunce	Conditions	Details	A	В	C	D	11000
5.b.2	All propellers feathered, if applicable.	Initial evaluation: ± 5 dB per 1/3 octave band.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Ground.	Normal condition prior to takeoff.				X	For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB tolerance but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct.  Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.
5.b.3.	Ground idle or equivalent.	Initial evaluation: ± 5 dB per 1/3 octave band.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Ground.	Normal condition prior to takeoff.				X	For initial evaluation, it is acceptable to have some $1/3$ octave bands out of $\pm$ 5 dB tolerance but not more than 2 that are consecutive and in any case within $\pm$ 7 dB from approved reference data, providing that the overall trend is correct.  Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.

		Tal	ole A2A - Full Flig	ht Simulator (FFS) Objective Te	ests				
			QPS REQUIREM	MENTS					INFORMATION
	Test	Tolerance	Flight	Test	S		ulato evel	r	Notes
Entry Number	Title	Toterunce	Conditions	Details	A	В	C	D	110005
5.b.4	Flight idle or equivalent.	Initial evaluation: ± 5 dB per 1/3 octave band.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Ground.	Normal condition prior to takeoff.				X	For initial evaluation, it is acceptable to have some $1/3$ octave bands out of $\pm$ 5 dB tolerance but not more than 2 that are consecutive and in any case within $\pm$ 7 dB from approved reference data, providing that the overall trend is correct.  Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.
5.b.5	All engines at maximum allowable power with brakes set.	Initial evaluation: ± 5 dB per 1/3 octave band.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Ground.	Normal condition prior to takeoff.				X	For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB tolerance but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct.  Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.
5.b.6	Climb.	Initial evaluation: ± 5 dB per 1/3 octave	En-route climb.	Medium altitude.				X	For initial evaluation, it is acceptable to have some 1/3

		Tab	le A2A - Full Fligh	t Simulator (FFS) Objective Tests					
			<b>QPS REQUIREM</b>	ENTS					INFORMATION
	Test	- Tolerance	Flight	Test	S		ılato evel	r	Notes
Entry Number	Title		Conditions	Details	A	В	C	D	
5.b.7	Cruise	band.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.  Initial evaluation: ± 5 dB per 1/3 octave band.	Cruise.	Normal cruise configuration.				X	octave bands out of ± 5 dB tolerance but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct.  Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.  For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB
		Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.							tolerance but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct.  Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.
5.b.8	Initial approach.	Initial evaluation: ± 5 dB per 1/3 octave band.	Approach.	Constant airspeed, gear up, flaps extended as appropriate, RPM as per operating manual.				X	For initial evaluation, it is acceptable to have some $1/3$ octave bands out of $\pm 5$ dB tolerance but not more than 2

Table A2A - Full Flight Simulator (FFS) Objective Tests											
			<b>QPS REQUIREM</b>	IENTS					INFORMATION		
	Test	Tolerance	Flight	Test	S	Simulator Level		r	Notes		
Entry Number	Title		Conditions	Details	A	В	C	D	- 1,5552		
5.b.9	Final approach.	Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Landing.	Constant airspeed				X	that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct.  Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.  For initial evaluation, it is		
3.0.9	гіпаі арргоасіі.	Initial evaluation: ± 5 dB per 1/3 octave band.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Landing.	Constant airspeed, gear down, landing configuration flaps, RPM as per operating manual.				X	For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB tolerance but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct.  Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.		
5.c.	Special cases.	Initial evaluation: ± 5 dB per 1/3 octave band.  Recurrent evaluation: cannot exceed ±5 dB	As appropriate.					X	This applies to special steady- state cases identified as particularly significant to the pilot, important in training, or unique to a specific airplane type or model.		

		Tab	le A2A - Full Fligh	t Simulator (FFS) Objective Tests													
			<b>QPS REQUIREM</b>	ENTS					INFORMATION								
	Test	Tolerance	Flight	Test	S	Simulator Level						Simulator Level				r	Notes
Entry Number	Title		Conditions	Details	A	В	C	D	1,000								
		difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.							For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB tolerance but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct.  Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used								
5.d	FSTD background noise	Initial evaluation: background noise levels must fall below the sound levels described in Paragraph 7.c (5) of this Attachment.  Recurrent evaluation: ±3 dB per 1/3 octave band compared to initial evaluation.		Results of the background noise at initial qualification must be included in the QTG document and approved by the NSPM.  The measurements are to be made with the simulation running, the sound muted and a dead cockpit.				X	during recurrent evaluations  The simulated sound will be evaluated to ensure that the background noise does not interfere with training.  Refer to paragraph 7 of this Attachment.  This test should be presented using an unweighted 1/3 octave band format from band 17 to 42 (50 Hz to 16 kHz).								
5.e	Frequency response	Initial evaluation: not applicable.  Recurrent evaluation: cannot exceed ±5 dB	Ground (static with all systems switched off)					X	Only required if the results are to be used during continuing qualification evaluations in lieu of airplane tests.								

		Tab	le A2A - Full Fligh	t Simulator (FFS) Objective Tests					
			<b>QPS REQUIREM</b>	ENTS					INFORMATION
	Test	- Tolerance	Flight	Test	Simulator Level			r	Notes
Entry Number	Title	2 0102 01200	Conditions	Details	A	В	C	D	
		difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.							The results must be approved by the NSPM during the initial qualification.  This test should be presented using an unweighted 1/3 octave band format from band 17 to 42 (50 Hz to 16 kHz).
6	SYSTEMS INTEGRATION								
6.a.	System response time								
6.a.1	Transport delay.	Motion system and instrument response: 100 ms (or less) after airplane response.  Visual system response: 120 ms (or less) after airplane response.	Pitch, roll and yaw.				X	X	One separate test is required in each axis.  Where EFVS systems are installed, the EFVS response should be within + or - 30 ms from visual system response, and not before motion system response.  Note.— The delay from the airplane EFVS electronic elements should be added to the 30 ms tolerance before comparison with visual system reference.
	Transport delay.	300 milliseconds or less after controller movement.	Pitch, roll and yaw.		X	X			, , , , , , , , , , , , , , , , , , , ,

3. Correct the tables appearing on pages 18284-18300 to read as follows:

	<b>Table A3A - Functions And Subjective Tests</b>				
	QPS REQUIREMENTS				
Entry Number	Operations Tasks		Simulator Leve		
	Tasks in this table are subject to evaluation if appropriate for the a		1		D
	indicated in the SOQ Configuration List or the level of simulator				
	Items not installed or not functional on the simulator and, therefore	•			
	SOQ Configuration List, are not required to be listed as exception				
1.	Preparation For Flight				
1.a.	<b>Pre-flight.</b> Accomplish a functions check of all switches, indi	cators.	syste	ms, an	d
	equipment at all crew members' and instructors' stations	s and c	leterm	ine tha	ıt:
1.a.1	The flight deck design and functions are identical to that of the	X	X	X	X
	airplane being simulated.				
1.a.2	Reserved				
1.a.3	Reserved				
2.	Surface Operations (pre-flight).				
2.a.	Engine Start	1	ı	ı	ı
2.a.1.	Normal start	X	X	X	X
2.a.2.	Alternate start procedures	X	X	X	X
2.a.3.	Abnormal starts and shutdowns (e.g., hot/hung start, tail pipe	X	X	X	X
21	fire)				
2.b.	Taxi Duckhook/novyowhook	l	v	v	v
2.b.1 2.b.2.	Pushback/powerback Thrust response	X	X	X	X
2.b.2. 2.b.3.	Thrust response  Power lever friction	X	X	X	X
2.b.3. 2.b.4.	Ground handling	X	X	X	X
2.b.5.	Nosewheel scuffing	Λ	Λ	X	X
2.b.6.	Taxi aids (e.g. taxi camera, moving map)			X	X
2.b.7.	Low visibility (taxi route, signage, lighting, markings, etc.)			X	X
2.c.	Brake Operation				
2.c.1.	Brake operation (normal and alternate/emergency)	X	X	X	X
2.c.2.	Brake fade (if applicable)	X	X	X	X
2.d	Other				
3.	Take-off.	•			
3.a.	Normal				
3.a.1.	Airplane/engine parameter relationships, including run-up	X	X	X	X
3.a.2.	Nosewheel and rudder steering	X	X	X	X
3.a.3.a	Crosswind (maximum demonstrated)	X	X	X	X
3.a.3.b	Gusting crosswind			X	X
3.a.4.	Special performance				
3.a.4.a	Reduced V <sub>1</sub>	X	X	X	X
3.a.4.b	Maximum engine de-rate	X	X	X	X
3.a.4.c	Soft surface	<u> </u>		X	X
3.a.4.d	Short field/short take-off and landing (STOL) operations	X	X	X	X

	Table A3A - Functions And Subjective Tests				
	QPS REQUIREMENTS	ı			
Entry Number	Operations Tasks	Sin	mulat B	tor Le	evel
3.a.4.e	Obstacle (performance over visual obstacle)	11		X	X
3.a.5.	Low visibility take-off	X	X	X	X
3.a.6.	Landing gear, wing flap leading edge device operation	X	X	X	X
3.a.7.	Contaminated runway operation			X	X
3.a.8.	Other				
3.b.	Abnormal/emergency		<b>J</b>		I
3.b.1.	Rejected Take-off	X	X	X	X
3.b.2.	Rejected special performance (e.g., reduced V <sub>1</sub> , max de-rate, short field operations)	X	X	X	X
2 h 2	Rejected take-off with contaminated runway	+		X	X
3.b.3. 3.b.4.	Takeoff with a propulsion system malfunction (allowing an	X	X	X	X
3.0.7.	analysis of causes, symptoms, recognition, and the effects on aircraft performance and handling) at the following points:  (i) Prior to V1 decision speed;  (ii) Between V1 and Vr (rotation speed); and  (iii)Between Vr and 500 feet above ground level.	A	A	A	A
3.b.5.	Flight control system failures, reconfiguration modes, manual reversion and associated handling.	X	X	X	X
3.b.6.	Other				
4.	Climb.	· ·			1
4.a.	Normal.	X	X	X	X
4.b.	One or more engines inoperative.	X	X	X	X
4.c.	Approach climb in icing (for airplanes with icing accountability).	X	X	X	X
4.d.	Other				
5.	Cruise.				
5.a.	Performance characteristics (speed vs. power, configuration,	and at	titude	:)	
5.a.1.	Straight and level flight.		X	X	X
5.a.2.	Change of airspeed.	X	X	X	X
5.a.3.	High altitude handling.	X	X	X	X
5.a.4.	High Mach number handling (Mach tuck, Mach buffet) and recovery (trim change).	X	X	X	X
5.a.5.	Overspeed warning (in excess of $V_{mo}$ or $M_{mo}$ ).	X	X	X	X
5.a.6.	High IAS handling.	X	X	X	X
5.a.7.	Other				
5.b.	Maneuvers	•	•	•	•
5.b.1.	High Angle of Attack				
5.b.1.a	High angle of attack, approach to stalls, stall warning, and stall buffet (take-off, cruise, approach, and landing configuration) including reaction of the autoflight system and stall protection system.	X	X		
5.b.1.b	High angle of attack, approach to stalls, stall warning, stall buffet, and stall (take-off, cruise, approach, and landing			X	X

	Table A3A - Functions And Subjective Tests				
	QPS REQUIREMENTS				
Entry Number	Operations Tasks	Sin	mulat B	or Le	vel
	configuration) including reaction of the autoflight system and	A	В		ע
	stall protection system.				
5.b.2.	Slow flight			X	X
5.b.3.	Upset prevention and recovery maneuvers within the FSTD's			X	X
3.0.3.	validation envelope.			21	1
5.b.4.	Flight envelope protection (high angle of attack, bank limit,	X	X	X	X
	overspeed, etc.)				
5.b.5.	Turns with/without speedbrake/spoilers deployed	X	X	X	X
5.b.6.	Normal and standard rate turns	X	X	X	X
5.b.7.	Steep turns	X	X	X	X
5.b.8.	Performance turn			X	X
5.b.9.	In flight engine shutdown and restart (assisted and windmill)	X	X	X	X
5.b.10.	Maneuvering with one or more engines inoperative, as	X	X	X	X
	appropriate				
5.b.11.	Specific flight characteristics (e.g. direct lift control)	X	X	X	X
5.b.12.	Flight control system failures, reconfiguration modes, manual	X	X	X	X
	reversion and associated handling	1			
5.b.13	Gliding to a forced landing	<u> </u>	<u> </u>	X	X
5.b.14	Visual resolution and FSTD handling and performance for the fo	llowing	g (whe	re	
	applicable by aircraft type and training program):	1	1		
5.b.14.a	Terrain accuracy for forced landing area selection;	-		X	X
5.b.14.b	Terrain accuracy for VFR Navigation;			X	X
5.b.14.c	Eights on pylons (visual resolution);			X	X
5.b.14.d	Turns about a point; and	1		X	X
5.b.14.e	S-turns about a road or section line.	1		X	X
5.b.15	Other.				
6.	Descent.	_	1	ı	1
6.a.	Normal	X	X	X	X
6.b.	Maximum rate/emergency (clean and with speedbrake, etc.).	X	X	X	X
6.c.	With autopilot.	X	X	X	X
6.d.	Flight control system failures, reconfiguration modes, manual	X	X	X	X
	reversion and associated handling.	1			
6.e.	Other				<u> </u>
7.	Instrument Approaches And Landing.				
	Those instrument approach and landing tests relevant to the simu				are
	selected from the following list. Some tests are made with limiting	-			c
	under windshear conditions, and with relevant system failures, in				10
	the Flight Director. If Standard Operating Procedures allow use a				***
	precision approaches, evaluation of the autopilot will be included	. Leve	1 A S11	nunato	IS
7.0	are not authorized to credit the landing maneuver.				
7.a. 7.a.1	Precision approach	1			
	CAT I published approaches.  Manual approach with/without flight director including	v	v	v	<b>3</b> 7
7.a.1.a	Manual approach with/without flight director including	X	X	X	X

	Table A3A - Functions And Subjective Tests				
	QPS REQUIREMENTS	I			
Entry Number	Operations Tasks	Sin	mulat B	or Le	evel
	landing.	А	<b>D</b>		<i>D</i>
7.a.1.b	Autopilot/autothrottle coupled approach and manual landing.	X	X	X	X
7.a.1.c	Autopilot/autothrottle coupled approach, engine(s) inoperative.	X	X	X	X
7.a.1.d	Manual approach, engine(s) inoperative.	X	X	X	X
7.a.1.e	HUD/EFVS			X	X
7.a.2	CAT II published approaches.				
7.a.2.a	Autopilot/autothrottle coupled approach to DH and landing (manual and autoland).	X	X	X	X
7.a.2.b	Autopilot/autothrottle coupled approach with one-engine- inoperative approach to DH and go-around (manual and autopilot).	X	X	X	X
7.a.2.c	HUD/EFVS			X	X
7.a.3	CAT III published approaches.				
7.a.3.a	Autopilot/autothrottle coupled approach to landing and roll- out (if applicable) guidance (manual and autoland).	X	X	X	X
7.a.3.b	Autopilot/autothrottle coupled approach to DH and go- around (manual and autopilot).	X	X	X	X
7.a.3.c	Autopilot/autothrottle coupled approach to land and roll-out (if applicable) guidance with one engine inoperative (manual and autoland).	X	X	X	X
7.a.3.d	Autopilot/autothrottle coupled approach to DH and go- around with one engine inoperative (manual and autopilot).	X	X	X	X
7.a.3.e	HUD/EFVS			X	X
7.a.4	Autopilot/autothrottle coupled approach (to a landing or to a goaround):				
7.a.4.a	With generator failure;	X	X	X	X
7.a.4.b.1	With maximum tail wind component certified or authorized;			X	X
7.a.4.b.2	With 10 knot tail wind;	X	X		
7.a.4.c.1	With maximum crosswind component demonstrated or authorized; and			X	X
7.a.4.c.2	With 10 knot crosswind.	X	X		
7.a.5	PAR approach, all engine(s) operating and with one or more engine(s) inoperative	X	X	X	X
7.a.6	MLS, GBAS, all engine(s) operating and with one or more engine(s) inoperative	X	X	X	X
7.b.	Non-precision approach.				
7.b.1	Surveillance radar approach, all engine(s) operating and with one or more engine(s) inoperative	X	X	X	X
7.b.2	NDB approach, all engine(s) operating and with one or more engine(s) inoperative	X	X	X	X

	Table A3A - Functions And Subjective Tests						
	QPS REQUIREMENTS						
Entry Number	Operations Tasks	Sin	1	ulator Level			
7.b.3	VOR, VOR/DME, TACAN approach, all engines(s) operating	X	X	X	X		
7.0.0	and with one or more engine(s) inoperative	1	7.	11	7.		
7.b.4	RNAV / RNP / GNSS (RNP at nominal and minimum	X	X	X	X		
	authorized temperatures) approach, all engine(s) operating and						
	with one or more engine(s) inoperative						
7.b.5	ILS LLZ (LOC), LLZ back course (or LOC-BC) approach, all	X	X	X	X		
	engine(s) operating and with one or more engine(s) inoperative						
7.b.6	ILS offset localizer approach, all engine(s) operating and with	X	X	X	X		
	one or more engine(s) inoperative						
7.c	Approach procedures with vertical guidance (APV), e.g.						
	SBAS, flight path vector						
7.c.1	APV/baro-VNAV approach, all engine(s) operating and with			X	X		
	one or more engine(s) inoperative						
7.c.2	Area navigation (RNAV) approach procedures based on SBAS,			X	X		
	all engine(s) operating and with one or more engine(s)						
8.	inoperative Visual Approaches (Visual Segment) And Landings.						
			or tnat	partic	ular		
⊢ 8.a.	approach procedure.  Maneuvering, normal approach and landing, all engines			•			
8.a.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance	X	X	x partic	eular X		
8.a. 8.b.	Maneuvering, normal approach and landing, all engines			•			
	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance	X	X	X	X		
8.b.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance  Approach and landing with one or more engines inoperative  Operation of landing gear, flap/slats and speedbrakes (normal	X	X	X	X		
8.b. 8.c.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance  Approach and landing with one or more engines inoperative  Operation of landing gear, flap/slats and speedbrakes (normal and abnormal)	X X X	X X X	X X X	X X X		
8.b. 8.c. 8.d.1	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures,	X X X	X X X	X X X	X X X		
8.b. 8.c. 8.d.1 8.d.2	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated	X X X	X X X	X X X	X X X		
8.b. 8.c. 8.d.1 8.d.2 8.e.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable)	X X X	X X X X	X X X X X	X X X X X		
8.b. 8.c. 8.d.1 8.d.2 8.e.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance  Approach and landing with one or more engines inoperative  Operation of landing gear, flap/slats and speedbrakes (normal and abnormal)  Approach and landing with crosswind (max. demonstrated)  Approach and landing with gusting crosswind  Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable)  Approach and landing with trim malfunctions	X X X X	X X X X	X X X X X	X X X X X		
8.b. 8.c. 8.d.1 8.d.2 8.e. 8.e.1.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable) Approach and landing with trim malfunctions Longitudinal trim malfunction	X X X X	X X X X X	X X X X X X X	X X X X X X X		
8.b. 8.c. 8.d.1 8.d.2 8.e. 8.e.1. 8.e.1.a 8.e.1.b	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable) Approach and landing with trim malfunctions Longitudinal trim malfunction Lateral-directional trim malfunction	X X X X X X	X X X X X X	X X X X X X X	X X X X X X X		
8.b. 8.c. 8.d.1 8.d.2 8.e. 8.e.1.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable) Approach and landing with trim malfunctions Longitudinal trim malfunction Lateral-directional trim malfunction Approach and landing with standby (minimum) electrical/hydraulic power	X X X X X X X X X	X X X X X X X X X X	X X X X X X X X	X X X X X X X X		
8.b. 8.c. 8.d.1 8.d.2 8.e. 8.e.1. 8.e.1.a 8.e.1.b	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable) Approach and landing with trim malfunctions Longitudinal trim malfunction Lateral-directional trim malfunction Approach and landing with standby (minimum)	X X X X X X	X X X X X X	X X X X X X X	X X X X X X X		
8.b. 8.c. 8.d.1 8.d.2 8.e. 8.e.1. 8.e.1.a 8.e.1.b 8.f.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable) Approach and landing with trim malfunctions Longitudinal trim malfunction Lateral-directional trim malfunction Approach and landing with standby (minimum) electrical/hydraulic power Approach and landing from circling conditions (circling	X X X X X X X X X X	X X X X X X X X X X X	X X X X X X X X	X X X X X X X X X X		
8.b. 8.c.  8.d.1 8.d.2 8.e.  8.e.1. 8.e.1.a 8.e.1.b 8.f.  8.g.  8.h. 8.i.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable) Approach and landing with trim malfunctions Longitudinal trim malfunction Lateral-directional trim malfunction Approach and landing with standby (minimum) electrical/hydraulic power Approach and landing from circling conditions (circling approach) Approach and landing from visual traffic pattern Approach and landing from non-precision approach	X X X X X X X X X X X	X X X X X X X X X X X X	X X X X X X X X X X X X	X X X X X X X X X X X X		
8.b. 8.c.  8.d.1 8.d.2 8.e.  8.e.1. 8.e.1.a 8.e.1.b 8.f.  8.g.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable) Approach and landing with trim malfunctions Longitudinal trim malfunction Lateral-directional trim malfunction Approach and landing with standby (minimum) electrical/hydraulic power Approach and landing from circling conditions (circling approach) Approach and landing from visual traffic pattern	X X X X X X X X X X	X X X X X X X X X X X	X X X X X X X X X X X X	X X X X X X X X X X		

	Table A3A - Functions And Subjective Tests				
	QPS REQUIREMENTS				
Entry Number	Operations Tasks	Simulator L			vel D
9.	Missed Approach.	1			
9.a.	All engines, manual and autopilot.	X	X	X	X
9.b.	Engine(s) inoperative, manual and autopilot.	X	X	X	X
9.c.	Rejected landing			X	X
9.d.	With flight control system failures, reconfiguration modes, manual reversion and associated handling	X	X	X	X
9.e.	Bounced landing recovery			X	X
10.	Surface Operations (landing, after-landing and post-flight).				
10.a	Landing roll and taxi				
10.a.1	HUD/EFVS			X	X
10.a.2.	Spoiler operation	X	X	X	X
10.a.3.	Reverse thrust operation	X	X	X	X
10.a.4.	Directional control and ground handling, both with and without reverse thrust		X	X	X
10.a.5.	Reduction of rudder effectiveness with increased reverse thrust (rear pod-mounted engines)		X	X	X
10.a.6.	Brake and anti-skid operation				
10.a.6.a	Brake and anti-skid operation with dry, patchy wet, wet on			X	X
	rubber residue, and patchy icy conditions				
10.a.6.b	Reserved				
10.a.6.c	Brake operation	X	X		
10.a.6.d	Auto-braking system operation	X	X	X	X
10.a.7	Other				
10.b	Engine shutdown and parking				
10.b.1	Engine and systems operation	X	X	X	X
10.b.2	Parking brake operation	X	X	X	X
10.b.3	Other				
11.	Any Flight Phase.				
11.a.	Airplane and engine systems operation (where fitted)	₹7	₹7	₹7	<b>T</b> 7
11.a.1.	Air conditioning and pressurization (ECS)	X	X	X	X
11.a.2.	De-icing/anti-icing	X	X	X	X
11.a.3.	Auxiliary power unit (APU).	X	X	X	X
11.a.4.	Communications	X	X	X	X
11.a.5.	Electrical	X	X	X	X
11.a.6.	Fire and smoke detection and suppression	X	X	X	X
11.a.7.	Flight controls (primary and secondary)	X	X	X	X
11.a.8.	Fuel and oil	X	X	X	X
11.a.9.	Hydraulic	X	X	X	X
11.a.10.	Pneumatic Londing good	X	X	X	X
11.a.11.	Landing gear	X	X	X	X
11.a.12.	Oxygen	X	X	X	X
11.a.13.	Engine	X	X	X	X

	Table A3A - Functions And Subjective Tests				
	QPS REQUIREMENTS				
<b>Entry</b> <b>Number</b>	Operations Tasks	Simula A B			evel
11.a.14.	Airborne radar	X	X	C X	X
11.a.15.	Autopilot and Flight Director	X	X	X	X
11.a.16.	Terrain awareness warning systems and collision avoidance systems (e.g. EGPWS, GPWS, TCAS)	X	X	X	X
11.a.17.	Flight control computers including stability and control augmentation	X	X	X	X
11.a.18.	Flight display systems	X	X	X	X
11.a.19.	Flight management computers	X	X	X	X
11.a.20.	Head-up displays (including EFVS, if appropriate)	X	X	X	X
11.a.21.	Navigation systems	X	X	X	X
11.a.22.	Stall warning/avoidance	X	X	X	X
11.a.23.	Wind shear avoidance/recovery guidance equipment	X	X	X	X
11.a.24.	Flight envelope protections	X	X	X	X
11.a.25.	Electronic flight bag			X	X
11.a.26.	Automatic checklists (normal, abnormal and emergency procedures)			X	X
11.a.27.	Runway alerting and advisory system			X	X
11.a.28.	Other				
11.b.	Airborne procedures			1	
11.b.1.	Holding	X	X	X	X
11.b.2.	Air hazard avoidance (traffic, weather, including visual correlation)			X	X
11.b.3.	Windshear				
11.b.3.a	Prior to take-off rotation			X	X
11.b.3.b	At lift-off			X	X
11.b.3.c	During initial climb			X	X
11.b.3.d	On final approach, below 150 m (500 ft) AGL			X	X
11.b.4.	Effects of airframe ice			X	X

	Table A3B - Functions and Subjective Tests					
	QPS REQUIREMENTS					
Entry Vumber	For Qualification At The Stated Level	Simulator Level				
En	Class I Airport Models	A	В	C	D	

This table specifies the minimum airport model content and functionality to qualify a simulator at the indicated level. This table applies only to the airport models required for simulator qualification; i.e., one airport model for Level A and Level B simulators; three airport models for Level C and Level D simulators.

	Begin QPS Requirements				
1.	Functional test content requirements for Level A and Level B s	imula	tors.		
	The following is the minimum airport model content requirement to				
	capability tests, and provides suitable visual cues to allow completi	on of	all fun	ctions	and
	subjective tests described in this attachment for simulators at Level	s A an	d B.		
1.a.	A minimum of one (1) representative airport model. This model	X	X		
	identification must be acceptable to the sponsor's TPAA,				
	selectable from the IOS, and listed on the SOQ.				
1.b.	The fidelity of the airport model must be sufficient for the	X	X		
	aircrew to visually identify the airport; determine the position of				
	the simulated airplane within a night visual scene; successfully				
	accomplish take-offs, approaches, and landings; and maneuver				
	around the airport on the ground as necessary.				
1.c.	Runways:	X	X		
1.c.1.	Visible runway number.	X	X		
1.c.2.	Runway threshold elevations and locations must be modeled to	X	X		
	provide sufficient correlation with airplane systems (e.g.,				
	altimeter).				
1.c.3.	Runway surface and markings.	X	X		
1.c.4.	Lighting for the runway in use including runway edge and	X	X		
	centerline.				
1.c.5.	Lighting, visual approach aid and approach lighting of	X	X		
	appropriate colors.				
1.c.6.	Representative taxiway lights.	X	X		
2.a.	Additional functional test content requirements				
2.a.1	Airport scenes				
2.a.1.a	A minimum of three (3) real-world airport models to be			X	X
	consistent with published data used for airplane operations and				
	capable of demonstrating all the visual system features below.				
	Each model should be in a different visual scene to permit				
	assessment of FSTD automatic visual scene changes. The model				
	identifications must be acceptable to the sponsor's TPAA,				
	selectable from the IOS, and listed on the SOQ.				
2.a.1.b	Reserved				
2.a.1.c	Reserved				
2.a.1.d	Airport model content.	X	X	X	X
	For circling approaches, all tests apply to the runway used for the				
	initial approach and to the runway of intended landing. If all				
	runways in an airport model used to meet the requirements of this				

	Table A3B - Functions and Subjective Tests									
	QPS REQUIREMENTS									
Entry Number	For Qualification At The Stated Level	Sin	nulat	or Le	vel					
A S	Class I Airport Models									
	attachment are not designated as "in use," then the "in use" runways must be listed on the SOQ (e.g., KORD, Rwys 9R, 14L, 22R). Models of airports with more than one runway must have all significant runways not "in-use" visually depicted for airport and runway recognition purposes. The use of white or off white light strings that identify the runway threshold, edges, and ends for twilight and night scenes are acceptable for this requirement. Rectangular surface depictions are acceptable for daylight scenes. A visual system's capabilities must be balanced between providing airport models with an accurate representation of the airport and a realistic representation of the surrounding environment. Airport model detail must be developed using airport pictures, construction drawings and maps, or other similar data, or developed in accordance with published regulatory material; however, this does not require that such models contain details that are beyond the design capability of the currently qualified visual system. Only one "primary" taxi route from parking to the runway end will be required for each "in-use" runway.									
2.a.2	Visual scene fidelity.									
2.a.2.a	The visual scene must correctly represent the parts of the airport	X	X	X	X					
	and its surroundings used in the training program.									
2.a.2.b	Reserved									
2.a.2.c	Reserved									
2.a.3	Runways and taxiways.									
2.a.3.a	Airport specific runways and taxiways.	X	X	X	X					
2.a.3.b	Reserved									
2.a.3.c	Reserved									
2.a.4	If appropriate to the airport, two parallel runways and one crossing runway displayed simultaneously; at least two runways must be capable of being lit simultaneously.			X	X					
2.a.5	Runway threshold elevations and locations must be modeled to provide correlation with airplane systems (e.g. HUD, GPS, compass, altimeter).			X	X					
2.a.6	Slopes in runways, taxiways, and ramp areas must not cause distracting or unrealistic effects, including pilot eye-point height variation.			X	X					
2.a.7	Runway surface and markings for each "in-use" runway must if appropriate:	includ	e the	follow	ing,					
2.a.7.a	Threshold markings.	X	X	X	X					
2.a.7.b	Runway numbers.	X	X	X	X					
2.a.7.c	Touchdown zone markings.	X	X	X	X					
2.a.7.d	Fixed distance markings.	X	X	X	X					

Class   A   B   C   D	Table A3B - Functions and Subjective Tests								
2.a.7.e Edge markings.		QPS REQUIREMENTS							
2.a.7.e Edge markings.	ntry mber	For Qualification At The Stated Level	Simulator Lev						
2.a.7.f   Center line markings.   X   X   X   X   X   2.a.7.g   Distance remaining signs.   X   X   X   X   X   X   X   2.a.7.h   Signs at intersecting runways and taxiways.   X   X   X   X   X   X   X   X   X	Ξ Š	Class I Airport Models	A	В	С	D			
2.a.7.g   Distance remaining signs.   X   X   X   X   X   2.a.7.h   Signs at intersecting runways and taxiways.   X   X   X   X   X   X   X   X   X	2.a.7.e	Edge markings.	X	X	X	X			
2.a.7.ih Signs at intersecting runways and taxiways. 2.a.7.i Windsock that gives appropriate wind cues. 2.a.8 Runway lighting of appropriate colors, directionality, behavior and spacing for the "in-use" runway including the following: 2.a.8.a Threshold lights. 2.a.8.b Edge lights. 2.a.8.c End lights. 2.a.8.c End lights. 2.a.8.d Center line lights. 2.a.8.d Conter line lights. 2.a.8.d Touchdown zone lights. 2.a.8.d Touchdown zone lights. 2.a.8.d Lead-off lights. 2.a.8.d Appropriate visual landing aid(s) for that runway. 2.a.8.d Appropriate approach lighting system for that runway. 2.a.8.h Appropriate approach lighting system for that runway. 2.a.9. Taxiway surface and markings (associated with each "in-use" runway): 2.a.9.a Edge markings 2.a.9.c Runway holding position markings. 2.a.9.c Runway holding position markings. 2.a.9.e All taxiway markings, lighting, and signage to taxi, as a minimum, from a designated parking position to a designated runway and return, after landing on the designated runway, to a designated parking position; a low visibilities. The designated runway and taxi routing must be consistent with that airport for operations in low visibilities.  The qualification of SMGCS, a demonstrated at one airport model for those operations authorized in low visibilities. The designated runway and taxi routing must be consistent with that airport for operations in low visibilities.  The qualification of SMGCS, a demonstrated at one airport model for those operations authorized in low visibilities.  The qualification of SMGCS, a demonstration model must be provided for evaluation.  2.a.10.a Edge lights.  X X X X X X X X X X X X X X X X X X X	2.a.7.f	Center line markings.	X	X	X	X			
2.a.7.i   Signs at intersecting runways and taxiways.   X   X   X   X   Z.a.7.i   Windsock that gives appropriate wind cues.   X   X   X   X   X   X   X   Z.a.8.a   Runway lighting of appropriate colors, directionality, behavior and spacing for the "in-use" runway including the following:   X   X   X   X   X   X   Z.a.8.a   Edge lights.   X   X   X   X   X   X   Z.a.8.c   End lights.   X   X   X   X   X   X   X   Z.a.8.d   Center line lights.   X   X   X   X   X   X   Z.a.8.d   Center line lights.   X   X   X   X   X   X   Z.a.8.f   Lead-off lights.   X   X   X   X   X   X   Z.a.8.f   Lead-off lights.   X   X   X   X   X   Z.a.8.f   Lead-off lights.   X   X   X   X   X   Z.a.8.f   Appropriate approach lighting system for that runway.   X   X   X   X   X   Z.a.9.a   Edge markings (associated with each "in-use" runway:   Z.a.9   Taxiway surface and markings (associated with each "in-use" runway:   Z.a.9.c   Runway holding position markings.   X   X   X   X   X   Z.a.9.c   Runway holding position markings.   X   X   X   X   X   Z.a.9.e   All taxiway markings, lighting, and signage to taxi, as a minimum, from a designated parking position to a designated runway and return, after landing on the designated runway, to a designated parking position; a low visibilities.   The designated runway and taxi routing must be consistent with that airport for operations in low visibilities.   The designated runway and taxi routing must be consistent with that airport for operations in low visibilities.   The qualification of SMGCS, a demonstration model must be provided for evaluation.   Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):   Z.a.10.a   Edge lights.   X   X   X   X   X   X   X   X   X	2.a.7.g	Distance remaining signs.	X	X	X	X			
2.a.7.i   Windsock that gives appropriate wind cues.   X   X		Signs at intersecting runways and taxiways.	X	X	X	X			
Runway lighting of appropriate colors, directionality, behavior and spacing for the "in-use" runway including the following:   2.a.8.a	2.a.7.i				X	X			
2.a.8.a   Threshold lights.   X	2.a.8	Runway lighting of appropriate colors, directionality, behavior	and s	pacing	g for t	he			
2.a.8.b   Edge lights.	2.a.8.a		X	X	X	X			
2.a.8.c   End lights.			X	X					
2.a.8.d   Center line lights.	2.a.8.c		X	X	X	X			
2.a.8.e   Touchdown zone lights.			X						
2.a.8.f   Lead-off lights.									
2.a.8.h Appropriate approach lighting system for that runway.  2.a.9 Taxiway surface and markings (associated with each "in-use" runway):  2.a.9.a Edge markings  2.a.9.b Center line markings.  2.a.9.c Runway holding position markings.  2.a.9.d ILS critical area markings.  2.a.9.e All taxiway markings, lighting, and signage to taxi, as a minimum, from a designated parking position to a designated runway and return, after landing on the designated runway, to a designated parking position; a low visibility taxi route (e.g. surface movement guidance control system, follow-me truck, daylight taxi lights) must also be demonstrated at one airport model for those operations authorized in low visibilities. The designated runway and taxi routing must be consistent with that airport for operations in low visibilities.  The qualification of surface movement guidance control systems (SMGCS) is optional at the request of the FSTD sponsor. For the qualification of SMGCS, a demonstration model must be provided for evaluation.  2.a.10 Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a Edge lights.  2.a.10.b Center line lights.  X X X X X X X X X X X X X X X X X X X	2.a.8.f		X	X	X	X			
2.a.8.h Appropriate approach lighting system for that runway.  2.a.9 Taxiway surface and markings (associated with each "in-use" runway):  2.a.9.a Edge markings  2.a.9.b Center line markings.  2.a.9.c Runway holding position markings.  2.a.9.d ILS critical area markings.  2.a.9.e All taxiway markings, lighting, and signage to taxi, as a minimum, from a designated parking position to a designated runway and return, after landing on the designated runway, to a designated parking position; a low visibility taxi route (e.g. surface movement guidance control system, follow-me truck, daylight taxi lights) must also be demonstrated at one airport model for those operations authorized in low visibilities. The designated runway and taxi routing must be consistent with that airport for operations in low visibilities.  The qualification of surface movement guidance control systems (SMGCS) is optional at the request of the FSTD sponsor. For the qualification of SMGCS, a demonstration model must be provided for evaluation.  2.a.10 Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a Edge lights.  2.a.10.b Center line lights.  X X X X X X X X X X X X X X X X X X X	2.a.8.g	Appropriate visual landing aid(s) for that runway.	X	X	X	X			
2.a.9.a Edge markings  2.a.9.b Center line markings.  2.a.9.c Runway holding position markings.  2.a.9.d ILS critical area markings.  2.a.9.e All taxiway markings, lighting, and signage to taxi, as a minimum, from a designated parking position to a designated runway and return, after landing on the designated runway, to a designated parking position; a low visibility taxi route (e.g. surface movement guidance control system, follow-me truck, daylight taxi lights) must also be demonstrated at one airport model for those operations authorized in low visibilities. The designated runway and taxi routing must be consistent with that airport for operations in low visibilities.  The qualification of surface movement guidance control systems (SMGCS) is optional at the request of the FSTD sponsor. For the qualification of SMGCS, a demonstration model must be provided for evaluation.  2.a.10  Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a Edge lights.  2.a.10.b Center line lights.  2.a.11.c Required visual model correlation with other aspects of the airport environment simulation.  2.a.11.a The airport model must be properly aligned with the navigational X X X X X				X					
2.a.9.b Center line markings.  2.a.9.c Runway holding position markings.  2.a.9.d ILS critical area markings.  3.	2.a.9	Taxiway surface and markings (associated with each "in-use" r	unwa	y):		•			
2.a.9.c Runway holding position markings.  2.a.9.d ILS critical area markings.  2.a.9.e All taxiway markings, lighting, and signage to taxi, as a minimum, from a designated parking position to a designated runway and return, after landing on the designated runway, to a designated parking position; a low visibility taxi route (e.g. surface movement guidance control system, follow-me truck, daylight taxi lights) must also be demonstrated at one airport model for those operations authorized in low visibilities. The designated runway and taxi routing must be consistent with that airport for operations in low visibilities.  The qualification of surface movement guidance control systems (SMGCS) is optional at the request of the FSTD sponsor. For the qualification of SMGCS, a demonstration model must be provided for evaluation.  2.a.10  Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a Edge lights.  2.a.10.b Center line lights.  2.a.10.c Runway holding position and ILS critical area lights.  2.a.11  Required visual model correlation with other aspects of the airport environment simulation.  The airport model must be properly aligned with the navigational  X X X X	2.a.9.a				X	X			
2.a.9.c Runway holding position markings.  2.a.9.d ILS critical area markings.  2.a.9.e All taxiway markings, lighting, and signage to taxi, as a minimum, from a designated parking position to a designated runway and return, after landing on the designated runway, to a designated parking position; a low visibility taxi route (e.g. surface movement guidance control system, follow-me truck, daylight taxi lights) must also be demonstrated at one airport model for those operations authorized in low visibilities. The designated runway and taxi routing must be consistent with that airport for operations in low visibilities.  The qualification of surface movement guidance control systems (SMGCS) is optional at the request of the FSTD sponsor. For the qualification of SMGCS, a demonstration model must be provided for evaluation.  2.a.10  Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a Edge lights.  2.a.10.b Center line lights.  2.a.10.c Runway holding position and ILS critical area lights.  2.a.11  Required visual model correlation with other aspects of the airport environment simulation.  2.a.11.a The airport model must be properly aligned with the navigational X X X X	2.a.9.b	Center line markings.	X	X	X	X			
2.a.9.e All taxiway markings, lighting, and signage to taxi, as a minimum, from a designated parking position to a designated runway and return, after landing on the designated runway, to a designated parking position; a low visibility taxi route (e.g. surface movement guidance control system, follow-me truck, daylight taxi lights) must also be demonstrated at one airport model for those operations authorized in low visibilities. The designated runway and taxi routing must be consistent with that airport for operations in low visibilities.  The qualification of surface movement guidance control systems (SMGCS) is optional at the request of the FSTD sponsor. For the qualification of SMGCS, a demonstration model must be provided for evaluation.  2.a.10  Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a Edge lights.  X X X X X X X X X X X X X X X X X X X	2.a.9.c		X	X	X	X			
minimum, from a designated parking position to a designated runway and return, after landing on the designated runway, to a designated parking position; a low visibility taxi route (e.g. surface movement guidance control system, follow-me truck, daylight taxi lights) must also be demonstrated at one airport model for those operations authorized in low visibilities. The designated runway and taxi routing must be consistent with that airport for operations in low visibilities.  The qualification of surface movement guidance control systems (SMGCS) is optional at the request of the FSTD sponsor. For the qualification of SMGCS, a demonstration model must be provided for evaluation.  2.a.10  Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a Edge lights. X X X X X X X X 2.a.10.b Center line lights. X X X X X X X X X 2.a.10.c Runway holding position and ILS critical area lights. X X X X X X X X X X X X X X X X X X X	2.a.9.d	ILS critical area markings.	X	X	X	X			
minimum, from a designated parking position to a designated runway and return, after landing on the designated runway, to a designated parking position; a low visibility taxi route (e.g. surface movement guidance control system, follow-me truck, daylight taxi lights) must also be demonstrated at one airport model for those operations authorized in low visibilities. The designated runway and taxi routing must be consistent with that airport for operations in low visibilities.  The qualification of surface movement guidance control systems (SMGCS) is optional at the request of the FSTD sponsor. For the qualification of SMGCS, a demonstration model must be provided for evaluation.  2.a.10  Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a Edge lights. X X X X X X X X 2.a.10.b Center line lights. X X X X X X X X X 2.a.10.c Runway holding position and ILS critical area lights. X X X X X X X X X X X X X X X X X X X	2.a.9.e	All taxiway markings, lighting, and signage to taxi, as a				X			
designated parking position; a low visibility taxi route (e.g. surface movement guidance control system, follow-me truck, daylight taxi lights) must also be demonstrated at one airport model for those operations authorized in low visibilities. The designated runway and taxi routing must be consistent with that airport for operations in low visibilities.  The qualification of surface movement guidance control systems (SMGCS) is optional at the request of the FSTD sponsor. For the qualification of SMGCS, a demonstration model must be provided for evaluation.  2.a.10  Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a Edge lights.  X X X X X X 2.a.10.b Center line lights.  X X X X X X X X 2.a.10.c Runway holding position and ILS critical area lights.  X X X X X X X X X X X X X X X X X X X									
surface movement guidance control system, follow-me truck, daylight taxi lights) must also be demonstrated at one airport model for those operations authorized in low visibilities. The designated runway and taxi routing must be consistent with that airport for operations in low visibilities.  The qualification of surface movement guidance control systems (SMGCS) is optional at the request of the FSTD sponsor. For the qualification of SMGCS, a demonstration model must be provided for evaluation.  2.a.10  Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a Edge lights.  X X X X X X 2.a.10.b Center line lights.  X X X X X X X 2.a.10.c Runway holding position and ILS critical area lights.  X X X X X X X 2.a.11  Required visual model correlation with other aspects of the airport environment simulation.  2.a.11.a The airport model must be properly aligned with the navigational X X X X X		runway and return, after landing on the designated runway, to a							
daylight taxi lights) must also be demonstrated at one airport model for those operations authorized in low visibilities. The designated runway and taxi routing must be consistent with that airport for operations in low visibilities.  The qualification of surface movement guidance control systems (SMGCS) is optional at the request of the FSTD sponsor. For the qualification of SMGCS, a demonstration model must be provided for evaluation.  2.a.10  Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a Edge lights.  X X X X X X X X X X X X X X X X X X X		designated parking position; a low visibility taxi route (e.g.							
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designated runway and taxi routing must be consistent with that airport for operations in low visibilities.  The qualification of surface movement guidance control systems (SMGCS) is optional at the request of the FSTD sponsor. For the qualification of SMGCS, a demonstration model must be provided for evaluation.  2.a.10  Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a Edge lights.  X X X X X X X X X X X X X X X X X X X		daylight taxi lights) must also be demonstrated at one airport							
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The qualification of surface movement guidance control systems (SMGCS) is optional at the request of the FSTD sponsor. For the qualification of SMGCS, a demonstration model must be provided for evaluation.  2.a.10  Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a  Edge lights.  X X X X X X X X X X X X X X X X X X X		designated runway and taxi routing must be consistent with that							
(SMGCS) is optional at the request of the FSTD sponsor. For the qualification of SMGCS, a demonstration model must be provided for evaluation.  2.a.10 Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a Edge lights. X X X X X X X X X X X X X X X X X X X		airport for operations in low visibilities.							
qualification of SMGCS, a demonstration model must be provided for evaluation.  2.a.10  Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a  Edge lights.  X X X X X X X X X X X X X X X X X X X									
provided for evaluation.  2.a.10 Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a Edge lights. X X X X  2.a.10.b Center line lights. X X X X  2.a.10.c Runway holding position and ILS critical area lights. X X X X  2.a.11 Required visual model correlation with other aspects of the airport environment simulation.  2.a.11.a The airport model must be properly aligned with the navigational X X X X									
2.a.10 Taxiway lighting of appropriate colors, directionality, behavior and spacing (associated with each "in-use" runway):  2.a.10.a Edge lights. X X X X X X X X X X X X X X X X X X X									
(associated with each "in-use" runway):  2.a.10.a Edge lights. X X X X  2.a.10.b Center line lights. X X X X  2.a.10.c Runway holding position and ILS critical area lights. X X X X  2.a.11 Required visual model correlation with other aspects of the airport environment simulation.  2.a.11.a The airport model must be properly aligned with the navigational X X X X									
2.a.10.a       Edge lights.       X	2.a.10		and s	pacin	g				
2.a.10.b       Center line lights.       X			1	1	ı	1			
2.a.10.c Runway holding position and ILS critical area lights. X X X X  2.a.11 Required visual model correlation with other aspects of the airport environment simulation.  2.a.11.a The airport model must be properly aligned with the navigational X X X X		Ü Ü							
2.a.11 Required visual model correlation with other aspects of the airport environment simulation.  2.a.11.a The airport model must be properly aligned with the navigational X X X X									
simulation.  2.a.11.a The airport model must be properly aligned with the navigational X X X X									
2.a.11.a The airport model must be properly aligned with the navigational X X X X	2.a.11		port e	nviror	ıment				
	2.a.11.a		X	X	X	X			

	Table A3B - Functions and Subjective Tests				
	QPS REQUIREMENTS				
Entry Number	For Qualification At The Stated Level	Siı	nulat	or Le	vel
E Z	Class I Airport Models	A	В	C	D
2.a.11.b	The simulation of runway contaminants must be correlated with the displayed runway surface and lighting.				X
2.a.12	Airport buildings, structures and lighting.		<u> </u>		
2.a.12.a	Buildings, structures and lighting:				
2.a.12.a.1	Airport specific buildings, structures and lighting.			X	X
2.a.12.a.2	Reserved			21	21
2.a.12.a.3	Reserved				
2.a.12.b	At least one useable gate, set at the appropriate height (required only for those airplanes that typically operate from terminal gates).			X	X
2.a.12.c	Representative moving and static airport clutter (e.g. other airplanes, power carts, tugs, fuel trucks, additional gates).			X	X
2.a.12.d	Gate/apron markings (e.g. hazard markings, lead-in lines, gate numbering), lighting and gate docking aids or a marshaller.	X		X	
2.a.13	Terrain and obstacles.				
2.a.13.a	Terrain and obstacles within 46 km (25 NM) of the reference airport.			X	X
2.a.13.b	Reserved				
2.a.14	Significant, identifiable natural and cultural features and movin	ng air	horne	traffi	<u>.                                    </u>
2.a.14.a	Significant, identifiable natural and cultural features within 46			X	X
2	km (25 NM) of the reference airport.				
	Note.— This refers to natural and cultural features that are				
	typically used for pilot orientation in flight. Outlying airports not intended for landing need only provide a reasonable facsimile of				
2 117	runway orientation.				
2.a.14.b	Reserved			<b>T</b> 7	<b>T</b> 7
2.a.14.c	Representative moving airborne traffic (including the capability to present air hazards – e.g. airborne traffic on a possible collision course).			X	X
2.b	Visual scene management.				
2.b.1	All airport runway, approach and taxiway lighting and cultural lighting intensity for any approach must be capable of being set to six (6) different intensities (0 to 5); all visual scene light points should fade into view appropriately.			X	X
2.b.2	Airport runway, approach and taxiway lighting and cultural lighting intensity for any approach must be set at an intensity representative of that used in training for the visibility set; all visual scene light points should fade into view appropriately.	X	X		
2.b.3 2.c	X	X	X	X	
<b>4.</b> C	Visual feature recognition.				

	Table A3B - Functions and Subjective Tests			Table A3B - Functions and Subjective Tests								
	QPS REQUIREMENTS											
Entry Number	For Qualification At The Stated Level	Simulator Level										
E S	Class I Airport Models	A	В	С	D							
	Note.— The following are the minimum distances at which runway visible. Distances are measured from runway threshold to an airple runway on an extended 3-degree glide slope in suitable simulated n conditions. For circling approaches, all tests below apply both to the initial approach and to the runway of intended landing.	ne ali neteor	gned v ologic	with th al	ne .							
2.c.1	Runway definition, strobe lights, approach lights, and runway edge white lights from 8 km (5 sm) of the runway threshold.	X	X	X	X							
2.c.2	Visual approach aids lights.											
2.c.2.a	Visual approach aids lights from 8 km (5 sm) of the runway threshold.			X	X							
2.c.2.b	Visual approach aids lights from 4.8 km (3 sm) of the runway threshold.	X	X									
2.c.3	Runway center line lights and taxiway definition from 4.8 km (3 sm).	X	X	X	X							
2.c.4	Threshold lights and touchdown zone lights from 3.2 km (2 sm).	X	X	X	X							
2.c.5	Runway markings within range of landing lights for night scenes; as required by the surface resolution test on day scenes.	X	X	X	X							
2.c.6	For circling approaches, the runway of intended landing and associated lighting must fade into view in a non-distracting manner.	X	X	X	X							
2.d	Selectable airport visual scene capability for:		·		•							
2.d.1	Night.	X	X	X	X							
2.d.2	Twilight.			X	X							
2.d.3	Day.			X	X							
2.d.4	Dynamic effects — the capability to present multiple ground and air hazards such as another airplane crossing the active runway or converging airborne traffic; hazards should be selectable via controls at the instructor station.			X	X							
2.d.5 2.e	Illusions — operational visual scenes which portray representative physical relationships known to cause landing illusions, for example short runways, landing approaches over water, uphill or downhill runways, rising terrain on the approach path and unique topographic features.  Note.— Illusions may be demonstrated at a generic airport or at a specific airport.  Correlation with airplane and associated equipment.				X							
2.e.1	Visual cues to relate to actual airplane responses.	X	X	X	X							
2.e.2	Visual cues during take-off, approach and landing.				1							
2.e.2.a	Visual cues to assess sink rate and depth perception during landings.		X	X	X							
2.e.2.b	Visual cueing sufficient to support changes in approach path by using runway perspective. Changes in visual cues during take-off, approach and landing should not distract the pilot.	X	X	X	X							

	Table A3B - Functions and Subjective Tests						
	QPS REQUIREMENTS	1					
Entry Number	For Qualification At The Stated Level	Sir	nulat	or Le	vel		
Ξ N	Class I Airport Models						
2.e.3	Accurate portrayal of environment relating to airplane attitudes.	X	X	X	X		
2.e.4	The visual scene must correlate with integrated airplane systems, where fitted (e.g. terrain, traffic and weather avoidance systems and HUD/EFVS).			X	X		
2.e.5	The effect of rain removal devices must be provided.			X	X		
2.f	Scene quality.						
2.f.1	Quantization.						
2.f.1.a	Surfaces and textural cues must be free from apparent quantization (aliasing).			X	X		
2.f.1.b	Surfaces and textural cues must not create distracting quantization (aliasing).	X	X				
2.f.2	System capable of portraying full color realistic textural cues.			X	X		
2.f.3	The system light points must be free from distracting jitter,	X	X	X	X		
	smearing or streaking.						
2.f.4	System capable of providing representative focus effects that simulate rain (e.g. reduced visibility and object resolution in the out the window view as a result of rain).			X	X		
2.f.5	System capable of providing light point perspective growth (e.g. relative size of runway and taxiway edge lights increase as the lights are approached).			X	X		
2.g	Environmental effects.	•	•				
2.g.1	The displayed scene must correspond to the appropriate surface contaminants and include runway lighting reflections for wet, partially obscured lights for snow, or suitable alternative effects.			X	X		
2.g.2	Special weather representations which include the sound, motion and visual effects of light, medium and heavy precipitation near a thunderstorm on take-off, approach and landings at and below an altitude of 600 m (2 000 ft) above the airport surface and within a radius of 16 km (10 sm) from the airport.			X	X		
2.g.3	One airport with a snow scene to include terrain snow and snow-covered taxiways and runways.			X	X		
2.g.4	In-cloud effects such as variable cloud density, speed cues and ambient changes should be provided.			X	X		
2.g.5	The effect of multiple cloud layers representing few, scattered, broken and overcast conditions giving partial or complete obstruction of the ground scene.			X	X		
2.g.6	Gradual break-out to ambient visibility/RVR, defined as up to 10% of the respective cloud base or top, 20 ft ≤ transition layer ≤ 200 ft; cloud effects should be checked at and below a height of 600 m (2 000 ft) above the airport and within a radius of 16 km (10 sm) from the airport. Transition effects should be complete when the IOS cloud base or top is reached when exiting and start when entering the cloud, i.e. transition effects should occur			X	X		

	Table A3B - Functions and Subjective Tests					
	QPS REQUIREMENTS					
Entry Number	For Qualification At The Stated Level	Siı	nulat	or Le	vel	
	within the IOS defined cloud layer.					
2.g.7	Visibility and RVR measured in terms of distance. Visibility/RVR must be checked at and below a height of 600 m (2 000 ft) above the airport and within a radius of 16 km (10 sm) from the airport.	X	X	X	X	
2.g.8	Patchy fog (sometimes referred to as patchy RVR) giving the effect of variable RVR. The lowest RVR should be that selected on the IOS, ie. variability is only greater than the IOS RVR.			X	X	
2.g.9	Effects of fog on airport lighting such as halos and defocus.			X	X	
2.g.10	Effect of ownship lighting in reduced visibility, such as reflected glare, to include landing lights, strobes, and beacons.			X	X	
2.g.11	Wind cues to provide the effect of blowing snow or sand across a dry runway or taxiway should be selectable from the instructor station.			X	X	
	End QPS Requirement					
	Begin Information					
3.	An example of being able to "combine two airport models to achieve two "in-use" runways:  One runway designated as the "in use" runway in the first model of the airport, and the second runway designated as the "in use" runway in the second model of the same airport. For example, the clearance is for the ILS approach to Runway 27, Circle to Land on Runway 18 right. Two airport visual models might be used: the first with Runway 27 designated as the "in use" runway for the approach to runway 27, and the second with Runway 18 Right designated as the "in use" runway. When the pilot breaks off the ILS approach to runway 27, the instructor may change to the second airport visual model in which runway 18 Right is designated as the "in use" runway, and the pilot would make a visual approach and landing. This process is acceptable to the FAA as long as the temporary interruption due to the visual model change is not distracting to the pilot, does not cause changes in navigational radio frequencies, and does not cause undue instructor/evaluator time.					
4.	Sponsors are not required to provide every detail of a runway, but the detail that is provided should be correct within the capabilities of the system.  End Information					
L	AMV AMVI HIMIVI		l	1		

	Table A3D - Functions and Subjection	ctive	Tests	3		
	QPS REQUIREMENTS					INFORMATION
ry lber		Sin	nulat	or Le	vel	
Entry Number	Motion System Effects	A	В	C	D	Notes
or situat	le specifies motion effects that are required to indicate when a flightion. Where applicable, flight simulator pitch, side loading and direstative of the airplane.					
1.	Taxiing effects such as lateral, longitudinal, and directional cues resulting from steering and braking inputs. Runway contamination with associated anti-skid and taxiway characteristics.			X	X	
2.	Runway rumble, oleo deflection, ground speed, uneven runway, runway/taxiway centerline light characteristics:  Procedure: After the airplane has been pre-set to the takeoff position and then released, taxi at various speeds with a smooth runway and note the general characteristics of the simulated runway rumble effects of oleo deflections. Repeat the maneuver with a runway roughness of 50%, then with maximum roughness. Note the associated motion vibrations affected by ground speed and runway roughness.		X	X	X	Different gross weights can also be selected, which may also affect the associated vibrations depending on airplane type. The associated motion effects for the above tests should also include an assessment of the effects of rolling over centerline lights, surface discontinuities of uneven runways, and various taxiway characteristics.
3.	Buffets on the ground due to spoiler/speedbrake extension and reverse thrust:  Procedure: Perform a normal landing and use ground spoilers	X	X	X	X	
	and reverse thrust – either individually or in combination – to					

	Table A3D - Functions and Subjective Tests						
	QPS REQUIREMENTS					INFORMATION	
<u> </u>		Siı	nulat	or Le	vel		
Entry Number	Motion System Effects	A	В	C	D	Notes	
	decelerate the simulated airplane. Do not use wheel braking so that only the buffet due to the ground spoilers and thrust reversers is felt.						
4.	Bumps associated with the landing gear:	X	X	X	X		
	Procedure: Perform a normal take-off paying special attention to the bumps that could be perceptible due to maximum oleo extension after lift-off. When the landing gear is extended or retracted, motion bumps can be felt when the gear locks into position.						
5.	Buffet during extension and retraction of landing gear:	X	X	X	X		
	Procedure: Operate the landing gear. Check that the motion cues of the buffet experienced represent the actual airplane.						
6.	Buffet in the air due to flap and spoiler/speedbrake extension:  Procedure: Perform an approach and extend the flaps and slats with airspeeds deliberately in excess of the normal approach speeds. In cruise configuration, verify the buffets associated with the spoiler/speedbrake extension. The above effects can also be verified with different combinations of spoiler/speedbrake, flap, and landing gear settings to assess the	X	X	X	X		
	interaction effects.						

	Table A3D - Functions and Subjective Tests							
	QPS REQUIREMENTS					INFORMATION		
<u> </u>		Sir	nulat	or Le	vel			
Entry Number	Motion System Effects	A	В	C	D	Notes		
7.	<b>Buffet due to atmospheric disturbances</b> (e.g. buffet due to turbulence, windshear, proximity to thunderstorms, gusting winds, etc.).			X	X			
8.	Approach to stall buffet and stall buffet (where applicable):  Procedure: Conduct an approach-to-stall with engines at idle and a deceleration of 1 knot/second. Check that the motion cues of the buffet, including the level of buffet increase with decreasing speed, are representative of the actual airplane.	X	X	X	X	For FSTDs qualified for full stall training tasks, modeling that accounts for any increase in buffet amplitude from initial buffet threshold of perception to critical angle of attack or deterrent buffet as a function of angle of attack. The stall buffet modeling should include effects of Nz, as well as Nx and Ny if relevant.		
9.	Touchdown cues for main and nose gear:  Procedure: Conduct several normal approaches with various rates of descent. Check that the motion cues for the touchdown bumps for each descent rate are representative of the actual airplane.	X	X	X	X			
10.	Nosewheel scuffing:  Procedure: Taxi at various ground speeds and manipulate the nosewheel steering to cause yaw rates to develop that cause the		X	X	X			

	Table A3D - Functions and Subje	ective	Tests	S		
	QPS REQUIREMENTS					INFORMATION
Entry Number	Motion System Effects	Sin	nulat B	cor Le	vel D	Notes
11.	nosewheel to vibrate against the ground ("scuffing"). Evaluate the speed/nosewheel combination needed to produce scuffing and check that the resultant vibrations are representative of the actual airplane.  Thrust effect with brakes set:	X	X	X	X	This effect is most discernible with wing-mounted engines.
	Procedure: Set the brakes on at the take-off point and increase the engine power until buffet is experienced. Evaluate its characteristics. Confirm that the buffet increases appropriately with increasing engine thrust.					
12.	Mach and maneuver buffet:  Procedure: With the simulated airplane trimmed in 1 g flight while at high altitude, increase the engine power so that the Mach number exceeds the documented value at which Mach buffet is experienced. Check that the buffet begins at the same Mach number as it does in the airplane (for the same configuration) and that buffet levels are representative of the actual airplane. For certain airplanes, maneuver buffet can also be verified for the same effects. Maneuver buffet can occur during turning flight at conditions greater than 1 g, particularly at higher altitudes.		X	X	X	
13.	Tire failure dynamics:			X	X	The pilot may notice some yawing with a multiple tire

	Table A3D - Functions and Subjective Tests						
	QPS REQUIREMENTS					INFORMATION	
ı		Sir	nulat	or Le	vel		
Entry Number	Motion System Effects	A	В	C	D	Notes	
	Procedure: Simulate a single tire failure and a multiple tire failure.					failure selected on the same side. This should require the use of the rudder to maintain control of the airplane.  Dependent on airplane type, a single tire failure may not be noticed by the pilot and should not have any special motion effect. Sound or vibration may be associated with the actual tire losing pressure.	
14.	Engine failures, malfunction, engine, and airframe structural damage:  Procedure: The characteristics of an engine malfunction as stipulated in the malfunction definition document for the particular flight simulator must describe the special motion effects felt by the pilot. Note the associated engine instruments varying according to the nature of the malfunction and note the replication of the effects of the airframe vibration.		X	X	X		
15.	Tail strikes, engine pod/propeller, wing strikes:  Procedure: Tail-strikes can be checked by over-rotation of the airplane at a speed below $V_r$ while performing a takeoff. The		X	X	X	The motion effect should be felt as a noticeable bump. If the tail strike affects the airplane angular rates, the	

Table A3D - Functions and Subjective Tests						
QPS REQUIREMENTS				INFORMATION		
• .			nulat	or Le	vel	
Entry Number	Motion System Effects	A	В	C	D	Notes
	effects can also be verified during a landing.  Excessive banking of the airplane during its take-off/landing roll can cause a pod strike.					cueing provided by the motion system should have an associated effect.

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Table A3F - Functions and Subjective Tests									
	QPS REQUIREMENTS								
Entry Number	Special Effects	S	imulat	or Level					
		A	В	C	D				
Th	is table specifies the minimum special effects necessary for the specified	d simu	ılator l	level.					
1.	Braking Dynamics: Representations of the dynamics of brake failure (flight simulator pitch, side-loading, and directional control characteristics representative of the airplane), including antiskid and decreased brake efficiency due to high brake temperatures (based on airplane related data), sufficient to enable pilot identification of the problem and implementation of appropriate procedures.			X	X				
2.	Required only for those airplanes authorized for operations in known icing conditions.  Procedure: With the simulator airborne, autopilot on and autothrottles off, engine and airfoil anti-ice/de-ice systems deactivated; activate icing conditions at a rate that allows monitoring of simulator and systems response. Icing recognition will typically include airspeed decay, change in simulator pitch attitude, change in engine performance indications (other than due to airspeed changes), and change in data from pitot/static system. Activate heating, anti-ice, or de-ice systems independently. Recognition will include proper effects of these systems, eventually returning the simulated airplane to normal flight. See Table A1A, section 2.j. and Attachment 7 for			X	X				

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3. Correct the tables appearing on pages 18308-18326 to read as follows:

	Table B1A – Minimum FTD Requirements		INFODMATION			
	QPS REQUIREMENTS	ETD				INFORMATION
Entry Number	General FTD Requirements		FTD Level 4 5 6 7			Notes
1. Genera	l Flight deck Configuration.	7		U	'	<u> </u>
1. Genera 1.a.	The FTD must have a flight deck that is a replica of the airplane simulated with controls, equipment, observable flight deck indicators, circuit breakers, and bulkheads properly located, functionally accurate and replicating the airplane. The direction of movement of controls and switches must be identical to that in the airplane. Pilot seat(s) must afford the capability for the occupant to be able to achieve the design "eye position." Equipment for the operation of the flight deck windows must be included, but the actual windows need not be operable. Fire axes, extinguishers, and spare light bulbs must be available in the flight FTD, but may be relocated to a suitable location as near as practical to the original position. Fire axes, landing gear pins, and any similar purpose instruments need only be represented in silhouette.  The use of electronically displayed images with physical overlay or masking for FTD instruments and/or instrument panel layouts are dimensionally correct with differences, if any, being imperceptible to the pilot;  (2) Instruments replicate those of the airplane including full instrument functionality and embedded logic;  (3) Instruments displayed are free of quantization (stepping);  (4) Instrument display characteristics replicate those of the airplane including: resolution, colors, luminance, brightness, fonts, fill patterns, line styles and symbology;  (5) Overlay or masking, including bezels and bugs, as applicable, replicates the airplane panel(s);			X	X	For FTD purposes, the flight deck consists of all that space forward of a cross section of the fuselage at the most extreme aft setting of the pilots' seats including additional, required flight crewmember duty stations and those required bulkheads aft of the pilot seats. For clarification, bulkheads containing only items such as landing gear pin storage compartments, fire axes and extinguishers, spare light bulbs, aircraft documents pouches are not considered essential and may be omitted.  For Level 6 FTDs, flight deck window panes may be omitted where non-distracting and subjectively acceptable to conduct qualified training tasks.

	OPS REQUIREMENTS						INFORMATION
Entry			FTD				
Number	General FTD Requirements			vel			Notes
1 (dillioe)		4	5	6	7		
	(6) Instrument controls and switches replicate and operate with the same						
	technique, effort, travel and in the same direction as those in the						
	airplane;						
	(7) Instrument lighting replicates that of the airplane and is operated from						
	the FSTD control for that lighting and, if applicable, is at a level						
	commensurate with other lighting operated by that same control; and						
	(8) As applicable, instruments must have faceplates that replicate those in						
	the airplane; and						
	Level 7 FTD only;						
	The display image of any three dimensional instrument, such as an electro- mechanical instrument, should appear to have the same three dimensional						
	depth as the replicated instrument. The appearance of the simulated						
	instrument, when viewed from the principle operator's angle, should replicate						
	that of the actual airplane instrument. Any instrument reading inaccuracy due						
	to viewing angle and parallax present in the actual airplane instrument should						
	be duplicated in the simulated instrument display image. Viewing angle error						
	and parallax must be minimized on shared instruments such and engine						
	displays and standby indicators.						
.b.	The FTD must have equipment (e.g., instruments, panels, systems, circuit	X	X				
	breakers, and controls) simulated sufficiently for the authorized						
	training/checking events to be accomplished. The installed equipment must						
	be located in a spatially correct location and may be in a flight deck or an						
	open flight deck area. Additional equipment required for the authorized						
	training/checking events must be available in the FTD, but may be located in						
	a suitable location as near as practical to the spatially correct position.						

	Table B1A – Minimum FTD Requirements					
	QPS REQUIREMENTS					
Entry Number	General FTD Requirements	FTD Level				Notes
Number		4	5	6	7	
	Actuation of equipment must replicate the appropriate function in the					
	airplane. Fire axes, landing gear pins, and any similar purpose instruments need only be represented in silhouette.					
1.c.	Those circuit breakers that affect procedures or result in observable flight deck indications must be properly located and functionally accurate.				X	
2. Progra						1
2.a.1	The FTD must provide the proper effect of aerodynamic changes for the combinations of drag and thrust normally encountered in flight. This must include the effect of change in airplane attitude, thrust, drag, altitude, temperature, and configuration.  Level 6 additionally requires the effects of changes in gross weight and center of gravity.  Level 5 requires only generic aerodynamic programming.		X	X		
	An SOC is required.					
2.a.2	A flight dynamics model that accounts for various combinations of drag and thrust normally encountered in flight must correspond to actual flight conditions, including the effect of change in airplane attitude, thrust, drag, altitude, temperature, gross weight, moments of inertia, center of gravity location, and configuration.  The effects of pitch attitude and of fuel slosh on the aircraft center of gravity must be simulated.				X	
	An SOC is required.					
2.b.	The FTD must have the computer capacity, accuracy, resolution, and dynamic	X	X	X	X	

	Table B1A – Minimum FTD Requirements								
	QPS REQUIREMENTS					INFORMATION			
Entry		Level							
Number	General FTD Requirements								Notes
1 (44212 02		4	5	6	7				
	response needed to meet the qualification level sought.								
	An SOC is required.								
2.c.1	Relative responses of the flight deck instruments must be measured by		X	X		The intent is to verify that the			
2.6.1	latency tests, or transport delay tests, and may not exceed 300 milliseconds.		1	11		FTD provides instrument cues			
	The instruments must respond to abrupt input at the pilot's position within the					that are, within the stated time			
	allotted time, but not before the time when the airplane responds under the					delays, like the airplane			
	same conditions.					responses. For airplane			
	(1) Latency: The FTD instrument and, if applicable, the motion system					response, acceleration in the			
	and the visual system response must not be prior to that time when the					appropriate, corresponding			
	airplane responds and may respond up to 300 milliseconds after that					rotational axis is preferred.			
	time under the same conditions.					Additional information			
	(2) Transport Delay: As an alternative to the Latency requirement, a					regarding Latency and			
	transport delay objective test may be used to demonstrate that the FTD					Transport Delay testing may			
	system does not exceed the specified limit. The sponsor must measure					be found in Appendix A,			
	all the delay encountered by a step signal migrating from the pilot's					Attachment 2, paragraph 15.			
	control through all the simulation software modules in the correct								
	order, using a handshaking protocol, finally through the normal output								
	interfaces to the instrument display and, if applicable, the motion								
	system, and the visual system.								
2.c.2.	Relative responses of the motion system, visual system, and flight deck				X	The intent is to verify that the			
	instruments, measured by latency tests or transport delay tests. Motion onset					FTD provides instrument,			
	should occur before the start of the visual scene change (the start of the scan					motion, and visual cues that			
	of the first video field containing different information) but must occur before					are, within the stated time			
	the end of the scan of that video field. Instrument response may not occur					delays, like the airplane			
	prior to motion onset. Test results must be within the following limits:					responses. For airplane			

	Table B1A – Minimum FTD Requirements					
	QPS REQUIREMENTS					INFORMATION
Entry Number	General FTD Requirements	FTD Level 4 5 6 7				Notes
2.d.	100 ms for the motion (if installed) and instrument systems; and 120 ms for the visual system.  Ground handling and aerodynamic programming must include the following:					response, acceleration in the appropriate, corresponding rotational axis is preferred.
2.d.1.	Ground effect.				X	Ground effect includes modeling that accounts for roundout, flare, touchdown, lift, drag, pitching moment, trim, and power while in ground effect.
2.d.2.	Ground reaction.				X	Ground reaction includes modeling that accounts for strut deflections, tire friction, and side forces. This is the reaction of the airplane upon contact with the runway during landing, and may differ with changes in factors such as gross weight, airspeed, or rate of descent on touchdown.
2.d.3.	Ground handling characteristics, including aerodynamic and ground reaction modeling including steering inputs, operations with crosswind, gusting crosswind, braking, thrust reversing, deceleration, and turning radius.				X	
2.e.	If the aircraft being simulated is one of the aircraft listed in § 121.358, Lowaltitude windshear system equipment requirements, the FTD must employ				X	Windshear models may consist of independent variable winds

	Table B1A – Minimum FTD Requirements					
	QPS REQUIREMENTS					INFORMATION
Entry Number	General FTD Requirements	FTD Level				Notes
		4	5	6	7	
	windshear models that provide training for recognition of windshear					in multiple simultaneous
	phenomena and the execution of recovery procedures. Models must be					components. The FAA
	available to the instructor/evaluator for the following critical phases of flight:					Windshear Training Aid
	(1) Prior to takeoff rotation;					presents one acceptable means
	(2) At liftoff;					of compliance with FTD wind
	(3) During initial climb; and					model requirements.
	(4) On final approach, below 500 ft AGL.					
	The QTG must reference the FAA Windshear Training Aid or present					The FTD should employ a
	alternate airplane related data, including the implementation method(s) used.					method to ensure the required
	If the alternate method is selected, wind models from the Royal Aerospace					survivable and non-survivable
	Establishment (RAE), the Joint Airport Weather Studies (JAWS) Project and					windshear scenarios are
	other recognized sources may be implemented, but must be supported and					repeatable in the training
	properly referenced in the QTG.					environment.
	The addition of realistic levels of turbulence associated with each required					For Level 7 FTDs, windshear
	windshear profile must be available and selectable to the instructor.					training tasks may only be
						qualified for aircraft equipped
	In addition to the four basic windshear models required for qualification, at					with a synthetic stall warning
	least two additional "complex" windshear models must be available to the					system. The qualified
	instructor which represent the complexity of actual windshear encounters.					windshear profile(s) are
	These models must be available in the takeoff and landing configurations and					evaluated to ensure the
	must consist of independent variable winds in multiple simultaneous					synthetic stall warning (and
	components. The Windshear Training Aid provides two such example					not the stall buffet) is first
	"complex" windshear models that may be used to satisfy this requirement.					indication of the stall.
2.f.	The FTD must provide for manual and automatic testing of FTD hardware				X	Automatic "flagging" of out-
	and software programming to determine compliance with FTD objective tests					of-tolerance situations is

	Table B1A – Minimum FTD Requirements															
	QPS REQUIREMENTS					INFORMATION										
Entry			FTD			FTD										
Number	General FTD Requirements	Level			T	Notes										
114111501		4	5	6	7											
	as prescribed in Attachment 2 of this appendix.					encouraged.										
	An SOC is required.															
2.g.	The FTD must accurately reproduce the following runway conditions:				X											
	(1) Dry;															
	(2) Wet;															
	(3) Icy;															
	(4) Patchy Wet;															
	(5) Patchy Icy; and															
	(6) Wet on Rubber Residue in Touchdown Zone.															
	An SOC is required.															
2.h.	The FTD must simulate:				X	FTD pitch, side loading, and										
	(1) brake and tire failure dynamics, including antiskid failure; and					directional control										
	(2) decreased brake efficiency due to high brake temperatures, if applicable.					characteristics should be										
						representative of the airplane.										
	An SOC is required															
2.i.	Engine and Airframe Icing				X	1										
	Modeling that includes the effects of icing, where appropriate, on the					describing the effects which										
	airframe, aerodynamics, and the engine(s). Icing models must simulate the					provide training in the specific										
	aerodynamic degradation effects of ice accretion on the airplane lifting					skills required for recognition										
	surfaces including loss of lift, decrease in stall angle of attack, change in					of icing phenomena and										
	pitching moment, decrease in control effectiveness, and changes in control					execution of recovery. The										
	forces in addition to any overall increase in drag. Aircraft systems (such as					SOC should describe the										
	the stall protection system and autoflight system) must respond properly to					source data and any analytical										
	ice accretion consistent with the simulated aircraft.					methods used to develop ice										

	Table B1A – Minimum FTD Requirements					
	QPS REQUIREMENTS					INFORMATION
Entry Number	General FTD Requirements	FTD Level				Notes
	Aircraft OEM data or other acceptable analytical methods must be utilized to develop ice accretion models that are representative of the simulated aircraft's performance degradation in a typical in-flight icing encounter. Acceptable analytical methods may include wind tunnel analysis and/or engineering analysis of the aerodynamic effects of icing on the lifting surfaces coupled with tuning and supplemental subjective assessment by a subject matter expert pilot.  SOC required.	4	5	6	7	accretion models including verification that these effects have been tested.  Icing effects simulation models are only required for those airplanes authorized for operations in icing conditions. Icing simulation models should be developed to provide training in the specific skills required for recognition of ice accumulation and execution of the required response.  See Attachment 7 of this Appendix for further guidance material.
2.j.	The aerodynamic modeling in the FTD must include:  (1) Low-altitude level-flight ground effect;  (2) Mach effect at high altitude;  (3) Normal and reverse dynamic thrust effect on control surfaces;  (4) Aeroelastic representations; and  (5) Nonlinearities due to sideslip.  An SOC is required and must include references to computations of				X	See Attachment 2 of this appendix, paragraph 5, for further information on ground effect.

QPS REQUIREMENTS  General FTD Requirements  aeroelastic representations and of nonlinearities due to sideslip.  The FTD must have aerodynamic and ground reaction modeling for the	4	F'I Le			INFORMATION
neroelastic representations and of nonlinearities due to sideslip.	4	Le			
<u> </u>	4		vei		Notes
<u> </u>		5	6	7	
The FTD must have aerodynamic and ground reaction modeling for the					
effects of reverse thrust on directional control, if applicable.				X	
An SOC is required.					
nt Operation.					
All relevant instrument indications involved in the simulation of the airplane must automatically respond to control movement or external disturbances to he simulated airplane; e.g., turbulence or windshear. Numerical values must be presented in the appropriate units.		X	X	X	
For Level 7 FTDs, instrument indications must also respond to effects resulting from icing.					
Navigation equipment must be installed and operate within the tolerances applicable for the airplane.  Levels 6 must also include communication equipment (inter-phone and hir/ground) like that in the airplane and, if appropriate to the operation being conducted, an oxygen mask microphone system.  Level 5 need have only that navigation equipment necessary to fly an instrument approach.		X	X		
Communications, navigation, caution, and warning equipment must be installed and operate within the tolerances applicable for the airplane.  Instructor control of internal and external navigational aids. Navigation aids must be usable within range or line-of-sight without restriction, as applicable				X	See Attachment 3 of this appendix for further information regarding longrange navigation equipment.
nstru Comn nstall nstru nust l	ment approach. nunications, navigation, caution, and warning equipment must be ed and operate within the tolerances applicable for the airplane.  ctor control of internal and external navigational aids. Navigation aids be usable within range or line-of-sight without restriction, as applicable	ment approach. nunications, navigation, caution, and warning equipment must be ed and operate within the tolerances applicable for the airplane.  ctor control of internal and external navigational aids. Navigation aids be usable within range or line-of-sight without restriction, as applicable	ment approach.  nunications, navigation, caution, and warning equipment must be ed and operate within the tolerances applicable for the airplane.  ctor control of internal and external navigational aids. Navigation aids be usable within range or line-of-sight without restriction, as applicable	ment approach. nunications, navigation, caution, and warning equipment must be ed and operate within the tolerances applicable for the airplane.  ctor control of internal and external navigational aids. Navigation aids be usable within range or line-of-sight without restriction, as applicable	ment approach. nunications, navigation, caution, and warning equipment must be ed and operate within the tolerances applicable for the airplane.  ctor control of internal and external navigational aids. Navigation aids

	Table B1A – Minimum FTD Requirements											
	QPS REQUIREMENTS					INFORMATION						
Entry Number	General FTD Requirements			Level				Level				Notes
Tuniber		4	5	6	7							
3.b.3.	Complete navigation database for at least 3 airports with corresponding precision and non-precision approach procedures, including navigational database updates.				X							
3.c.1.	Installed systems must simulate the applicable airplane system operation, both on the ground and in flight. Installed systems must be operative to the extent that applicable normal, abnormal, and emergency operating procedures included in the sponsor's training programs can be accomplished.  Level 6 must simulate all applicable airplane flight, navigation, and systems operation.  Level 5 must have at least functional flight and navigational controls, displays, and instrumentation.  Level 4 must have at least one airplane system installed and functional.	X	X	X								
3.c.2.	Simulated airplane systems must operate as the airplane systems operate under normal, abnormal, and emergency operating conditions on the ground and in flight.  Once activated, proper systems operation must result from system management by the crew member and not require any further input from the instructor's controls.				X	Airplane system operation should be predicated on, and traceable to, the system data supplied by the airplane manufacturer, original equipment manufacturer or alternative approved data for the airplane system or component.  At a minimum, alternate approved data should validate the operation of all normal, abnormal, and emergency						

	Table B1A – Minimum FTD Requirements					
	QPS REQUIREMENTS	1				INFORMATION
Entry Number	General FTD Requirements		Le	ΓD vel		Notes
Nullibei		4	5	6	7	
						operating procedures and training tasks the FSTD is qualified to conduct.
3.d.	The lighting environment for panels and instruments must be sufficient for the operation being conducted.	X	X	X	X	Back-lighted panels and instruments may be installed but are not required.
3.e.	The FTD must provide control forces and control travel that corresponds to the airplane being simulated. Control forces must react in the same manner as in the airplane under the same flight conditions.  For Level 7 FTDs, control systems must replicate airplane operation for the			X	X	
	normal and any non-normal modes including back-up systems and should reflect failures of associated systems. Appropriate cockpit indications and messages must be replicated.					
3.f.	The FTD must provide control forces and control travel of sufficient precision to manually fly an instrument approach.		X			
3.e.	FTD control feel dynamics must replicate the airplane. This must be determined by comparing a recording of the control feel dynamics of the FTD to airplane measurements. For initial and upgrade qualification evaluations, the control dynamic characteristics must be measured and recorded directly from the flight deck controls, and must be accomplished in takeoff, cruise, and landing flight conditions and configurations.				X	
4. Instruc	tor or Evaluator Facilities.					
4.a.1.	In addition to the flight crewmember stations, suitable seating arrangements for an instructor/check airman and FAA Inspector must be available. These seats must provide adequate view of crewmember's panel(s).	X	X	X		These seats need not be a replica of an aircraft seat and may be as simple as an office

	Table B1A – Minimum FTD Requirements					
	QPS REQUIREMENTS					INFORMATION
Entry Number	General FTD Requirements		FTD Level			Notes
Number		4	5	6	7	
						chair placed in an appropriate position.
4.a.2.	In addition to the flight crewmember stations, the FTD must have at least two suitable seats for the instructor/check airman and FAA inspector. These seats must provide adequate vision to the pilot's panel and forward windows. All seats other than flight crew seats need not represent those found in the airplane, but must be adequately secured to the floor and equipped with similar positive restraint devices.				X	The NSPM will consider alternatives to this standard for additional seats based on unique flight deck configurations.
4.b.1.	The FTD must have instructor controls that permit activation of normal, abnormal, and emergency conditions as appropriate. Once activated, proper system operation must result from system management by the crew and not require input from the instructor controls.	X	X	X		
4.b.2.	The FTD must have controls that enable the instructor/evaluator to control all required system variables and insert all abnormal or emergency conditions into the simulated airplane systems as described in the sponsor's FAA-approved training program; or as described in the relevant operating manual as appropriate.				X	
4.c.	The FTD must have instructor controls for all environmental effects expected to be available at the IOS; e.g., clouds, visibility, icing, precipitation, temperature, storm cells and microbursts, turbulence, and intermediate and high altitude wind speed and direction.				X	
4.d.	The FTD must provide the instructor or evaluator the ability to present ground and air hazards.				X	For example, another airplane crossing the active runway or converging airborne traffic.
5. Motion	· · · · · · · · · · · · · · · · · · ·					
5.a.	The FTD may have a motion system, if desired, although it is not required. If		X	X	X	The motion system standards

	Table B1A – Minimum FTD Requirements					
	QPS REQUIREMENTS					INFORMATION
Entry Number	General FTD Requirements			FD evel 6	7	Notes
	a motion system is installed and additional training, testing, or checking credits are being sought on the basis of having a motion system, the motion system operation may not be distracting and must be coupled closely to provide integrated sensory cues. The motion system must also respond to abrupt input at the pilot's position within the allotted time, but not before the time when the airplane responds under the same conditions.	4	3	0	7	set out in part 60, Appendix A for at least Level A simulators is acceptable.
5.b.	If a motion system is installed, it must be measured by latency tests or transport delay tests and may not exceed 300 milliseconds. Instrument response may not occur prior to motion onset.			X	X	The motion system standards set out in part 60, Appendix A for at least Level A simulators is acceptable.
6. Visual	System.					
6.a.	The FTD may have a visual system, if desired, although it is not required. If a visual system is installed, it must meet the following criteria:	X	X	X		
6.a.1.	The visual system must respond to abrupt input at the pilot's position.  An SOC is required.		X	X		
6.a.2.	The visual system must be at least a single channel, non-collimated display.  An SOC is required.	X	X	X		
6.a.3.	The visual system must provide at least a field-of-view of 18° vertical / 24° horizontal for the pilot flying.  An SOC is required.	X	X	X		
6.a.4.	The visual system must provide for a maximum parallax of 10° per pilot.  An SOC is required.	X	X	X		
6.a.5.	The visual scene content may not be distracting.  An SOC is required.	X	X	X		

	Table B1A – Minimum FTD Requirements					
	QPS REQUIREMENTS	INFORMATION				
Entry Number	General FTD Requirements	FTD Level				Notes
rumber		4	5	6	7	
6.a.6.	The minimum distance from the pilot's eye position to the surface of a direct view display may not be less than the distance to any front panel instrument.  An SOC is required.					
6.a.7.	The visual system must provide for a minimum resolution of 5 arc-minutes for both computed and displayed pixel size.  An SOC is required.	X	X	X		
6.b.	If a visual system is installed and additional training, testing, or checking credits are being sought on the basis of having a visual system, a visual system meeting the standards set out for at least a Level A FFS (see Appendix A of this part) will be required. A "direct-view," non-collimated visual system (with the other requirements for a Level A visual system met) may be considered satisfactory for those installations where the visual system design "eye point" is appropriately adjusted for each pilot's position such that the parallax error is at or less than 10° simultaneously for each pilot.			X		Directly projected, non-collimated visual displays may prove to be unacceptable for dual pilot applications.
6.c.	An SOC is required.  The FTD must have a visual system providing an out-of-the-flight deck view.				X	
6.d.	The FTD must provide a continuous visual field-of-view of at least176° horizontally and 36° vertically or the number of degrees necessary to meet the visual ground segment requirement, whichever is greater. The minimum horizontal field-of-view coverage must be plus and minus one-half (½) of the minimum continuous field-of-view requirement, centered on the zero degree azimuth line relative to the aircraft fuselage.  An SOC is required and must explain the system geometry measurements including system linearity and field-of-view.				X	The horizontal field-of-view is traditionally described as a 180° field-of-view. However, the field-of-view is technically no less than 176°. Additional field-of-view capability may be added at the sponsor's discretion provided the minimum fields of view are

	Table B1A – Minimum FTD Requirements					
	QPS REQUIREMENTS					INFORMATION
Entry Number	General FTD Requirements		Le	TD evel		Notes
Number		4	5	6	7	
	Collimation is not required but parallax effects must be minimized (not					
	greater than 10° for each pilot when aligned for the point midway between the left and right seat eyepoints).					
6.e.	The visual system must be free from optical discontinuities and artifacts that create non-realistic cues.					Non-realistic cues might include image "swimming" and image "roll-off," that may lead a pilot to make incorrect assessments of speed, acceleration, or situational awareness.
6.f.	The FTD must have operational landing lights for night scenes. Where used, dusk (or twilight) scenes require operational landing lights.				X	
6.g.	The FTD must have instructor controls for the following:  (1) Visibility in statute miles (km) and runway visual range (RVR) in ft.(m); (2) Airport selection; and (3) Airport lighting.				X	
6.h.	The FTD must provide visual system compatibility with dynamic response programming.				X	
6.i.	The FTD must show that the segment of the ground visible from the FTD flight deck is the same as from the airplane flight deck (within established tolerances) when at the correct airspeed, in the landing configuration, at the appropriate height above the touchdown zone, and with appropriate visibility.				X	This will show the modeling accuracy of RVR, glideslope, and localizer for a given weight, configuration, and speed within the airplane's operational envelope for a normal approach and landing.

	Table B1A – Minimum FTD Requirements					
	QPS REQUIREMENTS					INFORMATION
Entry Number	General FTD Requirements	FTD Level 4 5 6 7		7	Notes	
6.j.	The FTD must provide visual cues necessary to assess sink rates (provide depth perception) during takeoffs and landings, to include:  (1) Surface on runways, taxiways, and ramps; and  (2) Terrain features.	4	3	6	X	
6.k.	The FTD must provide for accurate portrayal of the visual environment relating to the FTD attitude.				X	Visual attitude vs. FTD attitude is a comparison of pitch and roll of the horizon as displayed in the visual scene compared to the display on the attitude indicator.
6.1.	The FTD must provide for quick confirmation of visual system color, RVR, focus, and intensity.  An SOC is required.				X	
6.m.	The FTD must be capable of producing at least 10 levels of occulting.				X	
6.n.	Night Visual Scenes. When used in training, testing, or checking activities, the FTD must provide night visual scenes with sufficient scene content to recognize the airport, the terrain, and major landmarks around the airport. The scene content must allow a pilot to successfully accomplish a visual landing. Scenes must include a definable horizon and typical terrain characteristics such as fields, roads and bodies of water and surfaces illuminated by airplane landing lights.				X	
6.0.	Dusk (or Twilight) Visual Scenes. When used in training, testing, or checking activities, the FTD must provide dusk (or twilight) visual scenes with sufficient scene content to recognize the airport, the terrain, and major landmarks around the airport. The scene content must allow a pilot to				X	

	Table B1A – Minimum FTD Requirements									
	QPS REQUIREMENTS					INFORMATION				
Entry Number	General FTD Requirements  FTD Level			Notes						
Number		4	5	6	7					
	successfully accomplish a visual landing. Dusk (or twilight) scenes, as a minimum, must provide full color presentations of reduced ambient intensity, sufficient surfaces with appropriate textural cues that include self-illuminated objects such as road networks, ramp lighting and airport signage, to conduct a visual approach, landing and airport movement (taxi). Scenes must include a definable horizon and typical terrain characteristics such as fields, roads and bodies of water and surfaces illuminated by airplane landing lights. If provided, directional horizon lighting must have correct orientation and be consistent with surface shading effects. Total night or dusk (twilight) scene content must be comparable in detail to that produced by 10,000 visible textured surfaces and 15,000 visible lights with sufficient system capacity to display 16 simultaneously moving objects.									
6.p.	An SOC is required.  Daylight Visual Scenes. The FTD must provide daylight visual scenes with sufficient scene content to recognize the airport, the terrain, and major landmarks around the airport. The scene content must allow a pilot to successfully accomplish a visual landing. Any ambient lighting must not "washout" the displayed visual scene. Total daylight scene content must be comparable in detail to that produced by 10,000 visible textured surfaces and 6,000 visible lights with sufficient system capacity to display 16 simultaneously moving objects. The visual display must be free of apparent and distracting quantization and other distracting visual effects while the FTD is in motion.  An SOC is required.				X					

	Table B1A – Minimum FTD Requirements					
	QPS REQUIREMENTS					INFORMATION
Entry Number	General FTD Requirements	4		TD evel 6	7	Notes
6.q.	The FTD must provide operational visual scenes that portray physical relationships known to cause landing illusions to pilots.	4	3		X	For example: short runways, landing approaches over water, uphill or downhill runways, rising terrain on the approach path, unique topographic features.
6.r.	The FTD must provide special weather representations of light, medium, and heavy precipitation near a thunderstorm on takeoff and during approach and landing. Representations need only be presented at and below an altitude of 2,000 ft. (610 m) above the airport surface and within 10 miles (16 km) of the airport.				X	
6.s.	The FTD must present visual scenes of wet and snow-covered runways, including runway lighting reflections for wet conditions, partially obscured lights for snow conditions, or suitable alternative effects.				X	
6.t.	The FTD must present realistic color and directionality of all airport lighting.				X	
6.u.	The following weather effects as observed on the visual system must be simulated and respective instructor controls provided.  (1) Multiple cloud layers with adjustable bases, tops, sky coverage and scud effect;  (2) Storm cells activation and/or deactivation;  (3) Visibility and runway visual range (RVR), including fog and patchy fog effect;  (4) Effects on ownship external lighting;  (5) Effects on airport lighting (including variable intensity and fog effects);  (6) Surface contaminants (including wind blowing effect);				X	Scud effects are low, detached, and irregular clouds below a defined cloud layer.

	Table B1A – Minimum FTD Requirements																																																					
	QPS REQUIREMENTS					INFORMATION																																																
Entry Number	General FTD Requirements	FTD Level			Level			Level			Level			Level			Level			Level			Level			Level			Level			Level			Level			Level			Level			Level			Level			Level			7	Notes
6.v.	<ul> <li>(7) Variable precipitation effects (rain, hail, snow);</li> <li>(8) In-cloud airspeed effect; and</li> <li>(9) Gradual visibility changes entering and breaking out of cloud.</li> <li>The simulator must provide visual effects for:</li> </ul>	4	3	0		Visual effects for light poles																																																
	<ul> <li>(1) Light poles;</li> <li>(2) Raised edge lights as appropriate; and</li> <li>(3) Glow associated with approach lights in low visibility before physical lights are seen,</li> </ul>					and raised edge lights are for the purpose of providing additional depth perception during takeoff, landing, and taxi training tasks. Three dimensional modeling of the actual poles and stanchions is not required.																																																
7. Sound	System.																																																					
7.a.	The FTD must provide flight deck sounds that result from pilot actions that correspond to those that occur in the airplane.			X	X																																																	
7.b.	The volume control must have an indication of sound level setting which meets all qualification requirements.				X	This indication is of the sound level setting as evaluated during the FTD's initial evaluation.																																																
7.c.	The FTD must accurately simulate the sound of precipitation, windshield wipers, and other significant airplane noises perceptible to the pilot during normal and abnormal operations, and include the sound of a crash (when the FTD is landed in an unusual attitude or in excess of the structural gear limitations); normal engine and thrust reversal sounds; and the sounds of flap, gear, and spoiler extension and retraction.				X																																																	

Table B1A – Minimum FTD Requirements								
QPS REQUIREMENTS					INFORMATION			
General FTD Requirements  FTD Level			Notes					
_	4	5	6	7				
Sounds must be directionally representative.								
An SOC is required.								
The FTD must provide realistic amplitude and frequency of flight deck noises and sounds. FTD performance must be recorded, subjectively assessed for the initial evaluation, and be made a part of the OTG.				X				
	General FTD Requirements  Sounds must be directionally representative.  An SOC is required.  The FTD must provide realistic amplitude and frequency of flight deck noises and sounds. FTD performance must be recorded, subjectively assessed for	General FTD Requirements  General FTD Requirements  4  Sounds must be directionally representative.  An SOC is required.  The FTD must provide realistic amplitude and frequency of flight deck noises	An SOC is required.  The FTD must provide realistic amplitude and frequency of flight deck noises and sounds. FTD performance must be recorded, subjectively assessed for	An SOC is required.  The FTD must provide realistic amplitude and frequency of flight deck noises and sounds. FTD performance must be recorded, subjectively assessed for	An SOC is required.  The FTD must provide realistic amplitude and frequency of flight deck noises and sounds. FTD performance must be recorded, subjectively assessed for			

	Table B1B - Table of Tasks vs. FTD L	Level				
	QPS REQUIREMENTS					INFORMATION
Entry Number	Subjective Requirements  In order to be qualified at the FTD qualification level indicated, the FTD must be able to perform at least the tasks associated with that level of qualification. See Notes 1, 2 and 3 at			ı	Notes	
Number	the end of the Table	4	5	6	7	
1. Preflight	Procedures.					
1.a.	Preflight Inspection (flight deck only)	A	A	X	X	
1.b.	Engine Start	A	A	X	X	
1.c.	Taxiing				T	
1.d.	Pre-takeoff Checks	A	A	X	X	
2. Takeoff a	nd Departure Phase.					
2.a.	Normal and Crosswind Takeoff				T	
2.b.	Instrument Takeoff				T	
2.c.	Engine Failure During Takeoff				T	
2.d.	Rejected Takeoff (requires visual system)			A	X	
2.e.	Departure Procedure		X	X	X	
3. Inflight M	laneuvers.					
3.a.	Steep Turns		X	X	X	
3.b	Approaches to Stalls		A	X	X	Approach to stall maneuvers qualified only where the aircraft does not exhibit stall buffet as the first indication of the stall.
3.c.	Engine Failure—Multiengine Airplane		A	X	X	
3.d.	Engine Failure—Single-Engine Airplane		A	X	X	
3.e.	Specific Flight Characteristics incorporated into the user's FAA approved flight training program.	A	A	A	A	Level 4 FTDs have no minimum requirement for aerodynamic programming and are generally not qualified to conduct in-flight maneuvers.
3.f.	Windshear Recovery				Т	For Level 7 FTD, windshear recovery may be qualified at the Sponsor's option. See Table B1A for specific requirements and limitations.
	nt Procedures.		1			
4.a.	Standard Terminal Arrival / Flight Management System Arrivals Procedures		A	X	X	

	Table B1B - Table of Tasks vs. FTD L	evel							
	QPS REQUIREMENTS					INFORMATION			
_	Subjective Requirements	FTD			FTD				
Entry	In order to be qualified at the FTD qualification level indicated, the FTD must be able to	Level				Notes			
Number	perform at least the tasks associated with that level of qualification. See Notes 1, 2 and 3 at the end of the Table	4	5	6	7	1,000			
4.b.	Holding		A	X	X				
4.c.	Precision Instrument								
4.c.1.	All engines operating.		A	X	X	e.g., Autopilot, Manual (Flt. Dir. Assisted), Manual (Raw Data)			
4.c.2.	One engine inoperative.				T	e.g., Manual (Flt. Dir. Assisted), Manual (Raw Data)			
4.d.	Non-precision Instrument Approach		A	X	X	e.g., NDB, VOR, VOR/DME, VOR/TAC, RNAV, LOC, LOC/BC, ADF, and SDF.			
4.e.	Circling Approach (requires visual system)			A	X	Specific authorization required.			
4.f.	Missed Approach								
4.f.1.	Normal.		A	X	X				
4.f.2.	One engine Inoperative.				T				
5. Landings	and Approaches to Landings.		•	•					
5.a.	Normal and Crosswind Approaches and Landings				T				
5.b.	Landing From a Precision / Non-Precision Approach				T				
5.c.	Approach and Landing with (Simulated) Engine Failure – Multiengine Airplane				T				
5.d.	Landing From Circling Approach				T				
5.e.	Rejected Landing				T				
5.f.	Landing From a No Flap or a Nonstandard Flap Configuration Approach				T				
6. Normal a	nd Abnormal Procedures.					<u></u>			
6.a.	Engine (including shutdown and restart)	A	A	X	X				
6.b.	Fuel System	A	A	X	X				
6.c.	Electrical System	A	A	X	X				
6.d.	Hydraulic System	A	A	X	X				
6.e.	Environmental and Pressurization Systems	A	A	X	X				
6.f.	Fire Detection and Extinguisher Systems	A	A	X	X				
6.g.	Navigation and Avionics Systems	A	A	X	X				
6.h.	Automatic Flight Control System, Electronic Flight Instrument System, and Related Subsystems	A	A	X	X				

	Table B1B - Table of Tasks vs. FTD Level								
	QPS REQUIREMENTS					INFORMATION			
Entry	Subjective Requirements  In order to be qualified at the FTD qualification level indicated, the FTD must be able to		FTD Level			Notes			
Number	perform at least the tasks associated with that level of qualification. See Notes 1, 2 and 3 at the end of the Table	4	5	6	7				
6.i.	Flight Control Systems	A	A	X	X				
6.j.	Anti-ice and Deice Systems	A	A	X	X				
6.k.	Aircraft and Personal Emergency Equipment	A	A	X	X				
7. Emergen	cy Procedures.								
7.a.	Emergency Descent (Max. Rate)		A	X	X				
7.b.	Inflight Fire and Smoke Removal		A	X	X				
7.c.	Rapid Decompression		A	X	X				
7.d.	Emergency Evacuation	A	A	X	X				
8. Postflight	Procedures.								
8.a.	After-Landing Procedures	A	A	X	X				
8.b.	Parking and Securing	A	A	X	X				

Note 1: An "A" in the table indicates that the system, task, or procedure, although not required to be present, may be examined if the appropriate airplane system is simulated in the FTD and is working properly.

Note 2: Items not installed or not functional on the FTD and not appearing on the SOQ Configuration List, are not required to be listed as exceptions on the SOQ.

Note 3: A "T" in the table indicates that the task may only be qualified for introductory initial or recurrent qualification training. These tasks may not be qualified for proficiency testing or checking credits in an FAA approved flight training program.

- 4. On page 18327, correct amendatory instruction 15 to read as follows:
  - 15. Amend Attachment 2 to Appendix B as follows:
  - A. Revise paragraph 2.e;
  - B. Revise Table B2A;
  - C. Revise Table B2B;
  - D. Revise Table B2C;
  - E. Revise Table B2D; and
  - F. Revise Table B2E.

The revisions and additions read as follows:

\* \* \* \* \*

5. Correct the tables appearing on pages 18329-18375 to read as follows:

		Tabl	e B2A - Flight Tra	ining Device (FTD) Objective Tests				
			QPS REQUIREM	ENTS				INFORMATION
Test		- Tolerance	Flight	Test	FTD Level			Notes
Entry Number		Total unite	Conditions	Details	5	6	7	Titotes
1. Perfor	mance.							
1.a.	Taxi.							
1.a.1	Minimum radius turn.	±0.9 m (3 ft) or ±20% of airplane turn radius.	Ground.	Plot both main and nose gear loci and key engine parameter(s). Data for no brakes and the minimum thrust required to maintain a steady turn except for airplanes requiring asymmetric thrust or braking to achieve the minimum radius turn.			X	
1.a.2	Rate of turn versus nosewheel steering angle (NWA).	$\pm 10\%$ or $\pm 2^{\circ}$ /s of turn rate.	Ground.	Record for a minimum of two speeds, greater than minimum turning radius speed with one at a typical taxi speed, and with a spread of at least 5 kt.			X	
1.b.	Takeoff.			Note.— For Level 7 FTD, all airplane manufacturer commonly-used certificated take-off flap settings must be demonstrated at least once either in minimum unstick speed (1.b.3), normal take-off (1.b.4), critical engine failure on take-off (1.b.5) or crosswind take-off (1.b.6).				
1.b.1	Ground acceleration time and distance.	±1.5 s or ±5% of time; and ±61 m (200 ft) or ±5% of distance. For Level 6 FTD: ±1.5 s or ±5% of time.	Takeoff.	Acceleration time and distance must be recorded for a minimum of 80% of the total time from brake release to V <sub>r</sub> . Preliminary aircraft certification data may be used.		X	X	takeoff (1.b.4.) or rejected takeoff (1.b.7.). Plotted data should be shown using appropriate scales for each portion of the maneuver.  For Level 6 FTD, this test is required only if RTO training credit is sought.
1.b.2	Minimum control speed, ground (V <sub>mcg</sub> ) using aerodynamic controls only per applicable airworthiness	±25% of maximum airplane lateral deviation reached or ±1.5 m (5 ft).	Takeoff.	Engine failure speed must be within ±1 kt of airplane engine failure speed. Engine thrust decay must be that resulting from the mathematical model for the engine applicable to the FTD under test. If the modeled engine is not the same as the airplane manufacturer's flight test engine, a			X	If a $V_{\rm mcg}$ test is not available, an acceptable alternative is a flight test snap engine deceleration to idle at a speed between $V_1$ and $V_1$ -10 kt, followed by control of heading using aerodynamic

		Table	<b>B2A - Flight Train</b>	ning Device (FTD) Objective Tests				
	INFORMATION							
	Test	- Tolerance	Flight	Test	FTD Level			Notes
Entry Number	Title	Tolerance	Conditions	Details	5	6	7	Tiotes
	requirement or alternative engine inoperative test to demonstrate ground control characteristics.	reversible flight control systems: ±10% or ±2.2 daN (5 lbf) rudder pedal force.		further test may be run with the same initial conditions using the thrust from the flight test data as the driving parameter.				control only and recovery should be achieved with the main gear on the ground.  To ensure only aerodynamic control, nosewheel steering must be disabled (i.e. castored) or the nosewheel held slightly off the ground.
1.b.3	Minimum unstick speed $(V_{mu})$ or equivalent test to demonstrate early rotation take-off characteristics.	±3 kt airspeed. ±1.5° pitch angle.	Takeoff.	Record time history data from 10 knots before start of rotation until at least 5 seconds after the occurrence of main gear lift-off.			X	U
1.b.4	Normal take-off.	±3 kt airspeed.  ±1.5° pitch angle.  ±1.5° AOA.  ±6 m (20 ft) height.  For airplanes with	Takeoff.	Data required for near maximum certificated takeoff weight at mid center of gravity location and light takeoff weight at an aft center of gravity location. If the airplane has more than one certificated take-off configuration, a different configuration must be used for each weight.  Record takeoff profile from brake release to at least 61 m (200 ft) AGL.			X	

		Table	B2A - Flight Trai	ning Device (FTD) Objective Tests							
	QPS REQUIREMENTS										
	Test	Tolerance	Flight	Test	FTD Level			Notes			
Entry Number	Title	Toterunce	Conditions	Details	5	6	7	110165			
		reversible flight control systems: ±2.2 daN (5 lbf) or									
		±10% of column force.									
1.b.5	Critical engine failure on take-off.	±3 kt airspeed. ±1.5° pitch angle.	Takeoff.	Record takeoff profile to at least 61 m (200 ft) AGL.			X				
		±1.5° AOA.									
		±6 m (20 ft) height.		Engine failure speed must be within $\pm 3$ kt of airplane data.							
		±2° roll angle.		Test at mean maximum talreaff weight							
		±2° side-slip angle.		Test at near maximum takeoff weight							
		±3° heading angle.									
		For airplanes with reversible flight control systems:									
		±2.2 daN (5 lbf) or ±10% of column force;									
		±1.3 daN (3 lbf) or ±10% of wheel force; and									
		±2.2 daN (5 lbf) or ±10% of rudder pedal force.									
1.b.6	Crosswind take-off.	± 3 kt airspeed.	Takeoff.	Record takeoff profile from brake release to at			X	In those situations where a maximum crosswind or a			
		±1.5° pitch angle.		least 61 m (200 ft) AGL.				maximum demonstrated			
		±1.5° AOA.		This test requires test data, including wind profile, for a crosswind component of at least 60% of the airplane performance data value				crosswind is not known, contact the NSPM.			
		±6 m (20 ft) height.		measured at 10 m (33 ft) above the runway.							
		±2° roll angle.		Wind components must be provided as headwind							

	Table B2A - Flight Training Device (FTD) Objective Tests  QPS REQUIREMENTS INFORMATION											
	INFORMATION											
	Test	_ Tolerance	Flight	Test	FTD Level			Notes				
Entry Number	Title	Tolerance	Conditions	Details	5	6	7	Hotes				
		±2° side-slip angle.		and crosswind values with respect to the runway.								
		±3° heading angle.										
		Correct trends at ground speeds below 40 kt for rudder/pedal and heading angle.										
		For airplanes with reversible flight control systems:										
		±2.2 daN (5 lbf) or ±10% of column force;										
		$\pm 1.3$ daN (3 lbf) or $\pm 10\%$ of wheel force; and										
		±2.2 daN (5 lbf) or ±10% of rudder pedal force.										
1.b.7.a.	Rejected Takeoff.	$\pm 5\%$ of time or $\pm 1.5$ s.	Takeoff.	Record at mass near maximum takeoff weight.			X	Autobrakes will be used where applicable.				
		±7.5% of distance or		Speed for reject must be at least 80% of V <sub>1</sub> .				аррисаніс.				
		±76 m (250 ft).		Maximum braking effort, auto or manual.								
		For Level 6 FTD: $\pm 5\%$ of time or $\pm 1.5$ s.		Where a maximum braking demonstration is not available, an acceptable alternative is a test using approximately 80% braking and full reverse, if applicable.								
				Time and distance must be recorded from brake release to a full stop.								

			B2A - Flight Tra PS REQUIREM	ining Device (FTD) Objective Tests				
	INFORMATION							
Test		Tolerance	Flight	Test	FTD Level			Notes
Entry Number	Title	1 ord unce	Conditions	Details	5	6	7	110005
1.b.7.b.	Rejected Takeoff.	$\pm$ 5% of time or $\pm$ 1.5 s.	Takeoff	Record time for at least 80% of the segment from initiation of the rejected takeoff to full stop.		X		For Level 6 FTD, this test is required only if RTO training credit is sought.
1.b.8.	Dynamic Engine Failure After Takeoff.	±2°/s or ±20% of body angular rates.	Takeoff.	Engine failure speed must be within ±3 kt of airplane data.  Engine failure may be a snap deceleration to idle.  Record hands-off from 5 s before engine failure to +5 s or 30° roll angle, whichever occurs first.  CCA: Test in Normal and Non-normal control state.			X	For safety considerations, airplane flight test may be performed out of ground effect at a safe altitude, but with correct airplane configuration and airspeed.
1.c.	Climb.			States				
1.c.1.	Normal Climb, all engines operating.	±3 kt airspeed.  ±0.5 m/s (100 ft/ min) or ±5% of rate of climb.	Clean.	Flight test data are preferred; however, airplane performance manual data are an acceptable alternative.  Record at nominal climb speed and mid initial climb altitude.  FTD performance is to be recorded over an interval of at least 300 m (1, 000 ft).	X	X	X	For Level 5 and Level 6 FTDs, this may be a snapshot test result.
1.c.2.	One-engine- inoperative 2nd segment climb.	±3 kt airspeed.  ±0.5 m/s (100 ft/ min) or ±5% of rate of climb, but not less than airplane performance data requirements.	2nd segment climb.	Flight test data is preferred; however, airplane performance manual data is an acceptable alternative.  Record at nominal climb speed.  FTD performance is to be recorded over an interval of at least 300 m (1,000 ft).  Test at WAT (weight, altitude or temperature) limiting condition.			X	

		Table	B2A - Flight Train	ning Device (FTD) Objective Tests								
	QPS REQUIREMENTS											
	Test	Tolerance	Flight	Test	FTD Level			Notes				
Entry Number	Title	1 0101 41100	Conditions	Details	5	6	7	Tiotes				
1.c.3.	One Engine Inoperative En route Climb.	$\pm 10\%$ time, $\pm 10\%$ distance, $\pm 10\%$ fuel used	Clean	Flight test data or airplane performance manual data may be used.  Test for at least a 1,550 m (5,000 ft) segment.			X					
1.c.4.	One Engine Inoperative Approach Climb for airplanes with icing accountability if provided in the airplane performance data for this phase of flight.	±3 kt airspeed.  ±0.5 m/s (100 ft/ min) or ±5% rate of climb, but not less than airplane performance data.	Approach	Flight test data or airplane performance manual data may be used.  FTD performance to be recorded over an interval of at least 300 m (1,000 ft).  Test near maximum certificated landing weight as may be applicable to an approach in icing conditions.			X	Airplane should be configured with all anti-ice and de-ice systems operating normally, gear up and go-around flap.  All icing accountability considerations, in accordance with the airplane performance data for an approach in icing conditions, should be applied.				
1.d.	Cruise / Descent.											
1.d.1.	Level flight acceleration	±5% Time	Cruise	Time required to increase airspeed a minimum of 50 kt, using maximum continuous thrust rating or equivalent.  For airplanes with a small operating speed range, speed change may be reduced to 80% of operational speed change.			X					
1.d.2.	Level flight deceleration.	±5% Time	Cruise	Time required to decrease airspeed a minimum of 50 kt, using idle power.  For airplanes with a small operating speed range, speed change may be reduced to 80% of operational speed change.			X					
1.d.3.	Cruise performance.	±.05 EPR or ±3% N1 or ±5% of torque.  ±5% of fuel flow.	Cruise.	The test may be a single snapshot showing instantaneous fuel flow, or a minimum of two consecutive snapshots with a spread of at least 3 minutes in steady flight.			X					
1.d.4.	Idle descent.	±3 kt airspeed. ±1.0 m/s (200 ft/min) or	Clean.	Idle power stabilized descent at normal descent speed at mid altitude.			X					
		±5% of rate of descent.		FTD performance to be recorded over an interval								

			PS REQUIREM	ining Device (FTD) Objective Tests ENTS				INFORMATION
	Test		Flight	Test	FTD Level			Notes
Entry Number	Title		Conditions	Details	5	6	7	Notes
				of at least 300 m (1,000 ft).				
1.d.5.	Emergency descent.	±5 kt airspeed. ±1.5 m/s (300 ft/min) or ±5% of rate of descent.	As per airplane performance data.	FTD performance to be recorded over an interval of at least 900 m (3,000 ft).			X	Stabilized descent to be conducted with speed brakes extended if applicable, at mid altitude and near V <sub>mo</sub> or according to emergency descending the emergen
1.e.	Stopping.							
1.e.1.	Deceleration time and distance, manual wheel brakes, dry runway, no reverse thrust.	$\pm 1.5$ s or $\pm 5\%$ of time. For distances up to 1,220 m (4,000 ft), the smaller of $\pm 61$ m (200 ft) or $\pm 10\%$ of distance. For distances greater than 1,220 m (4,000 ft), $\pm 5\%$ of distance.	Landing.	Time and distance must be recorded for at least 80% of the total time from touchdown to a full stop.  Position of ground spoilers and brake system pressure must be plotted (if applicable).  Data required for medium and near maximum certificated landing weight.  Engineering data may be used for the medium weight condition.			X	
1.e.2.	Deceleration time and distance, reverse thrust, no wheel brakes, dry runway.	$\pm 1.5$ s or $\pm 5\%$ of time; and the smaller of $\pm 61$ m (200 ft) or $\pm 10\%$ of distance.	Landing	Time and distance must be recorded for at least 80% of the total time from initiation of reverse thrust to full thrust reverser minimum operating speed.  Position of ground spoilers must be plotted (if applicable).  Data required for medium and near maximum certificated landing weight.  Engineering data may be used for the medium weight condition.			X	
1.e.3.	Stopping distance, wheel brakes, wet	±61 m (200 ft) or ±10% of distance.	Landing.	Either flight test or manufacturer's performance manual data must be used, where available.			X	

			PS REQUIREMI	ining Device (FTD) Objective Tests				INFORMATION
	Test	Tolerance	Flight		FTD Level			Notes
Entry Number	Title	Tolerance	Conditions	Details	5	6	7	Notes
	runway.			Engineering data, based on dry runway flight test stopping distance and the effects of contaminated runway braking coefficients, are an acceptable alternative.				
1.e.4.	Stopping distance, wheel brakes, icy runway.	$\pm 61$ m (200 ft) or $\pm 10\%$ of distance.	Landing.	Either flight test or manufacturer's performance manual data must be used, where available.  Engineering data, based on dry runway flight test stopping distance and the effects of contaminated runway braking coefficients, are an acceptable alternative.			X	
1.f.	Engines.	•						
1.f.1.	Acceleration.	For Level 7 FTD: ±10% Ti or ±0.25 s; and ±10% Tt or ±0.25 s. For Level 6 FTD: ±10% Tt or ±0.25 s.	Approach or landing	Total response is the incremental change in the critical engine parameter from idle power to go-around power.	X	X	X	See Appendix F of this part for definitions of $T_{i,}$ and $T_{t}$ .
1.f.2.	Deceleration.	For Level 5 FTD: ±1 s  For Level 7 FTD: ±10% Ti or ±0.25 s; and ±10% Tt or ±0.25 s.  For Level 6 FTD: ±10% Tt or ±0.25 s.  For Level 5 FTD: ±10% Tt or ±0.25 s.	Ground	Total response is the incremental change in the critical engine parameter from maximum take-off power to idle power.	X	X	X	See Appendix F of this part for definitions of $T_{i,}$ and $T_{t}$ .
2. Handlii	ng Qualities.	•						
2.a.	Static Control Tests.	•						
	Note 2 — Pitch, roll of at the flight controls when the directly recorded of static control checks,	and yaw controller position ve would be to have recording an and matched to the airplane do or equivalent means, and that	rsus force or time should be d measuring instrumentati uta. Provided the instrume evidence of the satisfactor	ated solely by use of airplane hardware in the FTD.  The measured at the control. An alternative method in lie  The built into the FTD. The force and position data fron  The force and position data fron  The force and position data fron  The time of the instrument of the instrument  The checks. Verification of the instrumentation by using ext	n this i ment v tation	instru while could	menta condu be us	tion could acting the red for both

				ning Device (FTD) Objective Tests				
		(	QPS REQUIREME	ENTS				INFORMATION
	Test	- Tolerance	Flight	Test	FTD Level			Notes
Entry Number	Title	Toterunce	Conditions	Details	5	6	7	
	being lost for the instal validation data where Note 3 — (Level 7 FTI	llation of external devices. S applicable. Donly) FTD static control te quired from the data provide	tatic and dynamic flight con sting from the second set of	rol loading system. Such a permanent installation coul atrol tests should be accomplished at the same feel or i pilot controls is only required if both sets of controls of pplicable to both sides. If controls are mechanically in	mpaci are no	t press t mec	sures hanic	as the ally interconnected on the
2.a.1.a.	Pitch controller position versus force and surface position calibration.	±0.9 daN (2 lbf) breakout. ±2.2 daN (5 lbf) or ±10% of force. ±2° elevator angle.	Ground.	Record results for an uninterrupted control sweep to the stops.		X	X	Test results should be validated with in-flight data from tests such as longitudinal static stability, stalls, etc.
2.a.1.b.	Pitch controller position versus force	±0.9 daN (2 lbf) breakout. ±2.2 daN (5 lbf) or ±10% of force.	As determined by sponsor	Record results during initial qualification evaluation for an uninterrupted control sweep to the stops. The recorded tolerances apply to subsequent comparisons on continuing qualification evaluations.	X			Applicable only on continuing qualification evaluations. The intent is to design the control feel for Level 5 to be able to manually fly an instrument approach; and not to compare results to flight test or other such data.
2.a.2.a.	Roll controller position versus force and surface position calibration.	±0.9 daN (2 lbf) breakout. ±1.3 daN (3 lbf) or ±10% of force. ±2° aileron angle. ±3° spoiler angle.	Ground.	Record results for an uninterrupted control sweep to the stops.		X	X	
2.a.2.b.	Roll controller position versus force	±0.9 daN (2 lbf) breakout.  ±1.3 daN (3 lbf) or ±10% of force.	As determined by sponsor	Record results during initial qualification evaluation for an uninterrupted control sweep to the stops. The recorded tolerances apply to subsequent comparisons on continuing qualification evaluations.	X			Applicable only on continuing qualification evaluations. The intent is to design the control feel for Level 5 to be able to manually fly an instrument approach; and not to compare results to flight test or other such

		Table	e B2A - Flight Trai	ning Device (FTD) Objective Tests				
			QPS REQUIREME	ENTS				INFORMATION
Test		- Tolerance	Flight	Test	FTD Level			Notes
Entry Number	Title	1 order unice	Conditions	Details	5	6	7	110005
2.a.3.a.	Rudder pedal position versus force and surface position calibration.	±2.2 daN (5 lbf) breakout. ±2.2 daN (5 lbf) or ±10% of force.	Ground.	Record results for an uninterrupted control sweep to the stops.		X	X	data.  Test results should be validated with in-flight data from tests such as engine-out trims, steady state side-slips, etc.
2.a.3.b.	Rudder pedal position versus force	±2° rudder angle. ±2.2 daN (5 lbf) breakout. ±2.2 daN (5 lbf) or ±10% of force.	As determined by sponsor	Record results during initial qualification evaluation for an uninterrupted control sweep to the stops. The recorded tolerances apply to subsequent comparisons on continuing qualification evaluations.	X			Applicable only on continuing qualification evaluations. The intent is to design the control feel for Level 5 to be able to manually fly an instrument approach; and not to compare results to flight test or other such data.
2.a.4.a.	Nosewheel Steering Controller Force and Position Calibration.	±0.9 daN (2 lbf) breakout. ±1.3 daN (3 lbf) or ±10% of force. ±2° NWA.	Ground.	Record results of an uninterrupted control sweep to the stops.			X	
2.a.4.b.	Nosewheel Steering Controller Force	±0.9 daN (2 lbf) breakout.  ±1.3 daN (3 lbf) or ±10% of force.	Ground.	Record results of an uninterrupted control sweep to the stops.		X		
2.a.5.	Rudder Pedal Steering Calibration.	±2° NWA.	Ground.	Record results of an uninterrupted control sweep to the stops.		X	X	
2.a.6.	Pitch Trim Indicator vs. Surface Position Calibration.	±0.5° trim angle.	Ground.			X	X	The purpose of the test is to compare FSTD surface position indicator against the FSTD flight controls model computed value.
2.a.7.	Pitch Trim Rate.	±10% of trim rate (°/s)	Ground and approach.	Trim rate to be checked at pilot primary induced			X	

		Table	B2A - Flight Train	ning Device (FTD) Objective Tests							
	QPS REQUIREMENTS										
	Test	Tolerance	Flight	Test	FTD Level			Notes			
Entry Number	Title		Conditions	Details	5	6	7	- 13132			
		or $\pm 0.1^{\circ}/s$ trim rate.		trim rate (ground) and autopilot or pilot primary trim rate in-flight at go-around flight conditions.  For CCA, representative flight test conditions must be used.							
2.a.8.	Alignment of cockpit throttle lever versus selected engine parameter.	When matching engine parameters:  ±5° of TLA.  When matching detents:  ±3% N1 or ±.03 EPR or ±3% torque, or ±3% maximum rated manifold pressure, or equivalent.  Where the levers do not have angular travel, a tolerance of ±2 cm (±0.8 in) applies.	Ground.	Simultaneous recording for all engines. The tolerances apply against airplane data.  For airplanes with throttle detents, all detents to be presented and at least one position between detents/ endpoints (where practical). For airplanes without detents, end points and at least three other positions are to be presented.		X	X	Data from a test airplane or engineering test bench are acceptable, provided the correct engine controller (both hardware and software) is used.  In the case of propeller-driven airplanes, if an additional lever, usually referred to as the propeller lever, is present, it should also be checked. This test may be a series of snapshot tests.			
2.a.9.a.	Brake pedal position versus force and brake system pressure calibration.	±2.2 daN (5 lbf) or ±10% of force. ±1.0 MPa (150 psi) or ±10% of brake system pressure.	Ground.	Relate the hydraulic system pressure to pedal position in a ground static test.  Both left and right pedals must be checked.			X	FTD computer output results may be used to show compliance.			
2.a.9.b.	Brake pedal position versus force	±2.2 daN (5 lbf) or ±10% of force.	Ground.	Two data points are required: zero and maximum deflection. Computer output results may be used to show compliance.		X		FTD computer output results may be used to show compliance.  Test not required unless RTO credit is sought.			

	INFORMATION  Notes  n = the sequential period of a full oscillation.  Refer to paragraph 4 of Appendix A, Attachment 2 for additional information.  For overdamped and critically damped systems, see Figure A2B of Appendix A for an illustration of the reference measurement.							
	Test Tolerance		Flight	Test		FTD Level		Notes
Entry Number	Title	Tolerance	Conditions	Details	5	6	7	Notes
2.b.	Dynamic Control T							
	airplane controller ı		r setting may be that requi	ntrol forces are completely generated within the red for level flight unless otherwise specified. See				
2.b.1.	Pitch Control.	For underdamped systems: $T(P_0) \pm 10\% \text{ of } P_0 \text{ or } \pm 0.05 \text{ s.}$ $T(P_1) \pm 20\% \text{ of } P_1 \text{ or } \pm 0.05 \text{ s.}$ $T(P_1) \pm 20\% \text{ of } P_1 \text{ or } \pm 0.05 \text{ s.}$ $T(P_2) \pm 30\% \text{ of } P_2 \text{ or } \pm 0.05 \text{ s.}$ $T(P_n) \pm 10*(n+1)\% \text{ of } P_n \text{ or } \pm 0.05 \text{ s.}$ $T(A_n) \pm 10\% \text{ of } A_{max}, \text{ where } A_{max} \text{ is the largest amplitude or } \pm 0.5\% \text{ of the total control travel (stop to stop).}$ $T(A_d) \pm 5\% \text{ of } A_d = \text{residual band or } \pm 0.5\% \text{ of the maximum control travel} = \text{residual band.}$ $\pm 1 \text{ significant overshoots (minimum of 1 \text{ significant overshoots (minimum of 1 \text{ significant overshoot).}$ Steady state position	Takeoff, Cruise, and Landing.	Data must be for normal control displacements in both directions (approximately 25% to 50% of full throw or approximately 25% to 50% of maximum allowable pitch controller deflection for flight conditions limited by the maneuvering load envelope).  Tolerances apply against the absolute values of each period (considered independently).			X	full oscillation.  Refer to paragraph 4 of Appendix A, Attachment 2 for additional information.  For overdamped and critically damped systems, see Figure A2B of Appendix A for an illustration of the reference

	Table B2A - Flight Training Device (FTD) Objective Tests										
		C	PS REQUIREME	NTS				INFORMATION			
	Test	Tolerance	Flight	Test		FTE Leve		Notes			
Entry Number	Title		Conditions	Details	5	6	7	riotes			
		within residual band.  Note 1.— Tolerances should not be applied on period or amplitude after the last significant overshoot.  Note 2.— Oscillations within the residual band are not considered significant and are not subject to tolerances.  For overdamped and critically damped systems only, the following tolerance applies: T(P <sub>0</sub> ) ±10% of P <sub>0</sub> or ±0.05 s.									
2.b.2.	Roll Control.	Same as 2.b.1.	Takeoff, Cruise, and Landing.	Data must be for normal control displacement (approximately 25% to 50% of full throw or approximately 25% to 50% of maximum allowable roll controller deflection for flight conditions limited by the maneuvering load envelope).			X	Refer to paragraph 4 of Appendix A, Attachment 2 for additional information.  For overdamped and critically damped systems, see Figure A2B of Appendix A for an illustration of the reference measurement.			
2.b.3.	Yaw Control.	Same as 2.b.1.	Takeoff, Cruise, and Landing.	Data must be for normal control displacement (approximately 25% to 50% of full throw).			X	Refer to paragraph 4 of Appendix A, Attachment 2 for additional information.			

	Table B2A - Flight Training Device (FTD) Objective Tests										
		Q	PS REQUIREME	ENTS				INFORMATION			
	Test	Tolerance	Flight	Test	FTD Level			Notes			
Entry Number	Title	Tolerance	Conditions	Details	5	6	7				
								For overdamped and critically damped systems, see Figure A2B of Appendix A for an illustration of the reference measurement.			
2.b.4.	Small Control Inputs – Pitch.	±0.15°/s body pitch rate or ±20% of peak body pitch rate applied throughout the time history.	Approach or Landing.	Control inputs must be typical of minor corrections made while established on an ILS approach (approximately 0.5 to 2°/s pitch rate).  Test in both directions.  Show time history data from 5 s before until at least 5 s after initiation of control input.  If a single test is used to demonstrate both directions, there must be a minimum of 5 s before control reversal to the opposite direction.  CCA: Test in normal and non-normal control state.			X				
2.b.5.	Small Control Inputs - Roll.	±0.15°/s body roll rate or ±20% of peak body roll rate applied throughout the time history.	Approach or landing.	Control inputs must be typical of minor corrections made while established on an ILS approach (approximately 0.5 to 2°/s roll rate).  Test in one direction. For airplanes that exhibit non-symmetrical behavior, test in both directions.  Show time history data from 5 s before until at least 5 s after initiation of control input.  If a single test is used to demonstrate both directions, there must be a minimum of 5 s before control reversal to the opposite direction.  CCA: Test in normal and non-normal control			X				

	Table B2A - Flight Training Device (FTD) Objective Tests										
		(	PS REQUIREME	ENTS				INFORMATION			
	Test	Tolerance	Flight	Test		FTD Leve		Notes			
Entry Number	Title	Toterunce	Conditions	Details	5	6	7	Tioles			
2.b.6.	Small Control Inputs – Yaw.	±0.15°/s body yaw rate or ±20% of peak body yaw rate applied throughout the time history.	Approach or landing.	Control inputs must be typical of minor corrections made while established on an ILS approach (approximately 0.5 to 2°/s yaw rate).  Test in both directions.  Show time history data from 5 s before until at least 5 s after initiation of control input.  If a single test is used to demonstrate both directions, there must be a minimum of 5 s before control reversal to the opposite direction.  CCA: Test in normal and non-normal control			X				
2.c.	Longitudinal Control	Tests.		state.							
	Ü	quired for level flight unless	otherwise specified.								
2.c.1.a.	Power Change Dynamics.	±3 kt airspeed. ±30 m (100 ft) altitude. ±1.5° or ±20% of pitch angle.	Approach.	Power change from thrust for approach or level flight to maximum continuous or go-around power.  Time history of uncontrolled free response for a time increment equal to at least 5 s before initiation of the power change to the completion of the power change + 15 s.  CCA: Test in normal and non-normal control			X				
2.c.1.b.	Power Change Force.	±5 lb (2.2 daN) or, ±20% pitch control force.	Approach.	mode  May be a series of snapshot test results. Power change dynamics test as described in test 2.c.1.a. will be accepted.  CCA: Test in Normal and Non-normal control mode.	X	X					

	Table B2A - Flight Training Device (FTD) Objective Tests										
		(	QPS REQUIREME	NTS				INFORMATION			
	Test	<b>Tolerance</b>	Flight	Test		FTD Level		Notes			
Entry Number	Title	20202.000	Conditions	Details	5	6	7	210000			
2.c.2.a.	Flap/Slat Change Dynamics.	$\pm 3$ kt airspeed. $\pm 30$ m (100 ft) altitude. $\pm 1.5^{\circ}$ or $\pm 20\%$ of pitch angle.	Takeoff through initial flap retraction, and approach to landing.	Time history of uncontrolled free response for a time increment equal to at least 5 s before initiation of the reconfiguration change to the completion of the reconfiguration change + 15 s.  CCA: Test in normal and non-normal control mode			X				
2.c.2.b.	Flap/Slat Change Force.	±5 lb (2.2 daN) or, ±20% pitch control force.	Takeoff through initial flap retraction, and approach to landing.	May be a series of snapshot test results. Flap/Slat change dynamics test as described in test 2.c.2.a. will be accepted.  CCA: Test in Normal and Non-normal control mode.	X	X					
2.c.3.	Spoiler/Speedbrake Change Dynamics.	±3 kt airspeed. ±30 m (100 ft) altitude. ±1.5° or ±20% of pitch angle.	Cruise.	Time history of uncontrolled free response for a time increment equal to at least 5 s before initiation of the configuration change to the completion of the configuration change +15 s.  Results required for both extension and retraction.  CCA: Test in normal and non-normal control mode			X				
2.c.4.a.	Gear Change Dynamics.	±3 kt airspeed. ±30 m (100 ft) altitude. ±1.5° or ±20% of pitch angle.	Takeoff (retraction), and Approach (extension).	Time history of uncontrolled free response for a time increment equal to at least 5 s before initiation of the configuration change to the completion of the configuration change + 15 s.  CCA: Test in normal and non-normal control mode			X				
2.c.4.b.	Gear Change Force.	±5 lb (2.2 daN) or, ±20% pitch control force.	Takeoff (retraction) and Approach (extension).	May be a series of snapshot test results. Gear change dynamics test as described in test 2.c.4.a. will be accepted.  CCA: Test in Normal and Non-normal control mode.	X	X					

	Table B2A - Flight Training Device (FTD) Objective Tests										
		(	PS REQUIREME	ENTS	1			INFORMATION			
	Test	Tolerance	Flight	Test	FTD Leve			Notes			
Entry Number			Conditions	Details	5	6	7	Tiotes			
2.c.5.	Longitudinal Trim.	±1° elevator angle.  ±0.5° stabilizer or trim surface angle.  ±1° pitch angle.  ±5% of net thrust or equivalent.	Cruise, Approach, and Landing.	Steady-state wings level trim with thrust for level flight. This test may be a series of snapshot tests.  Level 5 FTD may use equivalent stick and trim controllers in lieu of elevator and trim surface.  CCA: Test in normal or non-normal control mode, as applicable.	X	X	X				
2.c.6.	Longitudinal Maneuvering Stability (Stick Force/g).	±2.2 daN (5 lbf) or ±10% of pitch controller force.  Alternative method: ±1° or ±10% of the change of elevator angle.	Cruise, Approach, and Landing.	Continuous time history data or a series of snapshot tests may be used.  Test up to approximately 30° of roll angle for approach and landing configurations. Test up to approximately 45° of roll angle for the cruise configuration.  Force tolerance not applicable if forces are generated solely by the use of airplane hardware in the FTD.  Alternative method applies to airplanes which do not exhibit stick-force-per-g characteristics.  CCA: Test in normal or non-normal control mode		X	X				
2.c.7.	Longitudinal Static Stability.	±2.2 daN (5 lbf) or ±10% of pitch controller force.  Alternative method: ±1° or ±10% of the change of elevator angle.	Approach.	Data for at least two speeds above and two speeds below trim speed. The speed range must be sufficient to demonstrate stick force versus speed characteristics.  This test may be a series of snapshot tests.  Force tolerance is not applicable if forces are generated solely by the use of airplane hardware	X	X	X				

	Table B2A - Flight Training Device (FTD) Objective Tests									
		C	PS REQUIREME	NTS				INFORMATION		
	Test	Tolerance	Flight	Test		FTI Leve		Notes		
Entry Number	Title	Total	Conditions	Details	5	6	7	Tiotes		
	Approach to Stall Characteristics	±3 kt airspeed for initial buffet, stall warning, and stall speeds.  Control inputs must be plotted and demonstrate correct trend and magnitude.  ±2.0° pitch angle ±2.0° angle of attack ±2.0° bank angle ±2.0° sideslip angle  Additionally, for those simulators with reversible flight control systems: ±10% or ±5 lb (2.2 daN)) Stick/Column force (prior to "g break" only).	Second Segment Climb, High Altitude Cruise (Near Performance Limited Condition), and Approach or Landing	in the FTD.  Alternative method applies to airplanes which do not exhibit speed stability characteristics.  Level 5 must exhibit positive static stability, but need not comply with the numerical tolerance.  CCA: Test in normal or non-normal control mode, as applicable.  Each of the following stall entry methods must be demonstrated in at least one of the three required flight conditions:  Stall entry at wings level (1g)  Stall entry in turning flight of at least 25° bank angle (accelerated stall)  Stall entry in a power-on condition (required only for turboprop aircraft)  The required cruise condition must be conducted in a flaps-up (clean) configuration. The second segment climb and approach/landing conditions must be conducted at different flap settings.  For airplanes that exhibit stall buffet as the first indication of a stall, for qualification of this task, the FTD must be equipped with a vibration system that meets the applicable subjective and objective requirements in Appendix A of this Part.	V	V	X	Tests may be conducted at centers of gravity typically required for airplane certification stall testing.		
	Stall Warning (actuation of stall warning device.)	±3 kts. airspeed, ±2° bank for speeds greater than actuation of stall warning device or initial buffet.	Second Segment Climb, and Approach or Landing.	The stall maneuver must be entered with thrust at or near idle power and wings level (1g). Record the stall warning signal and initial buffet if applicable.	X	X				

				ning Device (FTD) Objective Tests				
		Ç	PS REQUIREME	NTS				INFORMATION
	Test	- Tolerance	Flight	Test		FTI Leve		Notes
Entry Number	Title	Toterunce	Conditions	Details	5	6	7	Tiones
				CCA: Test in Normal and Non-normal control states.				
2.c.9.a.	Phugoid Dynamics.	±10% of period.  ±10% of time to one half or double amplitude or ±0.02 of damping ratio.	Cruise.	Test must include three full cycles or that necessary to determine time to one half or double amplitude, whichever is less.  CCA: Test in non-normal control mode.		X	X	
2.c.9.b.	Phugoid Dynamics.	±10% period, Representative damping.	Cruise.	The test must include whichever is less of the following: Three full cycles (six overshoots after the input is completed), or the number of cycles sufficient to determine representative damping.  CCA: Test in non-normal control mode.	X			
2.c.10	Short Period Dynamics.	±1.5° pitch angle or ±2°/s pitch rate. ±0.1 g normal acceleration	Cruise.	CCA: (Level 7 FTD) Test in normal and non- normal control mode.  (Level 6 FTD) Test in non-normal control mode.		X	X	
2.c.11.	(Reserved)							
2.d.	Lateral Directional T	ests.						
	Power setting is that re	quired for level flight unless	otherwise specified.					
2.d.1.	Minimum control speed, air (V <sub>mcn</sub> ) or landing (V <sub>mcl</sub> ), per applicable airworthiness requirement or low speed engine-inoperative handling characteristics in the air.	±3 kt airspeed.	Takeoff or Landing (whichever is most critical in the airplane).	Takeoff thrust must be set on the operating engine(s).  Time history or snapshot data may be used.  CCA: Test in normal or non-normal control state, as applicable.			X	Minimum speed may be defined by a performance or control limit which prevents demonstration of $V_{\rm mca}$ or $V_{\rm mcl}$ in the conventional manner.
2.d.2.	Roll Response (Rate).	$\pm 2^{\circ}$ /s or $\pm 10\%$ of roll rate.	Cruise, and Approach or Landing.	Test with normal roll control displacement (approximately one-third of maximum roll controller travel).	X	X	X	

	Table B2A - Flight Training Device (FTD) Objective Tests										
		Ç	PS REQUIREME	NTS				INFORMATION			
Test		_ Tolerance	Flight	Test		FTI Leve		Notes			
Entry Number	Title	Toterance	Conditions	Details	5	6	7	110005			
		For airplanes with reversible flight control systems (Level 7 FTD only):  ±1.3 daN (3 lbf) or		This test may be combined with step input of flight deck roll controller test 2.d.3.							
		$\pm 1.3$ dain (3 lb1) or $\pm 10\%$ of wheel force.									
2.d.3.	Step input of flight deck roll controller.	$\pm 2^{\circ}$ or $\pm 10\%$ of roll angle.	Approach or Landing.	This test may be combined with roll response (rate) test 2.d.2.  CCA: (Level 7 FTD) Test in normal and non-normal control mode.  (Level 6 FTD) Test in non-normal control mode.		X	X	With wings level, apply a step roll control input using approximately one-third of the roll controller travel. When reaching approximately 20° to 30° of bank, abruptly return the roll controller to neutral and			
								allow approximately 10 seconds of airplane free response.			
2.d.4.a.	Spiral Stability.	Correct trend and $\pm 2^{\circ}$ or $\pm 10\%$ of roll angle in 20 s.  If alternate test is used: correct trend and $\pm 2^{\circ}$ aileron angle.	Cruise, and Approach or Landing.	Airplane data averaged from multiple tests may be used.  Test for both directions.  As an alternative test, show lateral control required to maintain a steady turn with a roll angle of approximately 30°.			X				
				CCA: Test in non-normal control mode.							
2.d.4.b.	Spiral Stability.	Correct trend and $\pm 3^{\circ}$ or $\pm 10\%$ of roll angle in 20 s.	Cruise	Airplane data averaged from multiple tests may be used.  Test for both directions.		X					
				As an alternative test, show lateral control required to maintain a steady turn with a roll angle of approximately 30°.							
			~ .	CCA: Test in non-normal control mode.							
2.d.4.c.	Spiral Stability.	Correct trend	Cruise	Airplane data averaged from multiple tests may	X						

	Table B2A - Flight Training Device (FTD) Objective Tests										
		(	PS REQUIREME	NTS				INFORMATION			
	Test	Tolerance	Flight	Test	FTI Leve			Notes			
Entry Number	Title	Tolerance	Conditions	Details	5	6	7	riotes			
				be used.							
				CCA: Test in non-normal control mode.							
2.d.5.	Engine Inoperative Trim.	$\pm 1^{\circ}$ rudder angle or $\pm 1^{\circ}$ tab angle or equivalent rudder pedal. $\pm 2^{\circ}$ side-slip angle.	Second Segment Climb, and Approach or Landing.	This test may consist of snapshot tests.			X	Test should be performed in a manner similar to that for which a pilot is trained to trim an engine failure condition.  2nd segment climb test should be at takeoff thrust. Approach or landing test should be at thrust for level flight.			
2.d.6.a.	Rudder Response.	±2°/s or ±10% of yaw rate.	Approach or Landing.	For Level 7 FTD: Test with stability augmentation on and off.  Test with a step input at approximately 25% of full rudder pedal throw.  Not required if rudder input and response is shown in Dutch Roll test (test 2.d.7).  CCA: Test in normal and non-normal control mode		X	X				
2.d.6.b.	Rudder Response.	Roll rate $\pm 2^{\circ}$ /sec, bank angle $\pm 3^{\circ}$ .	Approach or Landing.	May be roll response to a given rudder deflection.  CCA: Test in Normal and Non-normal control states.	X			May be accomplished as a yaw response test, in which case the procedures and requirements of test 2.d.6.a. will apply.			
2.d.7.	Dutch Roll	±0.5 s or ±10% of period.  ±10% of time to one half or double amplitude or ±.02 of damping	Cruise, and Approach or Landing.	Test for at least six cycles with stability augmentation off.  CCA: Test in non-normal control mode.		X	X				

	Table B2A - Flight Training Device (FTD) Objective Tests										
		(	PS REQUIREME	NTS				INFORMATION			
	Test	Tolerance	Flight	Test		FTI Leve		Notes			
Entry Number	Title	Toterunce	Conditions	Details	5	6	7	Hotes			
2.d.8.	Steady State Sideslip.	ratio.  (Level 7 FTD only): ±1 s or ±20% of time difference between peaks of roll angle and side-slip angle.  For a given rudder	Approach or Landing.	This test may be a series of snapshot tests using	X	X	X				
2.41.0.	Steady State Sideship.	For a given rudder position:  ±2° roll angle;  ±1° side-slip angle;  ±2° or ±10% of aileron angle; and  ±5° or ±10% of spoiler or equivalent roll controller position or force.  For airplanes with reversible flight control systems (Level 7 FTD only):  ±1.3 daN (3 lbf) or ±10% of wheel force.  ±2.2 daN (5 lbf) or ±10% of rudder pedal force.	Approach of Landing.	at least two rudder positions (in each direction for propeller-driven airplanes), one of which must be near maximum allowable rudder.  (Level 5 and Level 6 FTD only): Sideslip angle is matched only for repeatability and only on continuing qualification evaluations.	A	A	X				

	Table B2A - Flight Training Device (FTD) Objective Tests										
		(	PS REQUIREMI	ENTS				INFORMATION			
	Test	- Tolerance	Flight	Test	FTD Level			Notes			
Entry Number		Toterunee	Conditions	Details	5	6	7	Notes			
2.e.	Landings.										
2.e.1.	Normal Landing.	±3 kt airspeed.  ±1.5° pitch angle.  ±1.5° AOA.  ±3 m (10 ft) or ±10% of height.  For airplanes with reversible flight control systems:  ±2.2 daN (5 lbf) or	Landing.	Test from a minimum of 61 m (200 ft) AGL to nosewheel touchdown.  CCA: Test in normal and non-normal control mode, if applicable.			X	Two tests should be shown, including two normal landing flaps (if applicable) one of which should be near maximum certificated landing mass, the other at light or medium mass.			
2.e.2.	Minimum Flap Landing.	±10% of column force.  ±3 kt airspeed.  ±1.5° pitch angle.  ±1.5° AOA.  ±3 m (10 ft) or ±10% of height.  For airplanes with reversible flight control systems:  ±2.2 daN (5 lbf) or ±10% of column force.	Minimum Certified Landing Flap Configuration.	Test from a minimum of 61 m (200 ft) AGL to nosewheel touchdown.  Test at near maximum certificated landing weight.			X				
2.e.3.	Crosswind Landing.	±3 kt airspeed. ±1.5° pitch angle.	Landing.	Test from a minimum of 61 m (200 ft) AGL to a 50% decrease in main landing gear touchdown speed.			X	In those situations where a maximum crosswind or a maximum demonstrated crosswind is not known, contact			

	Table B2A - Flight Training Device (FTD) Objective Tests									
	(	PS REQUIREME	ENTS				INFORMATION			
Test	Tolerance	Flight	Test		FTI Leve		Notes			
Entry Number Title	Toterance	Conditions	Details	5	6	7				
	±1.5° AOA.  ±3 m (10 ft) or ±10% of height.  ±2° roll angle.  ±2° side-slip angle.  ±3° heading angle.  For airplanes with reversible flight control systems:  ±2.2 daN (5 lbf) or ±10% of column force.  ±1.3 daN (3 lbf) or ±10% of wheel force.  ±2.2 daN (5 lbf) or		It requires test data, including wind profile, for a crosswind component of at least 60% of airplane performance data value measured at 10 m (33 ft) above the runway.  Wind components must be provided as headwind and crosswind values with respect to the runway.				the NSPM.			
2.e.4. One Engine Inoperative Landing.	±10% of rudder pedal force.  ±3 kt airspeed.  ±1.5° pitch angle.  ±1.5° AOA.  ±3 m (10 ft) or ±10% of	Landing.	Test from a minimum of 61 m (200 ft) AGL to a 50% decrease in main landing gear touchdown speed.			X				

		Table B2A - Flight Training Device (FTD) Objective Tests										
			QPS REQUIREME	ENTS				INFORMATION				
	Test	Tolerance	Flight	Test		FTI Leve		Notes				
Entry Number	Title	1010101100	Conditions	Details	5	6	7	110000				
		±2° roll angle. ±2° side-slip angle. ±3° heading angle.										
2.e.5.	Autopilot landing (if applicable).	±1.5 m (5 ft) flare height.  ±0.5 s or ± 10% of Tf.  ±0.7 m/s (140 ft/min) rate of descent at touchdown.  ±3 m (10 ft) lateral deviation during rollout.	Landing.	If autopilot provides roll-out guidance, record lateral deviation from touchdown to a 50% decrease in main landing gear touchdown speed.  Time of autopilot flare mode engage and main gear touchdown must be noted.			X	See Appendix F of this part for definition of $T_{\rm f}$ .				
2.e.6.	All-engine autopilot go-around.	±3 kt airspeed.  ±1.5° pitch angle.  ±1.5° AOA.	As per airplane performance data.	Normal all-engine autopilot go-around must be demonstrated (if applicable) at medium weight.			X					
2.e.7.	One engine inoperative go around.	±3 kt airspeed.  ±1.5° pitch angle.  ±1.5° AOA.  ±2° roll angle.  ±2° side-slip angle.	As per airplane performance data.	Engine inoperative go-around required near maximum certificated landing weight with critical engine inoperative.  Provide one test with autopilot (if applicable) and one without autopilot.  CCA: Non-autopilot test to be conducted in non-normal mode.			X					
2.e.8.	Directional control (rudder effectiveness) with symmetric	±5 kt airspeed. ±2°/s yaw rate.	Landing.	Apply rudder pedal input in both directions using full reverse thrust until reaching full thrust reverser minimum operating speed.			X					

		Table	B2A - Flight Train	ning Device (FTD) Objective Tests				
		(	PS REQUIREME	NTS				INFORMATION
	Test	Tolerance	Flight	Test		FTI Leve		Notes
Entry Number	Title	Toterunee	Conditions	Details	5	6	7	110005
	reverse thrust.							
2.e.9.	Directional control (rudder effectiveness) with asymmetric reverse thrust.	±5 kt airspeed.  ±3° heading angle.	Landing.	With full reverse thrust on the operating engine(s), maintain heading with rudder pedal input until maximum rudder pedal input or thrust reverser minimum operation speed is reached.			X	
2.f.	Ground Effect.	•						
	Test to demonstrate Ground Effect.	±1° elevator angle.  ±0.5° stabilizer angle.  ±5% of net thrust or equivalent.  ±1° AOA.  ±1.5 m (5 ft) or ±10% of height.  ±3 kt airspeed.  ±1° pitch angle.	Landing.	A rationale must be provided with justification of results.  CCA: Test in normal or non-normal control mode, as applicable.			X	See paragraph on Ground Effect in this attachment for additional information.
2.g.	Reserved							
2.h.	-	Envelope Protection Funct						
	to control inputs during	e requirements of 2.h are only g entry into each envelope p ed. Set thrust as required to v	rotection function (i.e. with r	ontrolled airplanes. Time history results of response normal and degraded control states if their function n function.				
2.h.1.	Overspeed.	±5 kt airspeed.	Cruise.				X	
2.h.2.	Minimum Speed.	±3 kt airspeed.	Takeoff, Cruise, and Approach or Landing.				X	
2.h.3.	Load Factor.	±0.1g normal load factor	Takeoff, Cruise.				X	
2.h.4.	Pitch Angle.	±1.5° pitch angle	Cruise, Approach.				X	
2.h.5.	Bank Angle.	$\pm 2^{\circ}$ or $\pm 10\%$ bank angle	Approach.				X	
2.h.6.	Angle of Attack.	±1.5° angle of attack	Second Segment Climb,				X	

	Table B2A - Flight Training Device (FTD) Objective Tests								
		Ç	PS REQUIREM	ENTS				INFORMATION	
	Test	Tolerance	Flight	Test	FTD Level			_ Notes	
Entry Number	Title	_ 5352 3325	Conditions	<b>Details</b>	5	6	7	1,000	
			and Approach or Landing.						
3. Reserve	ed								
4. Visual S	System.								
4.a.	Visual scene quality								
4.a.1.	Continuous cross- cockpit visual field of view.	Visual display providing each pilot with a minimum of 176° horizontal and 36° vertical continuous field of view.	Not applicable.	Required as part of MQTG but not required as part of continuing evaluations.			X	measured using a visual test pattern filling the entire visual scene (all channels) consisting of a matrix of black and white 5° squares.  Installed alignment should be confirmed in an SOC (this would generally consist of	
4.a.2.	System Geometry	Geometry of image should have no distracting discontinuities.					X	results from acceptance testing).	
4.a.3	Surface resolution (object detection).	Not greater than 4 arc minutes.	Not applicable.				X	Resolution will be demonstrated by a test of objects shown to occupy the required visual angle in each visual display used on a scene from the pilot's eyepoint.  The object will subtend 4 arc minutes to the eye.  This may be demonstrated using threshold bars for a horizontal test.  A vertical test should also be demonstrated.  The subtended angles should be	

		Table	e B2A - Flight Trair	ning Device (FTD) Objective Tests				
			QPS REQUIREME	NTS				INFORMATION
Test		Tolerance	Flight	Test	FTD Level			Notes
Entry Number	Title	1 0101 41100	Conditions	Details	5	6	7	11000
								confirmed by calculations in an SOC.
4.a.4	Light point size.	Not greater than 8 arc minutes.	Not applicable.				X	Light point size should be measured using a test pattern consisting of a centrally located single row of white light points displayed as both a horizontal and vertical row.  It should be possible to move the light points relative to the eyepoint in all axes.  At a point where modulation is just discernible in each visual channel, a calculation should be made to determine the light spacing.  An SOC is required to state test
4.a.5	Raster surface contrast ratio.	Not less than 5:1.	Not applicable.				X	method and calculation.  Surface contrast ratio should be measured using a raster drawn test pattern filling the entire visual scene (all channels).  The test pattern should consist of black and white squares, 5° per square, with a white square in the center of each channel.  Measurement should be made on the center bright square for each channel using a 1° spot photometer. This value should have a minimum brightness of 7

	Table B2A - Flight Training Device (FTD) Objective Tests								
	Test	Tolerance	QPS REQUIREME	Test	FTD Level			INFORMATION Notes	
Entry Number	Title	Tolerance	Conditions	Details		6	7	Notes	
4.a.6	Light point contrast ratio.	Not less than 10:1.	Not applicable.				X	cd/m² (2 ft-lamberts). Measure any adjacent dark squares.  The contrast ratio is the bright square value divided by the dark square value.  Note 1. — During contrast ratio testing, FTD aft-cab and flight deck ambient light levels should be as low as possible.  Note 2. — Measurements should be taken at the center of squares to avoid light spill into the measurement device.  Light point contrast ratio should be measured using a test pattern demonstrating an area of greater than 1° area filled with white light points and should be compared to the adjacent background.  Note. — Light point modulation should be just discernible on calligraphic systems but will not be discernable on raster systems.  Measurements of the background should be taken such that the bright square is just out of the light meter FOV.	

	Table B2A - Flight Training Device (FTD) Objective Tests										
		(	QPS REQUIREMEN	NTS				INFORMATION			
	Test	Tolerance	Flight	Test		FTI Leve		Notes			
Entry Number	Title	1 orer unice	Conditions	Details	5	6	7	Tiotes			
								Note. — During contrast ratio testing, FTD aft-cab and flight deck ambient light levels should be as low as practical.			
4.a.7	Light point brightness.	Not less than 20 cd/m <sup>2</sup> (5.8 ft-lamberts).	Not applicable.				X	Light points should be displayed as a matrix creating a square.  On calligraphic systems the light			
								points should just merge.  On raster systems the light points should overlap such that the square is continuous (individual light points will not be visible).			
4.a.8	Surface brightness.	Not less than 14 cd/m <sup>2</sup> (4.1 ft-lamberts) on the display.	Not applicable.				X	Surface brightness should be measured on a white raster, measuring the brightness using the 1° spot photometer.  Light points are not acceptable.  Use of calligraphic capabilities to enhance raster brightness is acceptable.			
4.b	Head-Up Display (HUD)										
4.b.1	Static Alignment.	Static alignment with displayed image.  HUD bore sight must align with the center of the displayed image spherical pattern.					X	Alignment requirement only applies to the pilot flying.			

	Table B2A - Flight Training Device (FTD) Objective Tests										
		C	PS REQUIREME	NTS				INFORMATION			
	Test	Tolerance	Flight	Test		TI eve		Notes			
Entry Number	Title	Tolerunce	Conditions	Details	5	6	7	Notes			
		Tolerance +/- 6 arc min.									
4.b.2	System display.	All functionality in all flight modes must be demonstrated.					X	A statement of the system capabilities should be provided and the capabilities demonstrated			
4.b.3	HUD attitude versus FTD attitude indicator (pitch and roll of horizon).	Pitch and roll align with aircraft instruments.	Flight				X	Alignment requirement only applies to the pilot flying.			
4.c	Enhanced Flight Vision System (EFVS)										
4.c.1	Registration test.	Alignment between EFVS display and out of the window image must represent the alignment typical of the aircraft and system type.	Takeoff point and on approach at 200 ft.				X	Alignment requirement only applies to the pilot flying.  Note.— The effects of the alignment tolerance in 4.b.1 should be taken into account.			
4.c.2	EFVS RVR and visibility calibration.	The scene represents the EFVS view at 350 m (1,200 ft) and 1,609 m (1 sm) RVR including correct light intensity.	Flight				X	Infra-red scene representative of both 350 m (1,200 ft), and 1,609 m (1 sm) RVR.  Visual scene may be removed.			
4.c.3	Thermal crossover.	Demonstrate thermal crossover effects during day to night transition.	Day and night				X	The scene will correctly represent the thermal characteristics of the scene during a day to night transition.			
4.d	Visual ground segmen	nt									
4.d.1	Visual ground segment (VGS).	Near end: the correct number of approach lights within the computed VGS must be visible.	Trimmed in the landing configuration at 30 m (100 ft) wheel height above touchdown zone on glide slope at an RVR setting of 300 m (1,000 ft) or 350 m	This test is designed to assess items impacting the accuracy of the visual scene presented to a pilot at DH on an ILS approach. These items include:  1) RVR/Visibility;			X	Pre-position for this test is encouraged but may be achieved via manual or autopilot control to the desired position.			

		Table	e B2A - Flight Trai	ning Device (FTD) Objective Tests				
		(	QPS REQUIREME	ENTS				INFORMATION
	Test	- Tolerance	Flight	Test		FTI Leve		Notes
Entry Number	Title	1 orer unice	Conditions	Details	5	6	7	TVOCES
4.e	Visual System Capacity	Far end: ±20% of the computed VGS.  The threshold lights computed to be visible must be visible in the FTD.	(1,200 ft).	2) glide slope (G/S) and localizer modeling accuracy (location and slope) for an ILS;  3) for a given weight, configuration and speed representative of a point within the airplane's operational envelope for a normal approach and landing; and  4) Radio altimeter.  Note. — If non-homogeneous fog is used, the vertical variation in horizontal visibility should be described and included in the slant range visibility calculation used in the VGS computation.				
4.e.1	System capacity – Day mode.	Not less than: 10,000 visible textured surfaces, 6,000 light points, 16 moving models.	Not applicable				X	Demonstrated through use of a visual scene rendered with the same image generator modes used to produce scenes for training.  The required surfaces, light points, and moving models should be displayed simultaneously.
4.e.2	System capacity – Twilight/night mode.	Not less than: 10,000 visible textured surfaces, 15,000 light points, 16 moving models.	Not applicable				X	Demonstrated through use of a visual scene rendered with the same image generator modes used to produce scenes for training.  The required surfaces, light points, and moving models

	Table B2A - Flight Training Device (FTD) Objective Tests										
		(	PS REQUIREME	NTS				INFORMATION			
	Test	- Tolerance	Flight	Test	FTD Level			Notes			
Entry Number	Title	Toterance	Conditions	Details	5	6	7				
								should be displayed simultaneously.			
appropriate compared to sound syste the test or to evaluations unweighted	5. Sound System.  The sponsor will not be required to repeat the operational sound tests (i.e., tests 5.a.1. through 5.a.8. (or 5.b.1. through 5.b.9.) and 5.c., as appropriate) during continuing qualification evaluations if frequency response and background noise test results are within tolerance when compared to the initial qualification evaluation results, and the sponsor shows that no software changes have occurred that will affect the FTD's sound system. If the frequency response test method is chosen and fails, the sponsor may elect to fix the frequency response problem and repeat the test or the sponsor may elect to repeat the operational sound tests. If the operational sound tests are repeated during continuing qualification evaluations, the results may be compared against initial qualification evaluation results. All tests in this section must be presented using an unweighted 1/3-octave band format from band 17 to 42 (50 Hz to 16 kHz). A minimum 20 second average must be taken at a common location from where the initial evaluation sound results were gathered.  Turbo-jet airplanes.  Turbo-jet airplanes.										
5.a.1.	Ready for engine start.	Initial evaluation: Subjective assessment of 1/3 octave bands.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between	Ground.	Normal condition prior to engine start.  The APU must be on if appropriate.			X	Refer to paragraph 7 of Appendix A, Attachment 2.			

		Table	B2A - Flight Trai	ining Device (FTD) Objective Te	sts			
		(	PS REQUIREMI	ENTS				INFORMATION
	Test	- Tolerance	Flight	Test		FTI Leve		Notes
Entry Number	Title		Conditions	Details	5	6	7	
		initial and recurrent evaluation results cannot exceed 2 dB.						
5.a.2.	All engines at idle.	Initial evaluation: Subjective assessment of 1/3 octave bands.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Ground.	Normal condition prior to takeoff.			X	
5.a.3.	All engines at maximum allowable thrust with brakes set.	Initial evaluation: Subjective assessment of 1/3 octave bands.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Ground.	Normal condition prior to takeoff.			X	
5.a.4.	Climb	Initial evaluation: Subjective assessment of 1/3 octave bands.	En-route climb.	Medium altitude.			X	

	Table B2A - Flight Training Device (FTD) Objective Tests										
		(	PS REQUIREME	NTS				INFORMATION			
	Test	Tolerance	Flight	Test		FTI Leve		Notes			
Entry Number	Title		Conditions	Details	5 6 7	7	110165				
		Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.									
5.a.5.	Cruise	Initial evaluation: Subjective assessment of 1/3 octave bands.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Cruise.	Normal cruise configuration.			X				
5.a.6.	Speed brake/spoilers extended (as appropriate).	Initial evaluation: Subjective assessment of 1/3 octave bands.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute	Cruise.	Normal and constant speed brake deflection for descent at a constant airspeed and power setting.			X				

	Table B2A - Flight Training Device (FTD) Objective Tests							
	QPS REQUIREMENTS							
	Test	Title Tolerance Conditions Details				FTD Level		Notes
Entry Number	Title		Details	5	6	7		
		differences between initial and recurrent evaluation results cannot exceed 2 dB.						
5.a.7	Initial approach.	Initial evaluation: Subjective assessment of 1/3 octave bands.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Approach.	Constant airspeed, gear up, flaps/slats as appropriate.			X	
5.a.8	Final approach.	Initial evaluation: Subjective assessment of 1/3 octave bands.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Landing.	Constant airspeed, gear down, landing configuration flaps.			X	

	Table B2A - Flight Training Device (FTD) Objective Tests							
		(	PS REQUIREME	ENTS				INFORMATION
	Test	Tolerance	Flight	Test		FTD Level		Notes
Entry Number	Title	Toterance	Conditions	Details	5	6	7	1,000
5.b	Propeller-driven air	planes						All tests in this section should be presented using an unweighted 1/3-octave band format from at least band 17 to 42 (50 Hz to 16 kHz).  A measurement of minimum 20 s should be taken at the location corresponding to the approved data set.  Refer to paragraph 7 of Appendix A, Attachment 2.
5.b.1.	Ready for engine start.	Initial evaluation: Subjective assessment of 1/3 octave bands.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Ground.	Normal condition prior to engine start.  The APU must be on if appropriate.			X	
5.b.2	All propellers feathered, if applicable.	Initial evaluation: Subjective assessment of 1/3 octave bands.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when	Ground.	Normal condition prior to take-off.			X	

		Table	B2A - Flight Trai	ning Device (FTD) Objective Tes	sts			
			PS REQUIREME					INFORMATION
	Test	Tolerance	Flight	Test		FTD Level		Notes
Entry Number	Title		Conditions	Details	5	6	7	
		compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.						
5.b.3.	Ground idle or equivalent.	Initial evaluation: Subjective assessment of 1/3 octave bands.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Ground.	Normal condition prior to takeoff.			X	
5.b.4	Flight idle or equivalent.	Initial evaluation: Subjective assessment of 1/3 octave bands.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Ground.	Normal condition prior to takeoff.			X	

	Table B2A - Flight Training Device (FTD) Objective Tests							
		(	PS REQUIREME	ENTS				INFORMATION
	Test	- Tolerance	Flight	Test		FTD Level		Notes
Entry Number	Title	Toterunce	Conditions	Details	5	6	7	Trotes
5.b.5	All engines at maximum allowable power with brakes set.	Initial evaluation: Subjective assessment of 1/3 octave bands.	Ground.	Normal condition prior to takeoff.			X	
		Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.						
5.b.6	Climb.	Initial evaluation: Subjective assessment of 1/3 octave bands.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	En-route climb.	Medium altitude.			X	
5.b.7	Cruise	Initial evaluation: Subjective assessment of 1/3 octave bands.  Recurrent evaluation: cannot exceed ±5 dB difference on three	Cruise.	Normal cruise configuration.			X	

	Table B2A - Flight Training Device (FTD) Objective Tests							
		(	PS REQUIREME	NTS				INFORMATION
	Test	Tolerance	Flight Conditions	Test Details	FTD Level			Notes
Entry Number	Title		Conditions	Details	5	6	7	
		consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.						
5.b.8	Initial approach.	Initial evaluation: Subjective assessment of 1/3 octave bands.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Approach.	Constant airspeed, gear up, flaps extended as appropriate, RPM as per operating manual.			X	
5.b.9	Final approach.	Initial evaluation: Subjective assessment of 1/3 octave bands.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results	Landing.	Constant airspeed, gear down, landing configuration flaps, RPM as per operating manual.			X	

	Table B2A - Flight Training Device (FTD) Objective Tests							
		(	PS REQUIREME	NTS				INFORMATION
	Test	Tolerance	Flight	Test		FTD Level		Notes
Entry Number	Title		Conditions	Details	5	6	7	110165
		cannot exceed 2 dB.						
5.c.	Special cases.	Initial evaluation: Subjective assessment of 1/3 octave bands.  Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	As appropriate.				X	This applies to special steady- state cases identified as particularly significant to the pilot, important in training, or unique to a specific airplane type or model.
5.d	FTD background noise	Initial evaluation: background noise levels must fall below the sound levels described in Appendix A, Attachment 2, Paragraph 7.c (5).  Recurrent evaluation: ±3 dB per 1/3 octave band compared to initial evaluation.		Results of the background noise at initial qualification must be included in the QTG document and approved by the NSPM.  The measurements are to be made with the simulation running, the sound muted and a dead cockpit.			X	The simulated sound will be evaluated to ensure that the background noise does not interfere with training.  Refer to paragraph 7 of this Appendix A, Attachment 2.  This test should be presented using an unweighted 1/3 octave band format from band 17 to 42 (50 Hz to 16 kHz).
5.e	Frequency response	Initial evaluation: not applicable.  Recurrent evaluation: cannot exceed ±5 dB difference on three					X	Only required if the results are to be used during continuing qualification evaluations in lieu of airplane tests.  The results must be approved by

	Table B2A - Flight Training Device (FTD) Objective Tests							
		C	PS REQUIREME	NTS				INFORMATION
	Test	Tolerance	Flight	Test		FTD Level		Notes
Entry Number	Title	Toterance	Conditions	Details	5	6	7	Tions
		consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.						the NSPM during the initial qualification.  This test should be presented using an unweighted 1/3 octave band format from band 17 to 42 (50 Hz to 16 kHz).
6	SYSTEMS INTEGRATION	cannot exceed 2 dB.						
6.a.	System response time							
6.a.1	Transport delay.	Instrument response: 100 ms (or less) after airplane response.  Visual system response: 120 ms (or less) after airplane response.	Pitch, roll and yaw.				X	One separate test is required in each axis.  Where EFVS systems are installed, the EFVS response should be within + or - 30 ms from visual system response, and not before motion system response.  Note.— The delay from the airplane EFVS electronic elements should be added to the 30 ms tolerance before comparison with visual system reference.
6.a.2	Transport delay.	300 milliseconds or less after controller movement.	Pitch, roll and yaw.		X	X		If transport delay is the chosen method to demonstrate relative responses, the sponsor and the NSPM will use the latency values to ensure proper FTD response when reviewing those existing tests where latency can

	Table B2A - Flight Training Device (FTD) Objective Tests								
	QPS REQUIREMENTS								
Test Tolerance		Flight Test		FTD Level			Notes		
Entry Number	Title	Tolerance	Conditions	Details	5	6	7	Notes	
								be identified (e.g., short period, roll response, rudder response).	

	Table B2B - Alternative Data So	Table B2B - Alternative Data Source for FTD Level 5							
	Small, Single Engine (Recipr	ocating) Airplane							
	QPS REQUIREM								
	The performance parameters in this table must be used to program the FTD								
	if flight test data is not used to program the FTD.								
-	Applicable Test	Authorized							
Entry Number	Title and Procedure	Performance Range							
1.	Performance.								
1.c	Climb.								
1.c.1.	Normal climb with nominal gross weight, at best rate-of-climb  Climb rate = 500 - 1200 fpm (2.5 - 6 m/sec).								
	airspeed.								
1.f.	Engines.								
1.f.1.	Acceleration; idle to takeoff power.	2 - 4 Seconds.							
1.f.2.	Deceleration; takeoff power to idle.	2 - 4 Seconds.							
2.	Handling Qualities.								
2.c.	Longitudinal Tests.								
2.c.1.	Power change force.								
	(a) Trim for straight and level flight at 80% of normal cruise airspeed	5 - 15 lbs (2.2 - 6.6 daN) of force (Push).							
	with necessary power. Reduce power to flight idle. Do not change								
	trim or configuration. After stabilized, record column force necessary								
	to maintain original airspeed.								
	OR								

## Table B2B - Alternative Data Source for FTD Level 5 Small, Single Engine (Reciprocating) Airplane OPS REQUIREMENT The performance parameters in this table must be used to program the FTD if flight test data is not used to program the FTD. **Applicable Test** Authorized **Entry** Title and Procedure **Performance Range** Number (b) Trim for straight and level flight at 80 percent of normal cruise 5 - 15 lbs (2.2 - 6.6 daN) of force (Pull). airspeed with necessary power. Add power to maximum setting. Do not change trim or configuration. After stabilized, record column force necessary to maintain original airspeed. 2.c.2. Flap/slat change force. (a) Trim for straight and level flight with flaps fully retracted at a 5 - 15 lbs (2.2 - 6.6 daN) of force (Push). constant airspeed within the flaps-extended airspeed range. Do not adjust trim or power. Extend the flaps to 50 percent of full flap travel. After stabilized, record stick force necessary to maintain original airspeed. OR b) Trim for straight and level flight with flaps extended to 50% of full 5 - 15 lbs (2.2 - 6.6 daN) of force (Pull). flap travel, at a constant airspeed within the flaps-extended airspeed range. Do not adjust trim or power. Retract the flaps to zero. After stabilized, record stick force necessary to maintain original airspeed. 2.c.4. Gear change force. (a) Trim for straight and level flight with landing gear retracted at a 2 - 12 lbs (0.88 - 5.3 daN) of force (Push). constant airspeed within the landing gear-extended airspeed range. Do not adjust trim or power. Extend the landing gear. After stabilized, record stick force necessary to maintain original airspeed. OR (b) Trim for straight and level flight with landing gear extended, at a 2 - 12 lbs (0.88 - 5.3 daN) of force (Pull). constant airspeed within the landing gear-extended airspeed range. Do not adjust trim or power. Retract the landing gear. After stabilized, record stick force necessary to maintain original airspeed. Longitudinal trim. Must be able to trim longitudinal stick force to "zero" in each of the 2.c.5. following configurations: cruise; approach; and landing. Must exhibit positive static stability.

2.c.7.

Longitudinal static stability.

## Table B2B - Alternative Data Source for FTD Level 5

Small, Single Engine (Reciprocating) Airplane

QPS REQUIREMENT

The performance parameters in this table must be used to program the FTD if flight test data is not used to program the FTD.

	Applicable Test	
Entry Number	Title and Procedure	Authorized Performance Range
2.c.8.	Stall warning (actuation of stall warning device) with nominal gross weight; wings level; and a deceleration rate of not more than three (3) knots per second.	
	a) Landing configuration.	$40 - 60$ knots; $\pm 5^{\circ}$ of bank.
	b) Clean configuration.	Landing configuration speed + 10 - 20%.
2.c.9.b.	Phugoid dynamics.	Must have a phugoid with a period of 30 - 60 seconds. May not reach ½ or double amplitude in less than 2 cycles.
2.d.	Lateral Directional Tests.	· · · · · · · · · · · · · · · · · · ·
2.d.2.	Roll response (rate).	Must have a roll rate of 4° - 25°/second.
	Roll rate must be measured through at least 30 degree of roll. Aileron	
	control must be deflected 1/3 (33.3 percent) of maximum travel.	
2.d.4.c.	Spiral stability.	Initial bank angle ( $\pm 5^{\circ}$ ) after 20 seconds.
	Cruise configuration and normal cruise airspeed. Establish a 20 degree - 30 degree bank. When stabilized, neutralize the aileron	
	control and release. Must be completed in both directions of turn.	
2.d.6.b.	Rudder response.	2° - 6° /second yaw rate.
	Use 25 percent of maximum rudder deflection.	, and the second
	(Applicable to approach or landing configuration.)	
2.d.8.	Steady state sideslip.	2 percent – 10 percent of bank; 4 percent - 10 percent of sideslip; and
	Use 50 percent rudder deflection.	2 percent -10 percent of aileron.
	(Applicable to approach and landing configurations.)	
6.	FTD System Response Time.	
6.a.	Flight deck instrument systems response to an abrupt pilot controller input. One test is required in each axis (pitch, roll, yaw).	300 milliseconds or less.

## Table B2C - Alternative Data Source for FTD Level 5 Small, Multi-Engine (Reciprocating) Airplane OPS REQUIREMENT

QPS REQUIREMENT

The performance parameters in this table must be used to program the FTD if flight test data is not used to program the FTD.

	Applicable Test	Anthoninal
Entry Number	Title and Procedure	Authorized Performance Range
1.	Performance.	
1.c	Climb.	
1.c.1.	Normal climb with nominal gross weight, at best rate-of-climb airspeed.	Climb airspeed = 95 – 115 knots. Climb rate = 500 – 1500 fpm (2.5 – 7.5 m/sec)
1.f.	Engines.	
1.f.1.	Acceleration; idle to takeoff power.	2 - 5 Seconds.
1.f.2.	Deceleration; takeoff power to idle.	2 - 5 Seconds.
2.	Handling Qualities.	
2.c.	Longitudinal Tests.	
2.c.1.	Power change force.  (a) Trim for straight and level flight at 80 percent of normal cruise airspeed with necessary power. Reduce power to flight idle. Do not change trim or configuration. After stabilized, record column force necessary to maintain original airspeed.	10 - 25 lbs (2.2 - 6.6 daN) of force (Push).
	OR  (b) Trim for straight and level flight at 80 percent of normal cruise airspeed with necessary power. Add power to maximum setting. Do not change trim or configuration. After stabilized, record column force necessary to maintain original airspeed.	5 - 15 lbs (2.2 - 6.6 daN) of force (Pull).
2.c.2.	Flap/slat change force.  (a) Trim for straight and level flight with flaps fully retracted at a constant airspeed within the flaps-extended airspeed range. Do not adjust trim or power. Extend the flaps to 50 percent of full flap travel. After stabilized, record stick force necessary to maintain original airspeed.	5 - 15 lbs (2.2 - 6.6 daN) of force (Push).

	Table B2C - Alternative Data	Source for FTD Level 5							
	Small, Multi-Engine (Rec	iprocating) Airplane							
	QPS REQUIR								
	The performance parameters in this table must be used to program the FTD								
	if flight test data is not used to program the FTD.								
T 4	Applicable Test	Authorized							
Entry Number	Title and Procedure	Performance Range							
	OR								
	(b) Trim for straight and level flight with flaps extended to 50 percent of full flap travel, at a constant airspeed within the flaps-extended airspeed range. Do not adjust trim or power. Retract the flaps to zero. After stabilized, record stick force necessary to maintain original airspeed.	5 - 15 lbs (2.2 - 6.6 daN) of force (Pull).							
2.c.4.	Gear change force.  (a) Trim for straight and level flight with landing gear retracted at a constant airspeed within the landing gear-extended airspeed range. Do not adjust trim or power. Extend the landing gear.  After stabilized, record stick force necessary to maintain original airspeed.	2 - 12 lbs (0.88 - 5.3 daN) of force (Push).							
	OR								
	(b) Trim for straight and level flight with landing gear extended, at a constant airspeed within the landing gear-extended airspeed range. Do not adjust trim or power. Retract the landing gear. After stabilized, record stick force necessary to maintain original airspeed.	2 - 12 lbs (0.88 - 5.3 daN) of force (Pull).							
2.c.5.	Longitudinal trim.	Must be able to trim longitudinal stick force to "zero" in each of the following configurations: cruise; approach; and landing.							
2.c.7.	Longitudinal static stability.	Must exhibit positive static stability.							
2.c.8.	Stall warning (actuation of stall warning device) with nominal gross weight; wings level; and a deceleration rate of not more than three (3) knots per second.								

## Table B2C - Alternative Data Source for FTD Level 5

## Small, Multi-Engine (Reciprocating) Airplane

Applicable Test		A 4lo outino d
Entry Number	Title and Procedure	Authorized Performance Range
	(a) Landing configuration.	$60 - 90 \text{ knots}$ ; $\pm 5 \text{ degree of bank}$ .
	(b) Clean configuration.	Landing configuration speed + 10 - 20%.
2.c.9.b.	Phugoid dynamics.	Must have a phugoid with a period of 30 - 60 seconds. May not reach ½ or double amplitude in less than 2 cycles.
2.d.	Lateral Directional Tests.	
2.d.2.	Roll response. Roll rate must be measured through at least 30 degree of roll. Aileron control must be deflected 1/3 (33.3 percent) of maximum travel.  Must have a roll rate of 4- 25 degree /second.	
2.d.4.c.	Spiral stability. Cruise configuration and normal cruise airspeed. Establish a 20 degree – 30 degree bank. When stabilized, neutralize the aileron control and release. Must be completed in both directions of turn.	Initial bank angle (± 5 degree) after 20 seconds.
2.d.6.b.	Rudder response. Use 25 percent of maximum rudder deflection. (Applicable to approach or landing configuration.)	3 - 6 degree /second yaw rate.
2.d.8.	Steady state sideslip. Use 50 percent rudder deflection. (Applicable to approach and landing configurations.)	2 - 10 degree of bank; 4 - 10 degrees of sideslip; and 2 - 10 degree of aileron.
6.	FTD System Response Time.	
6.a.	Flight deck instrument systems response to an abrupt pilot controller input. One test is required in each axis (pitch, roll, yaw).	300 milliseconds or less.

# Table B2D - Alternative Data Source for FTD Level 5 Small, Single Engine (Turbo-Propeller) Airplane

Applicable Test		Authorized
Entry Number	Title and Procedure	Performance Range
1.	Performance.	
1.c	Climb.	
1.c.1.	Normal climb with nominal gross weight, at best rate-of-climb	Climb airspeed = $95 - 115$ knots.
	airspeed.	Climb rate = $800 - 1800 \text{ fpm } (4 - 9 \text{ m/sec})$
1.f.	Engines.	
1.f.1.	Acceleration; idle to takeoff power.	4 - 8 Seconds.
1.f.2.	Deceleration; takeoff power to idle.	3 - 7 Seconds.
2.	Handling Qualities.	
2.c.	Longitudinal Tests.	
2.c.1.	Power change force.	
	a) Trim for straight and level flight at 80 percent of normal cruise	8 lbs (3.5 daN) of Push force – 8 lbs (3.5 daN) of Pull force.
	airspeed with necessary power. Reduce power to flight idle. Do	
	not change trim or configuration. After stabilized, record column	
	force necessary to maintain original airspeed.	
	OR	
	b) Trim for straight and level flight at 80 percent of normal cruise	12 - 22 lbs (5.3 – 9.7 daN) of force (Pull).
	airspeed with necessary power. Add power to maximum setting.	
	Do not change trim or configuration. After stabilized, record	
	column force necessary to maintain original airspeed.	
2.c.2.	Flap/slat change force.	
	a) Trim for straight and level flight with flaps fully retracted at a	5 - 15 lbs (2.2 - 6.6 daN) of force (Push).
	constant airspeed within the flaps-extended airspeed range. Do	
	not adjust trim or power. Extend the flaps to 50 percent of full	
	flap travel. After stabilized, record stick force necessary to	
	maintain original airspeed.	
	OR	

# Table B2D - Alternative Data Source for FTD Level 5 Small, Single Engine (Turbo-Propeller) Airplane

Applicable Test		Authorized	
Entry Number	Title and Procedure	Performance Range	
	b) Trim for straight and level flight with flaps extended to 50 percent of full flap travel, at a constant airspeed within the flaps-extended airspeed range. Do not adjust trim or power. Retract the flaps to zero. After stabilized, record stick force necessary to maintain original airspeed.	5 - 15 lbs (2.2 - 6.6 daN) of force (Pull).	
2.c.4.	Gear change force.  a) Trim for straight and level flight with landing gear retracted at a constant airspeed within the landing gear-extended airspeed range. Do not adjust trim or power. Extend the landing gear. After stabilized, record stick force necessary to maintain original airspeed.  OR	2 - 12 lbs (0.88 - 5.3 daN) of force (Push).	
	b) Trim for straight and level flight with landing gear extended, at a constant airspeed within the landing gear-extended airspeed range. Do not adjust trim or power. Retract the landing gear. After stabilized, record stick force necessary to maintain original airspeed.	2 - 12 lbs (0.88 - 5.3 daN) of force (Pull).	
2.c.5.	Longitudinal trim.	Must be able to trim longitudinal stick force to "zero" in each of the following configurations: cruise; approach; and landing.	
2.c.7.	Longitudinal static stability.	Must exhibit positive static stability.	
2.c.8.	Stall warning (actuation of stall warning device) with nominal gross weight; wings level; and a deceleration rate of not more than three (3) knots per second.		
	a) Landing configuration.	60 - 90 knots; ± 5 degree of bank.	
2 - 0 h	b) Clean configuration.	Landing configuration speed + 10 - 20 percent.	
2.c.9.b.	Phugoid dynamics.	Must have a phugoid with a period of 30 - 60 seconds. May not reach ½ or double amplitude in less than 2 cycles.	

# Table B2D - Alternative Data Source for FTD Level 5 Small, Single Engine (Turbo-Propeller) Airplane OPS REQUIREMENT

Applicable Test		A male out on all
Entry Number	Title and Procedure	Authorized Performance Range
2.d.	Lateral Directional Tests.	
2.d.2.	Roll response. Roll rate must be measured through at least 30° of roll. Aileron control must be deflected 1/3 (33.3 percent) of maximum travel.	Must have a roll rate of 4 - 25 degree /second.
2.d.4.c.	Spiral stability.  Cruise configuration and normal cruise airspeed. Establish a 20° - 30° bank. When stabilized, neutralize the aileron control and release. Must be completed in both directions of turn.	Initial bank angle (± 5 degree) after 20 seconds.
2.d.6.b.	Rudder response. Use 25 percent of maximum rudder deflection. (Applicable to approach or landing configuration.)	3 - 6 degree /second yaw rate.
2.d.8.	Steady state sideslip. Use 50 percent rudder deflection. (Applicable to approach and landing configurations.)	2 - 10 degree of bank; 4 - 10 degree of sideslip; and 2 - 10 degree of aileron.
6.	FTD System Response Time.	
6.a.	Flight deck instrument systems response to an abrupt pilot controller input. One test is required in each axis (pitch, roll, yaw).	300 milliseconds or less.

# **Table B2E - Alternative Data Source for FTD Level 5** Multi-Engine (Turbo-Propeller) Airplane

Applicable Test		
Entry Number	Title and Procedure	Authorized Performance Range
1.	Performance.	
1.c	Climb.	
1.c.1.	Normal climb with nominal gross weight, at best rate-of-climb	Climb airspeed = $120 - 140$ knots.
	airspeed.	Climb rate = $1000 - 3000 \text{ fpm } (5 - 15 \text{ m/sec})$
1.f.	Engines.	
1.f.1.	Acceleration; idle to takeoff power.	2 - 6 Seconds.
1.f.2.	Deceleration; takeoff power to idle.	1 - 5 Seconds.
2.	Handling Qualities.	
2.c.	Longitudinal Tests.	
2.c.1.	Power change force.	
	a) Trim for straight and level flight at 80 percent of normal cruise	8 lbs (3.5 daN) of Push force to 8 lbs (3.5 daN) of Pull force.
	airspeed with necessary power. Reduce power to flight idle. Do	
	not change trim or configuration. After stabilized, record column	
	force necessary to maintain original airspeed.	
	OR	
	b) Trim for straight and level flight at 80 percent of normal cruise	12 - 22 lbs (5.3 – 9.7 daN) of force (Pull).
	airspeed with necessary power. Add power to maximum setting.	
	Do not change trim or configuration. After stabilized, record	
	column force necessary to maintain original airspeed.	
2.c.2.	Flap/slat change force.	
	a) Trim for straight and level flight with flaps fully retracted at a	5 - 15 lbs (2.2 - 6.6 daN) of force (Push).
	constant airspeed within the flaps-extended airspeed range. Do	
	not adjust trim or power. Extend the flaps to 50 percent of full	
	flap travel. After stabilized, record stick force necessary to	
	maintain original airspeed.	
	OR	

## **Table B2E - Alternative Data Source for FTD Level 5** Multi-Engine (Turbo-Propeller) Airplane

Applicable Test		Authorized	
Entry Number	Title and Procedure	Performance Range	
	b) Trim for straight and level flight with flaps extended to 50 percent of full flap travel, at a constant airspeed within the flaps-extended airspeed range. Do not adjust trim or power. Retract the flaps to zero. After stabilized, record stick force necessary to maintain original airspeed.	5 - 15 lbs (2.2 - 6.6 daN) of force (Pull).	
2.c.4.	Gear change force.  a) Trim for straight and level flight with landing gear retracted at a constant airspeed within the landing gear-extended airspeed range. Do not adjust trim or power. Extend the landing gear. After stabilized, record stick force necessary to maintain original airspeed.	2 - 12 lbs (0.88 - 5.3 daN) of force (Push).	
	b) Trim for straight and level flight with landing gear extended, at a constant airspeed within the landing gear-extended airspeed range. Do not adjust trim or power. Retract the landing gear. After stabilized, record stick force necessary to maintain original airspeed.	2 - 12 lbs (0.88 - 5.3 daN) of force (Pull).	
2.c.5.	Longitudinal trim.	Must be able to trim longitudinal stick force to "zero" in each of the following configurations: cruise; approach; and landing.	
2.c.7.	Longitudinal static stability.	Must exhibit positive static stability.	
2.c.8.	Stall warning (actuation of stall warning device) with nominal gross weight; wings level; and a deceleration rate of not more than three (3) knots per second.		
	a) Landing configuration.	$80 - 100 \text{ knots}$ ; $\pm 5^{\circ}$ of bank.	
	b) Clean configuration.	Landing configuration speed + 10 - 20 percent.	
2.c.9.b.	Phugoid dynamics.	Must have a phugoid with a period of 30 - 60 seconds. May not reach ½ or double amplitude in less than 2 cycles.	
2.d.	Lateral Directional Tests.		

### **Table B2E - Alternative Data Source for FTD Level 5** Multi-Engine (Turbo-Propeller) Airplane

Applicable Test		A with out and
Entry Number	Title and Procedure	Authorized Performance Range
2.d.2.	Roll response. Roll rate must be measured through at least 30 degree of roll. Aileron control must be deflected 1/3 (33.3 percent) of maximum travel.	Must have a roll rate of 4 - 25 degree /second.
2.d.4.c.	Spiral stability. Cruise configuration and normal cruise airspeed. Establish a 20 - 30 dgree bank. When stabilized, neutralize the aileron control and release. Must be completed in both directions of turn.	Initial bank angle (± 5°) after 20 seconds.
2.d.6.b.	Rudder response. Use 25 percent of maximum rudder deflection. (Applicable to approach or landing configuration.)	3 - 6 degree /second yaw rate.
2.d.8.	Steady state sideslip. Use 50 percent rudder deflection. (Applicable to approach and landing configurations.)	2 - 10 degree of bank; 4 - 10 degree of sideslip; and 2 -10 degree of aileron.
6.	. FTD System Response Time.	
6.a.	Flight deck instrument systems response to an abrupt pilot controller input. One test is required in each axis (pitch, roll, yaw).	300 milliseconds or less.

6. Correct the tables appearing on pages 18377-18387 to read as follows:

Table B3D - Table of Functions and Subjective Tests		
Level 7 FTD ODE DE OLUDEMENTS		
T4	QPS REQUIREMENTS	
Entry Number	Operations Tasks	
	Tasks in this table are subject to evaluation if appropriate for the airplane simulated as indicated in the SOQ Configuration List or the level of FTD qualification involved. Items not installed or not functional on the FTD and, therefore, not appearing on the SOQ Configuration List, are not required to be listed as exceptions on the SOQ.	
1.	Preparation For Flight	
1.a.	<b>Pre-flight.</b> Accomplish a functions check of all switches, indicators, systems, and equipment at all crew members' and instructors' stations and determine that:	
1.a.1	The flight deck design and functions are identical to that of the airplane simulated.	
2.	Surface Operations (pre-flight).	
2.a.	Engine Start.	
2.a.1.	Normal start.	
2.a.2.	Alternate start procedures.	
2.a.3.	Abnormal starts and shutdowns (e.g., hot/hung start, tail pipe fire).	
2.b.	Taxi.	
2.b.1	Pushback/powerback	
2.b.2.	Thrust response.	
2.b.3.	Power lever friction.	
2.b.4.	Ground handling.	
2.b.5.	Reserved	
2.b.6.	Taxi aids (e.g. taxi camera, moving map)	
2.b.7.	Low visibility (taxi route, signage, lighting, markings, etc.)	
2.c.	Brake Operation	
2.c.1.	Brake operation (normal and alternate/emergency).	
2.c.2.	Brake fade (if applicable). <b>Take-off.</b>	
3.a.	Normal.	
3.a.1.	Airplane/engine parameter relationships, including run-up.	
3.a.2.	Nosewheel and rudder steering.	
3.a.3.	Crosswind (maximum demonstrated and gusting crosswind).	
3.a.4.	Special performance	
3.a.4.a	Reduced V <sub>1</sub>	
3.a.4.b	Maximum engine de-rate.	
3.a.4.c	Soft surface.	
3.a.4.d	Short field/short take-off and landing (STOL) operations.	
3.a.4.e	Obstacle (performance over visual obstacle).	
3.a.5.	Low visibility take-off.	
3.a.6.	Landing gear, wing flap leading edge device operation.	
3.a.7.	Contaminated runway operation.	
3.b.	Abnormal/emergency.	

Table B3D - Table of Functions and Subjective Tests		
Level 7 FTD ODE DECLIDEMENTS		
E4	QPS REQUIREMENTS	
Entry Number	Operations Tasks	
	Dejected Teles off	
3.b.1.	Rejected Take-off.	
3.b.2.	Rejected special performance (e.g., reduced V <sub>1</sub> , max de-rate, short field operations).	
3.b.3.	Rejected take-off with contaminated runway.	
3.b.4.	Takeoff with a propulsion system malfunction (allowing an analysis of causes,	
	symptoms, recognition, and the effects on aircraft performance and handling) at	
	the following points: .	
	(iii) Prior to V1 decision speed.	
	(iv) Between V1 and Vr (rotation speed).	
	(iii)Between Vr and 500 feet above ground level.	
3.b.5.	Flight control system failures, reconfiguration modes, manual reversion and	
	associated handling.	
4.	Climb.	
4.a.	Normal.	
4.b.	One or more engines inoperative.	
4.c.	Approach climb in icing (for airplanes with icing accountability).	
5.	Cruise.	
5.a.	Performance characteristics (speed vs. power, configuration, and attitude)	
5.a.1.	Straight and level flight. Change of airspeed.	
5.a.2. 5.a.3.	High altitude handling.	
5.a.4.	High Mach number handling (Mach tuck, Mach buffet) and recovery (trim	
J.a.7.	change).	
5.a.5.	Overspeed warning (in excess of $V_{mo}$ or $M_{mo}$ ).	
5.a.6.	High IAS handling.	
5.b.	Maneuvers.	
5.b.1.	High Angle of Attack	
5.b.1.a	High angle of attack, approach to stalls, stall warning, and stall buffet (take-off,	
	cruise, approach, and landing configuration) including reaction of the autoflight	
	system and stall protection system.	
5.b.1.b	Reserved	
5.b.2.	Slow flight	
5.b.3.	Reserved	
5.b.4.	Flight envelope protection (high angle of attack, bank limit, overspeed, etc.).	
5.b.5.	Turns with/without speedbrake/spoilers deployed.	
5.b.6.	Normal and standard rate turns.	
5.b.7.	Steep turns	
5.b.8.	Performance turn	
5.b.9.	In flight engine shutdown and restart (assisted and windmill).	
5.b.10.	Maneuvering with one or more engines inoperative, as appropriate.	
5.b.11.	Specific flight characteristics (e.g., direct lift control).	
5.b.12.	Flight control system failures, reconfiguration modes, manual reversion and	
5 h 12	associated handling.	
5.b.13	Gliding to a forced landing.	

Table B3D - Table of Functions and Subjective Tests		
Level 7 FTD		
E4	QPS REQUIREMENTS	
Entry Number	Operations Tasks	
5.b.14	Visual resolution and FSTD handling and performance for the following (where	
3.0.14	applicable by aircraft type and training program):	
5.b.14.a	Terrain accuracy for forced landing area selection.	
5.b.14.b	Terrain accuracy for VFR Navigation.	
5.b.14.c	Eights on pylons (visual resolution).	
5.b.14.d	Turns about a point.	
5.b.14.e	S-turns about a road or section line.	
6.	Descent.	
6.a.	Normal.	
6.b.	Maximum rate/emergency (clean and with speedbrake, etc.).	
6.c.	With autopilot.	
6.d.	Flight control system failures, reconfiguration modes, manual reversion and	
	associated handling.	
7.	Instrument Approaches And Landing.	
	Those instrument approach and landing tests relevant to the simulated airplane	
	type are selected from the following list. Some tests are made with limiting wind	
	velocities, under windshear conditions, and with relevant system failures,	
	including the failure of the Flight Director. If Standard Operating Procedures	
	allow use autopilot for non-precision approaches, evaluation of the autopilot will	
7 -	be included.	
7.a. 7.a.1	Precision approach CAT I published approaches.	
7.a.1.a	Manual approach with/without flight director including landing.	
7.a.1.a 7.a.1.b	Autopilot/autothrottle coupled approach and manual landing.	
7.a.1.c	Autopilot/autothrottle coupled approach, engine(s) inoperative.	
7.a.1.d	Manual approach, engine(s) inoperative.	
7.a.1.e	HUD/EFVS	
7.a.2	CAT II published approaches.	
7.a.2.a	Autopilot/autothrottle coupled approach to DH and landing (manual and	
	autoland).	
7.a.2.b	Autopilot/autothrottle coupled approach with one-engine-inoperative	
	approach to DH and go-around (manual and autopilot).	
7.a.2.c	HUD/EFVS	
7.a.3	CAT III published approaches.	
7.a.3.a	Autopilot/autothrottle coupled approach to landing and roll-out (if	
	applicable) guidance (manual and autoland).	
7.a.3.b	Autopilot/autothrottle coupled approach to DH and go-around (manual and	
	autopilot).	
7.a.3.c	Autopilot/autothrottle coupled approach to land and roll-out (if applicable)	
	guidance with one engine inoperative (manual and autoland).	
7.a.3.d	Autopilot/autothrottle coupled approach to DH and go-around with one	
<b>7</b> - 2	engine inoperative (manual and autopilot).	
7.a.3.e	HUD/EFVS	
7.a.4	Autopilot/autothrottle coupled approach (to a landing or to a go-around):	

Table B3D - Table of Functions and Subjective Tests Level 7 FTD		
QPS REQUIREMENTS		
Entry Number	Operations Tasks	
7.a.4.a	With generator failure.	
7.a.4.b.1	With maximum tail wind component certified or authorized.	
7.a.4.b.2	Reserved	
7.a.4.c.1	With maximum crosswind component demonstrated or authorized.	
7.a.4.c.2	Reserved	
7.a.5	PAR approach, all engine(s) operating and with one or more engine(s) inoperative.	
7.a.6	MLS, GBAS, all engine(s) operating and with one or more engine(s) inoperative.	
7.b.	Non-precision approach.	
7.b.1	Surveillance radar approach, all engine(s) operating and with one or more engine(s) inoperative.	
7.b.2	NDB approach, all engine(s) operating and with one or more engine(s) inoperative.	
7.b.3	VOR, VOR/DME, TACAN approach, all engines(s) operating and with one or more engine(s) inoperative.	
7.b.4	RNAV / RNP / GNSS (RNP at nominal and minimum authorized temperatures) approach, all engine(s) operating and with one or more engine(s) inoperative.	
7.b.5	ILS LLZ (LOC), LLZ back course (or LOC-BC) approach, all engine(s) operating and with one or more engine(s) inoperative.	
7.b.6	ILS offset localizer approach, all engine(s) operating and with one or more engine(s) inoperative.	
7.c	Approach procedures with vertical guidance (APV), e.g. SBAS, flight path vector.	
7.c.1	APV/baro-VNAV approach, all engine(s) operating and with one or more engine(s) inoperative.	
7.c.2	Area navigation (RNAV) approach procedures based on SBAS, all engine(s) operating and with one or more engine(s) inoperative.	
8.	Visual Approaches (Visual Segment) And Landings.	
	Flight simulators with visual systems, which permit completing a special approach procedure in accordance with applicable regulations, may be approved for that particular approach procedure.	
8.a.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance.	
8.b.	Approach and landing with one or more engines inoperative.	
8.c.	Operation of landing gear, flap/slats and speedbrakes (normal and abnormal).	
8.d.	Approach and landing with crosswind (max. demonstrated and gusting crosswind).	
8.e.	Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable).	
8.e.1.	Approach and landing with trim malfunctions.	
8.e.1.a	Longitudinal trim malfunction.	
8.e.1.b	Lateral-directional trim malfunction.	

Table B3D - Table of Functions and Subjective Tests		
Level 7 FTD		
	QPS REQUIREMENTS	
Entry	Operations Tasks	
Number		
8.f.	Approach and landing with standby (minimum) electrical/hydraulic power.	
8.g.	Approach and landing from circling conditions (circling approach).	
8.h.	Approach and landing from visual traffic pattern.	
8.i.	Approach and landing from non-precision approach.	
8.j.	Approach and landing from precision approach.  Missed Approach.	
9.a.	All engines, manual and autopilot.	
9.b.	Engine(s) inoperative, manual and autopilot.	
9.c.	Rejected landing	
9.d.	With flight control system failures, reconfiguration modes, manual reversion and	
<i>J.</i> u.	associated handling.	
9.e.	Reserved	
10.	Surface Operations (landing, after-landing and post-flight).	
10.a	Landing roll and taxi.	
10.a.1	HUD/EFVS.	
10.a.2.	Spoiler operation.	
10.a.3.	Reverse thrust operation.	
10.a.4.	Directional control and ground handling, both with and without reverse thrust.	
10.a.5.	Reduction of rudder effectiveness with increased reverse thrust (rear pod-	
	mounted engines).	
10.a.6.	Brake and anti-skid operation	
10.a.6.a	Brake and anti-skid operation with dry, patchy wet, wet on rubber residue, and	
	patchy icy conditions.	
10.a.6.b	Reserved	
10.a.6.c	Reserved	
10.a.6.d	Auto-braking system operation.	
10.b	Engine shutdown and parking.	
10.b.1	Engine and systems operation.	
10.b.2	Parking brake operation.	
11.	Any Flight Phase.	
11.a.	Airplane and engine systems operation (where fitted).	
11.a.1.	Air conditioning and pressurization (ECS).	
11.a.2.	De-icing/anti-icing.	
11.a.3. 11.a.4.	Auxiliary power unit (APU).  Communications.	
11.a.4. 11.a.5.	Electrical.	
11.a.5. 11.a.6.	Fire and smoke detection and suppression.	
11.a.0.	Flight controls (primary and secondary).	
11.a.7.	Fuel and oil	
11.a.9.	Hydraulic	
11.a.10.	Pneumatic	
11.a.10.	Landing gear.	
11.a.11.	Oxygen.	
11.a.13.	Engine.	
11.0.13.	Linguit.	

Table B3D - Table of Functions and Subjective Tests Level 7 FTD					
QPS REQUIREMENTS					
Entry Number	Operations Tasks				
11.a.14.	Airborne radar.				
11.a.15.	Autopilot and Flight Director.				
11.a.16.	Terrain awareness warning systems and collision avoidance systems (e.g. EGPWS, GPWS, TCAS).				
11.a.17.	Flight control computers including stability and control augmentation.				
11.a.18.	Flight display systems.				
11.a.19.	Flight management computers.				
11.a.20.	Head-up displays (including EFVS, if appropriate).				
11.a.21.	Navigation systems				
11.a.22.	Stall warning/avoidance				
11.a.23.	Wind shear avoidance/recovery guidance equipment				
11.a.24.	Flight envelope protections				
11.a.25.	Electronic flight bag				
11.a.26.	Automatic checklists (normal, abnormal and emergency procedures).				
11.a.27.	Runway alerting and advisory system.				
11.b.	Airborne procedures.				
11.b.1.	Holding.				
11.b.2.	Air hazard avoidance (traffic, weather, including visual correlation).				
11.b.3.	Windshear.				
11.b.3.a	Prior to take-off rotation.				
11.b.3.b	At lift-off				
11.b.3.c	During initial climb.				
11.b.3.d	On final approach, below 150 m (500 ft) AGL.				
11.b.4.	Reserved				

Table B3E - Functions And Subjective Tests						
Level 7 FTD						
QPS REQUIREMENTS						
Entry Number	Airport Modeling Requirements					
This table spe	cifies the minimum airport model content and functionality to qualify a simulator at the					
indicated leve	l. This table applies only to the airport models required for FTD qualification.					
	Begin QPS Requirements					
1.	Reserved					
2.a.	Functional test content requirements					
2.a.1	Airport scenes					
2.a.1.a	A minimum of three (3) real-world airport models to be consistent with published data used for airplane operations and capable of demonstrating all the visual system features below. Each model should be in a different visual scene to permit assessment of FSTD automatic visual scene changes. The model identifications must be acceptable to the sponsor's TPAA, selectable from the IOS, and listed on the SOQ.					
2.a.1.b	Reserved					
2.a.1.c	Reserved					
2.a.1.d	Airport model content.  For circling approaches, all tests apply to the runway used for the initial approach and to the runway of intended landing. If all runways in an airport model used to meet the requirements of this attachment are not designated as "in use," then the "in use" runways must be listed on the SOQ (e.g., KORD, Rwys 9R, 14L, 22R). Models of airports with more than one runway must have all significant runways not "in-use" visually depicted for airport and runway recognition purposes. The use of white or off white light strings that identify the runway threshold, edges, and ends for twilight and night scenes are acceptable for this requirement. Rectangular surface depictions are acceptable for daylight scenes. A visual system's capabilities must be balanced between providing airport models with an accurate representation of the airport and a realistic representation of the surrounding environment. Airport model detail must be developed using airport pictures, construction drawings and maps, or other similar data, or developed in accordance with published regulatory material; however, this does not require that such models contain details that are beyond the design capability of the currently qualified visual system. Only one "primary" taxi route from parking to the runway end will be required for each "in-use" runway.					
2.a.2	Visual scene fidelity.					
2.a.2.a	The visual scene must correctly represent the parts of the airport and its surroundings used in the training program.					
2.a.2.b	Reserved					
2.a.2.c	Reserved					
2.a.3	Runways and taxiways.					
2.a.3.a	Reserved					
2.a.3.b	Representative runways and taxiways.					
2.a.3.c	Reserved					
2.a.4	Reserved					
2.a.5	Runway threshold elevations and locations must be modeled to provide correlation with airplane systems (e.g. HUD, GPS, compass, altimeter).					

	Table B3E - Functions And Subjective Tests					
Level 7 FTD						
Entry Number	QPS REQUIREMENTS  Airport Modeling Requirements					
2.a.6	Reserved					
2.a.7	Runway surface and markings for each "in-use" runway must include the following,					
	if appropriate:					
2.a.7.a	Threshold markings.					
2.a.7.b	Runway numbers.					
2.a.7.c	Touchdown zone markings.					
2.a.7.d	Fixed distance markings.					
2.a.7.e	Edge markings.					
2.a.7.f	Center line markings.					
2.a.7.g	Reserved					
2.a.7.h	Reserved					
2.a.7.i	Windsock that gives appropriate wind cues.					
2.a.8	Runway lighting of appropriate colors, directionality, behavior and spacing for the					
	"in-use" runway including the following:					
2.a.8.a	Threshold lights.					
2.a.8.b	Edge lights.					
2.a.8.c	End lights.					
2.a.8.d	Center line lights.					
2.a.8.e	Touchdown zone lights.					
2.a.8.f	Lead-off lights.					
2.a.8.g	Appropriate visual landing aid(s) for that runway.					
2.a.8.h	Appropriate approach lighting system for that runway.					
2.a.9	Taxiway surface and markings (associated with each "in-use" runway):					
2.a.9.a	Edge markings					
2.a.9.b	Center line markings.					
2.a.9.c	Runway holding position markings.					
2.a.9.d	ILS critical area markings.					
2.a.9.e	Reserved					
2.a.10	Taxiway lighting of appropriate colors, directionality, behavior and spacing					
2.a.10.a	(associated with each "in-use" runway):  Edge lights.					
2.a.10.a 2.a.10.b	Center line lights.					
2.a.10.b 2.a.10.c	Runway holding position and ILS critical area lights.					
2.a.10.c	Required visual model correlation with other aspects of the airport environment					
2.0.11	simulation.					
2.a.11.a	The airport model must be properly aligned with the navigational aids that are associated					
	with operations at the runway "in-use".					
2.a.11.b	Reserved					
2.a.12	Airport buildings, structures and lighting.					
2.a.12.a	Buildings, structures and lighting:					
2.a.12.a.1	Reserved					

Representative airport buildings, structures and lighting.					
Representative moving and static airport clutter (e.g. other airplanes, power carts, tugs, fuel trucks, additional gates).  Reserved					
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Note.— This refers to natural and cultural features that are typically used for pilot orientation in flight. Outlying airports not intended for landing need only provide a reasonable facsimile of					
runway orientation.					
Representative moving airborne traffic (including the capability to present air hazards –					
e.g. airborne traffic on a possible collision course).					
Visual scene management.  Reserved					
Airport runway, approach and taxiway lighting and cultural lighting intensity for any approach should be set at an intensity representative of that used in training for the visibility set; all visual scene light points must fade into view appropriately.					
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Table B3E - Functions And Subjective Tests							
Level 7 FTD							
QPS REQUIREMENTS							
Entry	Airport Modeling Requirements						
2.d.1	Night.						
2.d.2	Twilight.						
2.d.3	Day.						
2.d.4	Dynamic effects — the capability to present multiple ground and air hazards such as another airplane crossing the active runway or converging airborne traffic; hazards must be selectable via controls at the instructor station.						
2.d.5	Reserved						
2.e	Correlation with airplane and associated equipment.						
2.e.1	Visual cues to relate to actual airplane responses.						
2.e.2	Visual cues during take-off, approach and landing.						
2.e.2.a	Visual cues to assess sink rate and depth perception during landings.						
2.e.2.b	Reserved						
2.e.3	Accurate portrayal of environment relating to airplane attitudes.						
2.e.4	The visual scene must correlate with integrated airplane systems, where fitted (e.g. terrain, traffic and weather avoidance systems and HUD/EFVS).						
2.e.5	Reserved						
2.f	Scene quality.						
2.f.1	Quantization.						
2.f.1.a	Surfaces and textural cues must be free from apparent quantization (aliasing).						
2.f.1.b	Reserved						
2.f.2	System capable of portraying full color realistic textural cues.						
2.f.3	The system light points must be free from distracting jitter, smearing or streaking.						
2.f.4	Reserved						
2.f.5	System capable of providing light point perspective growth (e.g. relative size of runway and taxiway edge lights increase as the lights are approached).						
2.g	Environmental effects.						
2.g.1	Reserved						
2.g.2	Reserved						
2.g.3	Reserved						
2.g.4	Reserved						
2.g.5	Reserved						
2.g.6	Reserved						
2.g.7	Visibility and RVR measured in terms of distance. Visibility/RVR must be checked at and below a height of 600 m (2 000 ft) above the airport and within a radius of 16 km (10 sm) from the airport.						
2.g.8	Reserved						
2.g.9	Reserved						
2.g.10	Reserved						
2.g.11	Reserved						
	End QPS Requirement						
-	Begin Information						

Table B3E - Functions And Subjective Tests Level 7 FTD			
QPS REQUIREMENTS			
Entry Number	Airport Modeling Requirements		
3.	An example of being able to "combine two airport models to achieve two "in-use" runways:  One runway designated as the "in use" runway in the first model of the airport, and the second runway designated as the "in use" runway in the second model of the same airport. For example, the clearance is for the ILS approach to Runway 27, Circle to Land on Runway 18 right. Two airport visual models might be used: the first with Runway 27 designated as the "in use" runway for the approach to runway 27, and the second with Runway 18 Right designated as the "in use" runway. When the pilot breaks off the ILS approach to runway 27, the instructor may change to the second airport visual model in which runway 18 Right is designated as the "in use" runway, and the pilot would make a visual approach and landing. This process is acceptable to the FAA as long as the temporary interruption due to the visual model change is not distracting to the pilot, does not cause changes in navigational radio frequencies, and does not cause undue instructor/evaluator time.		
4.	Sponsors are not required to provide every detail of a runway, but the detail that is provided should be correct within the capabilities of the system.  End Information		
	End Information		

Table B3F - Functions and Subjective Tests					
	Level 7 FTD				
QPS REQUIREMENTS					
Entry Number	Sound System Requirements				
The following checks are performed during a normal flight profile.					
1.	Precipitation.				
2.	Reserved				
3.	Significant airplane noises perceptible to the pilot during normal operations.				
4.	Abnormal operations for which there are associated sound cues including, engine malfunctions, landing gear/tire malfunctions, tail and engine pod strike and pressurization malfunction.				
5.	Sound of a crash when the flight simulator is landed in excess of limitations.				

